# AUTOMORPHISMS OF CUBIC SURFACES IN POSITIVE CHARACTERISTIC

### IGOR DOLGACHEV AND ALEXANDER DUNCAN

ABSTRACT. We classify all possible automorphism groups of smooth cubic surfaces over an algebraically closed field of arbitrary characteristic. As an intermediate step we also classify automorphism groups of quartic del Pezzo surfaces. We show that the moduli space of smooth cubic surfaces is rational in every characteristic, determine the dimensions of the strata admitting each possible isomorphism class of automorphism group, and find explicit normal forms in each case. Finally, we completely characterize when a smooth cubic surface in positive characteristic, together with a group action, can be lifted to characteristic zero.

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# 1. INTRODUCTION

Let X be a smooth cubic surface in  $\mathbb{P}^3$  defined over an algebraically closed field k of arbitrary characteristic p. The primary purpose of this paper is to classify the possible automorphism groups of X. This is progress towards the larger goal of classifying finite subgroups of the plane Cremona group in positive characteristic (see [8] for characteristic 0).

In characteristic 0, the first attempts at a classification of cubic surfaces were undertaken by S. Kantor [17], then A. Wiman [25] in late nineteenth century. In 1942, B. Segre [20] classified all automorphism groups in his book on cubic surfaces. Unfortunately, all of these classification had errors. The first correct classification was carried out using computers by T. Hosoh [16] in 1997. A modern classification, which does not require computers, can be found in [9].

Our approach emphasizes the similarities across characteristics, rather than the differences. There is a well-known injective group homomorphism  $\operatorname{Aut}(X) \to W(\mathsf{E}_6)$ , unique up to conjugacy, where  $\operatorname{Aut}(X)$  is the group of automorphisms of X and  $W(\mathsf{E}_6)$  is the Weyl group of the root system  $\mathsf{E}_6$ . This homomorphism can also be described as the induced action of  $\operatorname{Aut}(X)$ on the configuration of 27 lines. In this way, automorphism groups of cubic surfaces can be directly compared to each other even if they are defined over different fields.

Let  $\mathcal{M}_{\text{cub}}(\Bbbk)$  be the coarse moduli space of smooth cubic surfaces over  $\Bbbk$ . The space  $\mathcal{M}_{\text{cub}}(\Bbbk)$  is rational in all characteristics (Theorem 7.1). The conjugacy classes of elements in Weyl groups of root systems were classified by Carter [2], although we use the Atlas [5] labeling 1A, ..., 12C for the classes in  $W(\mathsf{E}_6)$ . To each conjugacy class of  $W(\mathsf{E}_6)$  we may associate the closed subvariety of  $\mathcal{M}_{\text{cub}}(\Bbbk)$  corresponding to surfaces admitting an automorphism of that class. For example, the 1A stratum corresponds to the set of all cubic surfaces since 1A is the class of the trivial automorphism. This gives a stratification of  $\mathcal{M}_{\text{cub}}(\Bbbk)$  by conjugacy classes of  $W(\mathsf{E}_6)$ . Some of these strata will be empty (for example, 12C) and some will coincide with others (for example, the 9A and 3C strata coincide).

We see the strata for cubic surfaces in characteristic 0 in Figure 1, where we choose only one label for each stratum. Here an arrow  $A \rightarrow B$  means that the stratum A strictly contains the stratum B and those arrows implied by transitivity are omitted for clarity. Each successive row corresponds to strata of dimension one less than the preceding row with the 1A stratum having dimension 4 and the strata for 3C, 5A, 8A, and 12A all being single points. See Figures 2, 3, and 4 in the Appendix for other characteristics.

We are interested in the full automorphism groups of smooth cubic surfaces. Each automorphism group gives rise to a conjugacy class of subgroups of  $W(\mathsf{E}_6)$ . Remarkably and conveniently, the strata in this case are the same as the strata for cyclic groups. Thus, we can name the stratum of a conjugacy class of automorphism groups by a cyclic subgroup that gives rise to



FIGURE 1. Specialization of strata in  $\mathcal{M}_{cub}$  when  $p \neq 2, 3, 5$ .

the same stratum. These labels may not be unique, but this is a feature when comparing different characteristics. For example, the 3C, 5A, 12A strata are all distinct in characteristic 0, but they coincide in characteristic 2.

We can now state our main theorem:

**Theorem 1.1.** Suppose X is a smooth cubic surface in  $\mathbb{P}^3$  defined over an algebraically closed field  $\Bbbk$  of arbitrary characteristic p. Then the group of automorphisms of X is one of the groups in Table 1 and all such groups occur. Each row of the table corresponds to the stratum of  $\mathcal{M}_{cub}(\Bbbk)$  which admits an automorphism of the named class. The heading "dim" gives the dimension of the stratum, char( $\Bbbk$ ) gives the conditions on the characteristic, and Aut(X) is the full automorphism group of a general cubic surface in that stratum along with its order. (See section 2.1 for explanations of the group theoretic notation.)

In addition to classifying the automorphism groups and the dimensions of their strata, we also find explicit equations for the cubic surfaces in each class (see the summary in Table 7). The specific choices of normal forms are certainly subjective, but they all have the nice property that the number of parameters is exactly the same as the dimension of the corresponding stratum of the moduli space.

There are several approaches that one could take to carry out the classification; for some other approaches see Remarks 4.8, 8.2, and 8.3. We have taken a conceptual geometric approach; as a consequence, we believe many of our intermediate results and their corollaries will be of independent interest. We discuss these in the remainder of the introduction, while also providing a tour of the cubic surfaces and their automorphisms. 4

Name	dim	$\operatorname{char}(\Bbbk)$	$\operatorname{Aut}(X)$	Order
1A	4	any	1	1
2A	3	any	2	2
2B	2	$\neq 2$	$2^{2}$	4
		2	$2^{4}$	16
3A	1	any	$\mathcal{H}_3(3) \rtimes 2$	54
3C	0	$\neq 2, 3$	$3^3 \rtimes \mathfrak{S}_4$	648
		2	$PSU_4(2)$	25920
3D	2	any	$\mathfrak{S}_3$	6
4A	1	$\neq 2$	4	4
		2	$2^3 \rtimes \mathfrak{S}_4$	192
4B	1	$\neq 2$	$\mathfrak{S}_4$	24
		2	(same as 4A)	
5A	0	$\neq 2, 5$	$\mathfrak{S}_5$	120
		2	(same as 3C)	
6E	1	$\neq 2$	$\mathfrak{S}_3  imes \mathfrak{S}_2$	12
		2	(same as 4A)	
8A	0	$\neq 2, 3$	8	8
		3	$\mathcal{H}_3(3) \rtimes 8$	216
12A	0	$\neq 2, 3$	$\mathcal{H}_3(3) \rtimes 4 = 108$	
		3	(same as 8A)	
		2	(same as 3C)	

TABLE 1. Automorphism groups of cubic surfaces.

1.1. Lifting to characteristic 0. Let X be a smooth projective irreducible variety over an algebraically closed field k of positive characteristic and G a finite group of automorphisms of X. We say that a group G is *tame* (resp. *wild*) if the characteristic p does not divide (resp. divides) the order of G. One expects that the behavior of tame groups to be similar across different characteristics. The order of  $|W(E_6)|$  is  $51840 = 2^7 \times 3^4 \times 5$ , so one only expects unusual automorphism groups of cubic surfaces in characteristics 2,3,5.

More precisely, we say a pair (X, G) can be *lifted to characteristic* 0 if there exists a complete discrete valuation ring R of characteristic 0 with residue field  $\Bbbk$ , and a smooth projective A-scheme  $\mathcal{X}$  with an action of G over A, such that the fiber over the closed point is G-equivariantly isomorphic to X.

When X is a smooth rational surface (for example, a smooth cubic) and G is tame, the pair can be lifted to characteristic 0 by a result of Serre (see  $\S 5$  of [22]).

An obvious obstruction to doing this for wild groups is that some automorphism groups in characteristic 2 and 3 do not act on any cubic surface in characteristic 0. This is the only obstruction:

**Theorem 1.2.** Let X be a smooth cubic surface defined over an algebraically closed field k of positive characteristic and let G be a group of automorphisms of X. Then (X, G) can be lifted to characteristic 0 if and only if  $G \subset W(\mathsf{E}_6)$  is realized as a group of automorphisms on some smooth cubic surface in characteristic 0.

1.2. Reflections and Eckardt points. Recall that a reflection is a linear transformation of order 2 which fixes a hyperplane pointwise. Note that this definition makes sense for projective linear transformations and when the characteristic is 2. Reflections are of class 2A in  $W(E_6)$ . If three exceptional lines on a cubic surface X all pass through the same point, it is classically called an *Eckardt point*. There is a well-known bijective correspondence between Eckardt points and reflections that leave X invariant.

Most of the automorphism groups of cubic surfaces are generated by reflections and can be completely described by the geometric arrangements of their Eckardt points. If two reflections commute, then their product has class 2B and their corresponding Eckardt points lie on a common exceptional line. Conversely, an involution of class 2B implies the existence of those two Eckardt points.

If two reflections do not commute, then their product has class 3D and the line  $\ell$  between the corresponding Eckardt points does not lie inside the cubic surface. The third point on the  $\ell$  is also an Eckardt point and the three points generate a group isomorphic to the symmetric group  $\mathfrak{S}_3$ , which recovers the original automorphism of class 3D. Similarly, geometric interpretations of the configurations of Eckardt points exist for 3A, 3C, 4B, 5A, and 6E classes as well (Section 13.1).

When the characteristic is not 2, then there are at most 2 Eckardt points on an exceptional line. However, when p = 2, there are exactly 5 Eckardt points on any exceptional line as soon there is more than 1 Eckardt point. We will see that this can be explained by the fact that the exceptional line blows down to the *canonical point* of a quartic del Pezzo surface Y described in [10], and thus the full automorphism group of Y must also act on X. This distinction between the number of Eckardt points is the fundamental reason why the automorphism groups are so much larger, and why so many strata coincide, when the characteristic is 2.

It is well known that reflections generate a subgroup of index 1, 2, or 4 in the automorphism group of a cubic surface when p = 0; we show this holds in all characteristics (Corollary 14.1). The reflections fail to generate only if there are automorphisms with classes 4A, 8A, and 12A, which always have a power of class 2A.

1.3. Forms of Sylvester and Emch. A classical theorem of Sylvester states that a general cubic surface in characteristic 0 can be defined by

$$\sum_{i=0}^{4} x_i^3 = \sum_{i=0}^{4} c_i x_i = 0$$

in  $\mathbb{P}^4$  where  $c_0, \ldots, c_4$  are parameters. When the parameters are all equal, one obtains the *Clebsch diagonal cubic surface*, which has an obvious  $\mathfrak{S}_5$ -action. The Clebsch cubic is the unique surface admitting an automorphism of class 5A, which we take as its definition when  $p \neq 0$ .

More generally, by selectively setting certain parameters equal to one another, we obtain families of cubic surfaces admitting automorphism groups isomorphic to subgroups of  $\mathfrak{S}_5$ . In this way we obtain general representatives of cubic surfaces realizing automorphisms of class 1A, 2A, 2B, 3D, 4B, 6E and 5A that correspond to the permutations (), (12), (12)(34), (123), (1234), (123)(12), and (12345) respectively.

When p = 5, the Clebsch cubic surface does not exist (Sylvester's normal form yields a singular surface); this is essentially the only difference between p = 5 and higher characteristics. When p = 3, the cubics in Sylvester's normal form are totally singular. When p = 2, we will see that all cubics from Sylvester's normal form are isomorphic to one another!

In Section 6, we rectify this bad behavior in characteristics 2 and 3 by instead discussing a lesser known normal form due to Emch [12]. We prove that, in all characteristics, a general cubic surface can be defined by

$$x_0^3 + x_1^3 + x_2^3 + x_3^3 + c_0 x_1 x_2 x_3 + c_1 x_0 x_2 x_3 + c_2 x_0 x_1 x_3 + c_3 x_0 x_1 x_2 = 0$$

in  $\mathbb{P}^3$  for parameters  $c_0, \ldots, c_3$ .

When these parameters are all equal to 0 we obtain the *Fermat cubic* surface

$$x_0^3 + x_1^3 + x_2^3 + x_3^3 = 0$$
.

This is the unique surface realizing an automorphism of class 3C. When p = 3, the surface is not reduced and the 3C stratum is empty. When  $p \ge 5$ , the automorphism group is generated by permutations and multiplying the coordinates by third roots of unity. When p = 2, the automorphism group of the Fermat cubic is the simple group  $PSU_4(2)$  of order 25920. In fact, we will see that the possible automorphism groups of any cubic surface in characteristic 2 are closely related to the subspaces of the non-degenerate Hermitian space  $\mathbb{F}_4^4$ .

1.4. Cyclic Surfaces. A cubic surface X is *cyclic* if there exists a Galois cover of degree 3 over  $\mathbb{P}^2$ . The deck transformation of the cover has class 3A. These surfaces are discussed in more detail in Section 10.3.

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When  $p \neq 3$ , these can always be defined by the form

$$x_0^3 + x_1^3 + x_2^3 + x_3^3 + cx_0x_1x_2 = 0$$

in  $\mathbb{P}^3$  where c is a parameter. The deck transformation g of the cover is generated by  $x_3 \mapsto \zeta_3 x_3$  for a primitive third root of unity  $\zeta_3$ . The ramification locus C is a smooth curve of genus 1.

A subgroup G of the automorphism group of X fits into an exact sequence

$$1 \to \langle g \rangle \to G \to \operatorname{Aut}_{\mathbb{P}^2}(C) \to 1$$

where  $\operatorname{Aut}_{\mathbb{P}^2}(C)$  is the embedded automorphism group of  $C \subset \mathbb{P}^2$ . The group  $\operatorname{Aut}_{\mathbb{P}^2}(C)$  is isomorphic to  $3^2 \rtimes 2$  for a general curve of genus 1. This explains why  $\operatorname{Aut}(X)$  has order 54 for a general X on the 3A stratum. For special values of c, the curve C has additional automorphisms, which give rise to additional automorphisms of X. When  $p \ge 5$ , an additional automorphism of order 4 occurs on the unique surface of class 12A; and one of order 3 occurs on surface of class 3C (the Fermat). When p = 2, there is only one isomorphism class of genus 1 curve with a larger automorphism group: this is another explanation for why the 12A and 3C strata coincide when p = 2.

When  $p \neq 3$ , there are exactly 9 Eckardt points lying in the plane fixed by the deck transformation g. These points are the flexes of the ramification curve C and can be identified with the 3-torsion subgroup of a group structure on C. There are 12 lines that pass through exactly 3 of these points and each point lies on exactly 4 of these lines. Together these points and lines form the *Hesse configuration* (9<sub>4</sub> 12<sub>3</sub>).

When p = 3, we find a different normal form for cyclic surfaces (Proposition 10.10). Here the ramification curve C is a cuspidal cubic instead of an elliptic curve. Nevertheless, the automorphism group for the general cyclic surface is still abstractly isomorphic to the situation when  $p \neq 3$ . Again we find 9 Eckardt points in the Hesse configuration, which can be identified with a subgroup of a group structure on C. For one special surface in the 3A stratum, there is an additional automorphism of C of order 8 that stabilizes this subgroup. This explains why the 8A and 12A strata coincide when p = 3.

1.5. Structure of the paper. We fix notation and review the basics of cubic surfaces in Section 2. The following sections establish several general facts which will be useful in carrying out the classification. In Section 3, we establish some facts about del Pezzo surfaces of degree 4 in arbitrary characteristic; in particular, we classify all the possible automorphism groups. In Section 4, we discuss some interesting phenomena for cubic surfaces that only occur in special characteristics — much of this section is of independent interest. In Section 5, we study the Fermat cubic surface, which has an unusually large automorphism group. In Section 6, we discuss normal forms for general cubic surfaces by Sylvester and Emch — the latter will turn out to be better behaved in general characteristics. In Section 7, we show that the moduli space of cubic surfaces is rational in all characteristics.

The paper then turns to the classification in earnest. For each conjugacy class in  $W(\mathsf{E}_6)$ , we describe the cubic surfaces that admit an automorphism with that class. Sections 8 through 12 go through each possibility, describe automorphism groups acting on these surfaces, and provide normal forms in each case. In Section 13, we consider the possible reflection groups acting on cubic surfaces, which we use in Section 14 to finish the proof of the classification. Finally, in Section 15, we prove Theorem 1.2.

# 2. Preliminaries

Throughout this paper k will be an algebraically closed field and p will denote its characteristic. Moreover, X will be a smooth cubic surface and  $\operatorname{Aut}(X)$  its automorphism group. Note that, since the usual embedding  $X \hookrightarrow \mathbb{P}^3$  is the anti-canonical embedding, we may assume  $\operatorname{Aut}(X) \subseteq$  $\operatorname{PGL}_4(\Bbbk)$ .

It is known (see [9], Corollary 8.2.40, where the proof does not use the assumption on the characteristic) that for any del Pezzo surface  $\mathcal{D}$  of degree  $\leq 5$  the automorphism group  $\operatorname{Aut}(\mathcal{D})$  has a faithful linear representation in the orthogonal complement  $K_{\mathcal{D}}$  of the canonical class in the Picard group  $\operatorname{Pic}(\mathcal{D})$ . This defines an embedding of  $\operatorname{Aut}(\mathcal{D})$  into the Weyl group of the root lattice of type  $\mathsf{E}_{9-d}$ , where, by definition,  $\mathsf{E}_5 = \mathsf{D}_5, \mathsf{E}_4 = \mathsf{A}_4$ . In our case where X is a del Pezzo surface of degree 3, we have a faithful embedding of  $\operatorname{Aut}(X)$  in  $W(\mathsf{E}_6)$ . In particular, since  $|W(\mathsf{E}_6)| = 51840$ , the possible prime orders of automorphisms of X are 2, 3 and 5.

It has been known for more than 150 years that a nonsingular cubic surface contains exactly 27 lines. We will refer to these as *exceptional lines* to differentiate them from other lines in  $\mathbb{P}^3$ . They are exceptional curves of the first kind on X, i.e. smooth rational curves E satisfying  $E^2 = -1$  and  $E \cdot K_X = -1$ . We will identify them with their divisor classes in  $\operatorname{Pic}(X)$ .

A smooth cubic surface X can be obtained by blowing up six points in general position in  $\mathbb{P}^2$  — in this case, this means that no three points are collinear and the six points do not lie on a conic. The exceptional curves of the blow-up are six skew exceptional lines on X. Conversely, given six skew lines  $E_1, \ldots, E_6$  on X, we may blow them down to 6 points  $p_1, \ldots, p_6$  on  $\mathbb{P}^2$ (this is called a *geometric marking* of X). Given a geometric marking, the remaining 21 lines will be labeled by  $F_{ij}$  for the strict transforms of the lines  $\overline{p_i p_j}$ , and  $G_i$  for the strict transforms of the unique conic passing through the five points excluding  $p_i$ .

A *double-sixer* is a set of 12 lines divided into two sets of 6 skew lines such that each line is incident to exactly 5 lines in the other set. An example is  $E_1, \ldots, E_6, G_1, \ldots, G_6$ . There are exactly 36 double-sixers in a cubic surface.

Given any two incident exceptional lines, there is a unique third exceptional line incident to both. We call such a collection a *tritangent trio* there are exactly 45 tritangent trios on a cubic surface. A *tritangent plane* 

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is a hyperplane section of X which consists of three lines, which are a tritangent trio. If the three exceptional lines are concurrent (in other words, they share a common point), then the common point is called an *Eckardt point*.

We will see in Theorem 9.2 below that Eckardt points are in bijection with reflections in the automorphism group of X. In Lemma 9.4 below, we will find that when  $p \neq 2$  there are either 0, 1, or 2 Eckardt points on an exceptional line; but when p = 2 there are 0, 1 or 5 Eckardt points on an exceptional line. A *trihedral line* is a line  $\ell$  which is *not* contained in X and contains exactly three Eckardt points. We will see in Corollary 10.2 that, if a line  $\ell$  contains two Eckardt points and does not lie on X, then  $\ell$  must contain a third Eckardt point.

Below, we will see that Eckardt points are in bijection with automorphisms of class 2A, pairs of Eckardt points sharing a common exceptional line are in bijection with automorphisms of class 2B, and trihedral lines are in bijection with cyclic groups generated by an automorphism of class 3D. Moreover, many of the other automorphism classes correspond to certain geometric arrangements of these objects.

2.1. Group Theoretic notation. Throughout, we use the following notation, some of which is borrowed from [5]:

- $A \rtimes B$  is a semidirect product where A is normal.
- $n^m$  is the abelian group  $(\mathbb{Z}/n\mathbb{Z})^m$ .
- $\mathfrak{S}_n$  is the symmetric group on *n* letters.
- $\mathfrak{A}_n$  is the alternating group on *n* letters.
- $D_{2n}$  the dihedral group of order 2n.
- $\mathcal{H}_n(q)$  is the group of  $n \times n$  strictly upper-triangular matrices with coefficients in the field of q elements.
- $\operatorname{PGL}_n(q)$  is the projective general linear group over a vector space of dimension n with q elements.
- $PSL_n(q)$  is the projective special linear group over a vector space of dimension n with q elements.
- $PSU_n(q)$  is the projective special unitary group over a Hermitian vector space of dimension n with  $q^2$  elements.

We will need the following well-known classification:

**Theorem 2.1.** Let G be a finite subgroup of  $PGL_2(\mathbb{k})$  where  $\mathbb{k}$  is an algebraically closed field of characteristic p. Then G is isomorphic to one of the following groups

- (1)  $G \cong D_{2n}$ , a dihedral group of order 2n where n > 1 is coprime to p.
- (2)  $G \cong \mathfrak{A}_4$ , the alternating group on 4 letters.
- (3)  $p \neq 2$  and  $G \cong \mathfrak{S}_4$ , the symmetric group on 4 letters.
- (4)  $G \cong \mathfrak{A}_5$ , the alternating group on 5 letters.
- (5) p > 0 and  $G \simeq PSL_2(p^n)$  for n > 0.
- (6) p > 0 and  $G \simeq \operatorname{PGL}_2(p^n)$  for n > 0.

(7)  $G \simeq A \rtimes \mu_n$  where *n* is coprime to *p*,  $\mu_n$  is the group of *n*th roots of unity of  $\Bbbk$ , and the group *A* is a  $\mu_n$ -stable finite subgroup of the additive group of  $\Bbbk$ .

### Moreover, all of these possibilities occur.

*Proof.* The classification in characteristic 0 is due to F. Klein [18] and can be found in many modern algebra textbooks. The classification in positive characteristic is essentially due to L. Dickson. We recover it as follows. Since k is algebraically closed, the groups  $PGL_2(k)$  and  $PSL_2(k)$  coincide, so it suffices to find subgroups of the latter. Note that if the lift to  $GL_2(k)$ is reducible, then it must be upper triangular in some basis, and thus is described by the final case in the statement of the theorem. Otherwise, by [26] we may assume that G is contained in  $PSL_2(q)$  for some  $q = p^n$ . From Theorems 3.6.25 and 3.6.26 of [24], we obtain all the remaining cases.  $\Box$ 

**Remark 2.2.** Groups from the last case (7) are always conjugate to a subgroup of the affine group

 $(x:y) \mapsto (mx + ay:y)$ 

for  $m \in \mathbb{k}^{\times}$  and  $a \in \mathbb{k}$ . This case contains cyclic groups of order coprime to p (in particular, all finite cyclic groups when p = 0). This also contains all finite elementary abelian p-groups for p > 0 when n = 1. Note that conjugacy is a delicate question here as, even up to conjugacy, there are infinitely many elementary abelian p-subgroups of the additive group of an infinite field of positive characteristic.

**Remark 2.3.** A group isomorphic to  $2^2$  occurs in all characteristics: it is the degenerate dihedral group  $D_4$  when  $p \neq 2$  and is an elementary abelian 2-group when p = 2. Individual groups may occur multiple times in the above list due to exceptional isomorphisms. For example,  $A_5 \cong \text{PSL}_2(4) \cong$  $\text{PSL}_2(5)$ , and  $\text{PSL}_2(\mathbb{F}) \cong \text{PGL}_2(\mathbb{F})$  for many finite fields  $\mathbb{F}$ .

# 3. Del Pezzo surfaces of degree 4

A smooth cubic surface is isomorphic to the blow-up of one point on a del Pezzo surface of degree 4 that does not lie on any of the 16 lines contained within (in its anti-canonical embedding as a quartic surface in  $\mathbb{P}^4$ ). Since we will use this several times, we will classify automorphism groups of del Pezzo surfaces of degree 4 before moving to cubic surfaces.

When  $p \neq 2$ , the story is not much different than the well-known case of p = 0 discussed in, for example, §8.6 of [9]. The case of p = 2 extends the work in [10].

A del Pezzo surface Y of degree 4 is isomorphic to a complete intersection of two quadrics  $V(q_1) \cap V(q_2)$  in  $\mathbb{P}^4$ . If  $p \neq 2$ , the equations can be reduced to the form

(3.1) 
$$q_1 = x_1^2 + x_2^2 + x_3^2 + bx_4^2 = 0,$$
$$q_2 = x_0^2 + x_2^2 + ax_3^2 + x_4^2 = 0,$$

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otherwise

(3.2) 
$$q_1 = (ab+b+1)x_2^2 + ax_3^2 + x_2y_1 + x_3y_2 = 0$$
$$q_2 = bx_1^2 + (ab+a+1)x_2^2 + x_1y_1 + x_2y_2 = 0.$$

where a and b are parameters. In both cases

(3.3) 
$$\{(1:0), (0:1), (1:-1), (-a:1), (1:-b)\} \subset \mathbb{P}^1(\Bbbk)$$

are the roots of a degree five binary form  $\Delta$ . They correspond to parameters  $(\lambda : \mu) \in \mathbb{P}^1$  such that the quadric  $V(\lambda q_1 + \mu q_2)$  is singular.

In the case  $p \neq 2$ , the equations have an obvious symmetry defined by negations of the projective coordinates. They generate a subgroup of  $\operatorname{Aut}(Y)$ isomorphic to an elementary abelian group  $2^4$ . One can choose generators to be reflections that negate only one coordinate. In the case p = 2, Y has a similar but less obvious group of symmetries. The subgroup  $2^4$  of  $\operatorname{Aut}(Y)$ in either case is generated by reflections in  $\mathbb{k}^5$  defined by

$$\rho_i(v) = v - \frac{b_{\lambda q_1 + \mu q_2}(z_i, v)}{(\lambda q_1 + \mu q_2)(z_i)} z_i,$$

where  $z_i$  are vectors representing the singular points of quadrics in the pencil  $\lambda q_1 + \mu q_2 = 0$  and  $b_{\lambda q_1 + \mu q_2}$  is the associated polar symmetric bilinear form. Here  $(\lambda : \mu)$  must be chosen in such a way that the corresponding quadric does not vanish at any of the points  $z_i$ ; the transformation does not depend on this choice.

The group of automorphisms  $\operatorname{Aut}(Y)$  acts on the coordinates  $(\lambda : \mu)$  of the pencil of quadrics leaving the polynomial  $\Delta$  invariant. In this way we realize  $\operatorname{Aut}(Y)$  as the semi-direct product

$$\operatorname{Aut}(Y) \cong 2^4 \rtimes G,$$

where G is a finite subgroup of  $\mathrm{PGL}_2(\Bbbk)$  that leaves the zeros of the binary form  $\Delta$  invariant. Note that this agrees with the known structure of the Weyl group  $W(\mathsf{D}_5) \cong 2^4 \rtimes \mathfrak{S}_5$ . The group G corresponds to the subgroup of  $\mathfrak{S}_5$  that permutes the roots of  $\Delta$ .

**Theorem 3.1.** The coarse moduli space of del Pezzo surfaces of degree 4 is isomorphic to the coarse moduli space of 5 distinct points in  $\mathbb{P}^1$ . The automorphism group of a given surface Y is isomorphic to  $2^4 \rtimes G$  where G is the subgroup of PGL<sub>2</sub>( $\mathbb{k}$ ) leaving invariant the corresponding set of 5 points. The possible groups are enumerated in Table 2.

*Proof.* If p = 0, the possible groups G and corresponding equations of Y are listed in [9], 8.6.4. We will extend these results using a more uniform approach that works for all characteristics.

Let us explain the remaining columns of Table 2. The (a, b) column give parameters for (3.1) or (3.2) realizing the surface Y on which G acts, while the  $\lambda$  column lists the sizes of the orbits of G on the 5 points.

p	G	(a,b)	$\lambda$
$\neq 2, 3, 5$	1	general	(1, 1, 1, 1, 1)
	2	a = b	(2, 2, 1)
	4	(i,i)	(4, 1)
	$\mathfrak{S}_3$	$(\zeta,\zeta)$	(3, 2)
	$D_{10}$	$(\phi,\phi)$	(5)
2	1	general	(1, 1, 1, 1, 1)
	$2^{2}$	a = b	(4, 1)
	$\mathfrak{A}_5$	$(\zeta,\zeta)$	(5)
3	1	general	(1, 1, 1, 1, 1)
	2	a = b	(2, 2, 1)
	4	(i,i)	(4, 1)
	$D_{10}$	$(\phi,\phi)$	(5)
5	1	general	(1, 1, 1, 1, 1)
	2	(a,a)	(2, 2, 1)
	$\mathfrak{S}_3$	$(\zeta,\zeta)$	(3,2)
	$5 \rtimes 4$	(i,i)	(5)

TABLE 2. Automorphisms of 5 distinct points in  $\mathbb{P}^1$ .

Let  $\zeta$ , i and  $\phi$  be elements of k which are solutions to the equations  $\zeta^2 + \zeta + 1 = 0$ ,  $i^2 + 1 = 0$ , and  $\phi^2 - \phi - 1$ . When p = 0, note  $\zeta$  is a primitive cube root of unity, i is a primitive 4th root of unity, and  $\phi = \frac{1+\sqrt{5}}{2}$  is the Golden ratio. When p = 2, we may assume  $\zeta = \phi$  and note that i = 1 is not permitted for a or b in (3.2) since the 5 points would not be distinct. When p = 3, we have  $\zeta = 1$  which is invalid for a or b in (3.1). When p = 5, we have  $\phi = 3$  and i = 2 or i = 3.

Consider the following matrices:

$$g_2 := \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \ g_3 := \begin{pmatrix} \zeta & 0 \\ 0 & \zeta^{-1} \end{pmatrix}, \ g_4 := \begin{pmatrix} \frac{1+i}{2} & \frac{1-i}{2} \\ \frac{1-i}{2} & \frac{1+i}{2} \end{pmatrix}, \ g_5 := \begin{pmatrix} -\phi & -1 \\ 1 & 0 \end{pmatrix}.$$

With the exception of  $g_4$  when p = 2 and  $g_3$  when p = 3, each matrix  $g_n$  is well-defined and has order n in  $PGL_2(\Bbbk)$ .

We will explicitly describe the groups G that show up in the table. When a = b, the matrix  $g_2$  leaves invariant the 5 points from (3.3). If p = 2 and a = b, then the matrix

$$g_2' = \begin{pmatrix} a & 1\\ 1 & a \end{pmatrix}$$

also leaves invariant the 5 points. Thus when a = b, we have exhibited the group  $G = \langle g_2 \rangle \cong 2$  when  $p \neq 2$  and exhibited  $G = \langle g_2, g'_2 \rangle \cong 2^2$  when p = 2. If  $a = b = \zeta$  and  $p \neq 3$ , then  $\mathfrak{S}_3 \cong \langle g_2, g_3 \rangle \subseteq G$ . If a = b = i and  $p \neq 2$ , then  $4 \cong \langle g_4 \rangle \subseteq G$ . If  $a = b = \phi$ , then  $D_{10} \cong \langle g_2, g_5 \rangle \subseteq G$ . If p = 2, then  $\zeta = \phi$  and so in the case  $a = b = \zeta = \phi$  we obtain  $\mathfrak{A}_5 \cong \langle g_3, g_5 \rangle \subseteq G$ . If p = 5, then in the case where a = b = i we obtain  $5 \times 4 \cong \langle g_4, g_5 \rangle \subseteq G$ ; note that  $\phi$  is equal to one of the two possible values of *i*.

It remains to demonstrate that these are the only subgroups that occur. First, observe that, in any characteristic, there is no non-trivial automorphism of  $\mathbb{P}^1$  which fixes three or more points. Thus, as a subgroup of  $\mathfrak{S}_5$ , the group G cannot contain any transpositions. Up to conjugacy, these are the only subgroups of  $\mathfrak{S}_5$  containing no transpositions:

$$(3.4) 1, 2, 3, 4, 22, 5, \mathfrak{S}_3, D_{10}, 5 \rtimes 4, \mathfrak{A}_5.$$

(Note there are other subgroups isomorphic to 2,  $2^2$  and  $\mathfrak{S}_3$  which do have transpositions.)

This means that G contains elements only of orders 1, 2, 3, 4 and 5; and that an element of order 2 must act as a double transposition in  $\mathfrak{S}_5$ . In characteristic 2, there are no elements of order 4 in PGL<sub>2</sub>( $\Bbbk$ ). In characteristic 3, any element of order 3 can fix at most one point on  $\mathbb{P}^1$ , so 5 points cannot be a disjoint union of orbits. Since cyclic subgroups of fixed order are all conjugate in PGL<sub>2</sub>( $\Bbbk$ ) (consider diagonalizations or Jordan canonical forms), we conclude that every non-trivial cyclic subgroup is generated by one of  $g_2, g_3, g_4, g_5$  up to conjugacy.

Moreover, we claim that up to choice of coordinates the 5 points can be put into the form (3.3) with one of the matrices  $g_2, g_3, g_4, g_5$  given above. For order 2, there is only one fixed point which we may assume is -1; up to scaling, we may assume one of the orbits is  $\{0,\infty\}$  and so the other must be  $\{-a, -a^{-1}\}$  for some choice of a. For the other orders, we only have to show that the group and set of invariant points is unique up to conjugacy: that they can be put in form (3.3) then follows. For order 3, we may assume  $p \neq 3$  and the group acts via  $x \mapsto \zeta x$ , so the two fixed points are 0 and  $\infty$ ; scaling x commutes with the group action, so we may assume the non-trivial orbit contains 1 and so also  $\zeta, \zeta^2$ . For order 4, we may assume  $p \neq 2$  and the group acts via  $x \mapsto ix$  fixing either 0 or  $\infty$ ; scaling x commutes with the group action and so we may assume the non-trivial orbit is  $\{1, -1, i, -i\}$ . The change of coordinates  $x \to x^{-1}$  normalizes the group action and leaves invariant the non-trivial orbit  $\{1, -1, i, -i\}$  and so we may assume the fixed point is 0. For order 5, if we assume  $p \neq 5$ , then the group acts diagonally and we may scale to ensure the orbit consists of the 5 fifth roots of unity. If p = 5, then we may assume the group acts via  $x \mapsto x + 1$  and, possibly after translation, the orbit is  $\{0, 1, 2, 3, 4\}$ .

Due to our choice of coordinates for the 5 points and  $g_2, g_3, g_4, g_5$  above, we see that the presence of an element of order 3 forces G to contain  $\mathfrak{S}_3$ . Using similar arguments, one concludes that the rows of Table 2 are as desired. It only remains to exclude the following possibilities:  $2^2$  and  $\mathfrak{A}_5$ when  $p \neq 2$ , and  $5 \rtimes 4$  when  $p \neq 5$ . Observe that  $2^2$  must fix one of the 5 points; when  $p \neq 2$ , the group  $2^2$  must act faithfully on the tangent space at the fixed point, which is impossible. The group  $\mathfrak{A}_5$  contains a subgroup isomorphic to  $2^2$  and so it also does not occur when  $p \neq 2$ . Finally, the group  $5 \times 4$  acts on  $\mathbb{P}^1$  only when p = 5 by Theorem 2.1.

Let Y be a del Pezzo surface of degree 4. There are 16 exceptional lines. The surface Y can be obtained by blowing up 5 points in general position on the plane, which always lie on a unique conic. Indeed, del Pezzo surfaces of degree 4 are determined up to isomorphism by a set of 5 distinct points on  $\mathbb{P}^1$ .

As we stated earlier, the automorphism group  $\operatorname{Aut}(Y)$  has an injection into the Weyl group  $W(\mathsf{D}_5) \cong 2^4 \rtimes \mathfrak{S}_5$ . One representation of  $W(\mathsf{D}_5)$  is an action on  $\mathbb{Z}^5$  where the group  $\mathfrak{S}_5$  acts by permuting basis elements and the group  $2^4$  acts by multiplying an even number of coordinates by -1. For  $A \subseteq \{1, 2, 3, 4, 5\}$ , we will use the notation  $\iota_A$  to denote the involution multiplying the corresponding coordinates by -1. When A has 4 (resp. 2) elements, we say  $\iota_A$  is an *involution of the first* (resp. *second*) *kind*. The group  $2^4$  is realized on every del Pezzo surface of degree 4 and the group  $2^4$ acts simply transitively on the set of 16 lines.

We recall from [2] that conjugacy classes of elements of the group  $W(D_5)$  correspond to *signed cycle types*. They are listed in Table 3. The trace and characteristic polynomial are for the standard 5-dimensional representation. The column "realizable" indicates whether, and in what characteristics, the corresponding class can be realized on a del Pezzo surface of degree 4 — this is obtained from Theorem 3.1. The class in  $W(E_6)$  indicates the corresponding conjugacy class under the standard embedding  $D_5 \hookrightarrow E_6$ ; this is obtained by comparing characteristic polynomials with those from Table 4 below. Elements in the conjugacy class  $\overline{1111}$  are involutions of the first kind, while elements in the class  $\overline{1111}$  are involutions of the second kind.

It will be useful to explicitly describe the action of  $W(D_5)$  on the 16 lines. Let  $E_1, \ldots, E_5$  be 5 skew lines obtained by blowing up 5 points  $p_1, \ldots, p_5$  on the plane model; let  $F_{ij}$  be the strict transforms of the lines  $\overline{p_i p_j}$  and let G be the strict transform of the unique conic containing all 5 points (this would be  $G_6$  in the cubic surface).

One identifies the 16 lines with sequences in  $\mathbb{F}_2^5$  with an odd number of non-zero entries. The lines  $E_i$  are identified with the standard basis vectors. The lines  $F_{ij}$  are identified with the vectors which have 0's in the *i*th and *j*th spot, but 1's elsewhere. The line G is identified with the vector (1, 1, 1, 1, 1). Two lines are incident if their sum has 4 ones and skew if their sum has 2 ones.

The group  $\mathfrak{S}_5$  acts on  $\mathbb{F}_2^5$  by permuting the coordinates. The normal subgroup  $2^4$  is identified with the subgroup of  $\mathbb{F}_2^5$  consisting of an even number of non-zero entries. The involutions of the first kind correspond to 4 ones, while the involutions of the second kind correspond to 2 ones. The action of  $2^4$  on the 16 lines is simply by addition in  $\mathbb{F}_2^5$ .

This makes computations quite transparent. For example, we now immediately see that involutions of the first kind partition the 16 lines into 8

Order	Name	Trace	Char. Poly	Realizable	Class in $W(E_6)$
1	11111	5	$\Phi_1^5$	yes	1A
2	$111\bar{1}\bar{1}$	1	$\Phi_1^3\Phi_2^2$	yes	2B
2	$1\overline{1}\overline{1}\overline{1}\overline{1}\overline{1}$	-3	$\Phi^1_1\Phi^4_2$	yes	2A
2	2111	3	$\Phi_1^4\Phi_2^1$		$2\mathrm{C}$
2	$21\overline{1}\overline{1}$	-1	$\Phi_1^2\Phi_2^3$		2D
2	221	1	$\Phi_1^3\Phi_2^2$	yes	$2\mathrm{B}$
3	311	2	$\Phi_1^3\Phi_3^1$	p  eq 3	3C
4	$2\bar{2}\bar{1}$	-1	$\Phi_1^1 \Phi_2^2 \Phi_4^1$	yes	4B
4	41	1	$\Phi_1^{ar{2}}\Phi_2^{ar{1}}\Phi_4^{ar{1}}$	$p \neq 2$	4D
4	$\bar{2}11\bar{1}$	1	$\Phi_{1}^{2}\Phi_{2}^{1}\Phi_{4}^{1}$		4D
4	$\bar{2}\bar{1}\bar{1}\bar{1}$	-3	$\Phi_{2}^{\bar{3}}\Phi_{4}^{\bar{1}}$		$4\mathrm{C}$
4	$\bar{2}\bar{2}1$	1	$\Phi_1^{\overline{1}}\Phi_4^{\overline{2}}$	yes	$4\mathrm{A}$
5	5	0	$\Phi^1_1\Phi^1_5$	yes	5A
6	32	0	$\Phi_1^2 \Phi_2^1 \Phi_3^1$		6G
6	$3\bar{1}\bar{1}$	-2	$\Phi_{1}^{ar{1}}\Phi_{2}^{ar{2}}\Phi_{3}^{ar{1}}$	p  eq 3	$6\mathrm{F}$
6	$\bar{3}1\bar{1}$	0	$\Phi_1^1 \Phi_2^2 \Phi_6^1$	p  eq 3	$6\mathrm{C}$
8	$\overline{41}$	-1	$\Phi_2^1\Phi_8^1$	$p \neq 2$	8A
12	$\bar{3}\bar{2}$	0	$\Phi^1_2\Phi^1_4\Phi^1_6$		12C

AUTOMORPHISMS OF CUBIC SURFACES IN POSITIVE CHARACTERISTIC 15

TABLE 3. Conjugacy classes in  $W(D_5)$ .

orbits of incident lines, while involutions of the second kind partition the lines into 8 orbits of skew lines.

The classification of possible groups of automorphisms of a quartic del Pezzo surface shows that the conjugacy classes 2111,  $21\overline{11}$ ,  $\overline{2}11\overline{1}$  and  $\overline{21}\overline{11}\overline{1}$  are never realized geometrically on a del Pezzo surface of degree 4. Similarly, the realizability of the other classes are obstructed or permitted, accordingly.

We will need a fairly detailed understanding of the fixed loci of involutions of the first and second kind. First, note that in the case p = 2, substituting  $y_1 = y_2 = 0$  in the equations (3.2) we get a point

$$p_0 = (a\sqrt{b} + a + \sqrt{a} : \sqrt{ab} : b\sqrt{a} + b + \sqrt{b} : 0 : 0)$$
.

This point is called the *canonical point* of Y in [10]. It is independent of the choice of projective coordinates.

**Proposition 3.2.** If  $p \neq 2$ , the fixed loci of the 5 involutions of the first kind form 5 elliptic curves; the curves in each pair meet at 4 distinct points, which are the fixed locus of an involution of the second kind.

If p = 2, the fixed locus of an involution of the second kind is the canonical point. For an involution  $\tau$  of the first kind there are two possibilities:

 There exists an involution not of the first or second kind commuting with τ. In this case, the fixed locus of τ is a pair of smooth rational curves that are tangent to one another at the canonical point. • Otherwise, the fixed locus is a rational curve with a unique cuspidal singularity at the canonical point.

*Proof.* For  $p \neq 2$ , this is easy to see from the diagonal normal form noting that a complete intersection of smooth quadrics in  $\mathbb{P}^3$  is an elliptic curve.

Let us investigate the case where p = 2 in more detail.

The reflection  $r_1$  corresponding to (1:0) is given by  $r_1(x_3) = x_3 + \frac{1}{a}y_2$  and acts as the identity on the other coordinates. The reflection  $r_2$  corresponding to (0:1) acts similarly via  $r_2(x_1) = x_1 + \frac{1}{b}y_1$ . The reflection  $r_3$  corresponding to (1:1) acts via

$$r_3(x_i) = x_i + \frac{1}{c}(y_1 + y_2)$$
 for  $i = 1, 2, 3$   
 $r_3(y_j) = y_j$  for  $j = 1, 2$ 

where c = ab + a + b + 1.

Let *H* be the fixed point locus of the reflection  $r_3$ ; it is defined by  $y_1 + y_2 = 0$ . Let  $C = H \cap Y$ . The scheme *C* is integral if and only if every member of the restricted pencil is an irreducible conic. The general element of the pencil  $(\lambda q_1 + \mu q_2)|_H$  when restricted to *H* is

$$\mu bx_1^2 + ((\lambda + \mu)(ab + 1) + \lambda b + \mu a)x_2^2 + \lambda ax_3^2 + (\mu x_1 + (\lambda + \mu)x_2 + \lambda x_3)y_1$$

If this is reducible then it has the form

$$(\mu x_1 + (\lambda + \mu)x_2 + \lambda x_3)(Sx_1 + Rx_2 + Tx_3 + y_1)$$
.

Immediately, we see that S = b and T = a by considering the coefficients of  $x_1^2$  and  $x_3^2$ ; and thus  $b\lambda = a\mu$  by considering  $x_1x_3$ . Note  $a \neq 0, 1$  and  $b \neq 0, 1$  or else the half-discriminant  $\Delta$  has multiple zeroes. Thus  $\lambda, \mu \neq 0$ . From the  $x_1x_2$  term we conclude that R = a + b. From the  $x_2^2$  term we obtain  $(\lambda + \mu)(ab + a + b + 1) = 0$ , or equivalently, (a + b)(a + 1)(b + 1) = 0. Since  $a, b \neq 1$ , we conclude that C is reducible if and only if a = b. Note that, from the description of automorphisms above, a = b if and only if there exists a non-trivial involution commuting with  $\tau$  not of the first or second kind.

If C is reducible, then there are two components; one is contained in the plane  $x_1 + x_3 = y_1 + y_2 = 0$  and the other in the plane  $a(x_1 + x_2) + y_1 = y_1 + y_2 = 0$ . One obtains smooth conics in each plane that intersect only at the canonical point where they share the tangent line  $x_1 + x_3 = y_1 = y_2 = 0$ .

If C is irreducible, then one checks that the canonical point is the unique singular point, which is a cusp. Since C has arithmetic genus 1, we conclude that C is a rational curve.  $\Box$ 

#### 4. DIFFERENTIAL STRUCTURE IN SPECIAL CHARACTERISTICS

Here, X is a smooth cubic surface defined by a homogeneous form F of degree 3. Recall that the *Hessian surface* He(X) of X is the hypersurface

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defined by the determinant of the matrix of second partial derivatives of F:

$$H(F) := \det\left(\frac{\partial^2 F}{\partial x_i \partial x_j}\right)$$

The Hessian surface is independent of choice of coordinates for F.

In characteristic 0, we have the following result, essentially due to Dardanelli and van Geeman [6], which partitions the cubic surfaces based on the structure of their Hessian surfaces:

**Theorem 4.1.** Let X be a smooth cubic surface over an algebraically closed field of characteristic 0 and let He(X) be its Hessian hypersurface. Then exactly one of the following holds:

- (a)  $\operatorname{He}(X)$  is irreducible with 10 ordinary double points,
- (b)  $\operatorname{He}(X)$  is irreducible with 7 singularities,
- (c)  $\operatorname{He}(X)$  is irreducible with 4 singularities,
- (d)  $\operatorname{He}(X)$  is a union of a hyperplane and an irreducible surface,
- (e)  $\operatorname{He}(X)$  is a union of 4 hyperplanes.

In [6], they also find normal forms for the cubics in each of these classes; they correspond to (not necessarily closed) subvarieties of the moduli space of smooth cubic surfaces. The cubics in class (a) correspond to those which have a non-degenerate Sylvester form (see Section 6 below). The cubics in classes (d) and (e) correspond to cyclic surfaces (see Section 10.4), with (e) being the Fermat cubic surface (see Section 5).

**Remark 4.2.** The Hessian surfaces constrain the possible automorphism groups of the corresponding cubic surfaces. One could classify cubic surfaces along with their automorphisms by considering each class in turn and using the normal forms given by Dardanelli and van Geeman. Note that surfaces with isomorphic automorphism groups can lie in different classes, however.

In characteristic 2 and 3, the behavior of partial derivatives of cubic forms is very different. In characteristic 2, the Hessian matrix always has zero determinant so Hessian surfaces do not exist. In characteristic 3, the Hessian surfaces exist but the information they encode is more naturally captured by the critical loci of the cubic surfaces, which are non-empty even though the surfaces are smooth! We discuss these differences in the next two sections.

4.1. Canonical Point in characteristic 2. Note that while the Hessian matrix in characteristic 2 always has zero determinant, the matrix itself is not necessarily trivial. In fact, if  $a_{123}, a_{023}, a_{013}, a_{012}$  are the coefficients of the monomials  $x_1x_2x_3, x_0x_2x_3, x_0x_1x_3, x_0x_1x_2$  of a cubic form F defining the surface, we have

$$H(F) = (h_{ij})_{0 \le i \le j \le 3},$$

where  $h_{ii} = 0$  and  $h_{ij} = h_{ji} = x_k a_{ijk} + x_l a_{ijl}$  for i, j, k, l distinct.

The Hessian matrix H(F) evaluated at the point  $y = (y_0, y_1, y_2, y_3)$  is the symmetric matrix associated to the symmetric bilinear form associated to

the polar quadratic form  $P_y(F) = \sum y_i \frac{\partial F}{\partial x_i}$  (this can be checked directly or see [9], Proposition 1.1.17). The singular locus of the corresponding quadric  $V(P_y(F))$  is the projective space associated to the null space of the matrix H(F)(y).

Assume at least one of the  $a_{ijk}$  is non-zero. Let  $v = (a_{123}, a_{023}, a_{013}, a_{012})$ and  $\bar{v}$  be the corresponding point in  $\mathbb{P}^3$ . One checks that H(F)(v) is the zero matrix, and so the singular locus of the quadric  $V(P_v(F))$  is the whole space. Thus  $P_v(F)$  is the square of a linear form. We immediately check that, for all y, we have

(4.1) 
$$H(F)(y) \cdot v = 0$$

We claim that the point  $\bar{v}$  is the unique point with this property. Viewing  $y_0, y_1, y_2, y_3$  as algebraically independent indeterminates, equation (4.1) is equivalent to a linear system of 16 equations in the coordinates of v. The rank of the corresponding  $16 \times 4$  matrix is 3, so we have a unique solution up to proportionality. This establishes the claim.

Let us record what we have found.

**Lemma 4.3.** Let X = V(F) be a smooth cubic surface with p = 2. If the Hessian matrix H(F) is non-zero, then there is a unique vector  $v \in \mathbb{k}^4$  up to scaling such that  $H(F)(y) \cdot v = 0$  at all  $y \in \mathbb{k}^4$ . Given a defining form F for X in coordinates  $x_0, x_1, x_2, x_3$ , we find

$$v = (a_{123}, a_{023}, a_{013}, a_{012})$$

where  $a_{ijk}$  is the coefficient of the monomial  $x_i x_j x_k$  in F. The polar quadratic form  $P_v(F)$  is a square of a linear form.

In the case when  $(a_{123}, a_{023}, a_{013}, a_{012}) \neq 0$  we denote by  $c_X$  the point  $(a_{123}: a_{023}: a_{013}: a_{012}) \in \mathbb{P}^3$  and call it the *canonical point* of X (note that this point does not necessarily lie on X). The linear form whose square is  $P_v(F)$  defines the *canonical plane*.

We find different normal forms for X depending on the behavior of this canonical point. The following can be viewed as a rough analog to Theorem 4.1 in characteristic 2.

**Proposition 4.4.** Assume p = 2. Then exactly one of the following holds:

(a) X has no canonical point and is isomorphic to the Fermat surface defined by

$$x_0^3 + x_1^3 + x_2^3 + x_3^3 = 0$$
.

(b) X has a canonical point but it does not lie on X; the form F has the normal form

$$x_0(x_0 + cx_1)^2 + C(x_1, x_2, x_3) = 0$$
.

(c) X contains its canonical point and the canonical plane is not a tritangent plane; F has the normal form

$$x_0(x_0x_1 + x_2^2) + C(x_1, x_2, x_3) = 0$$

(d) the canonical plane of X is a tritangent plane of X with the canonical point being its Eckardt point; F has the normal form

$$x_0 x_1 (x_0 + x_1) + C(x_1, x_2, x_3) = 0$$
.

In each case, c is a constant and C is a homogeneous cubic form in  $x_1, x_2, x_3$ .

*Proof.* If the canonical point does not exist, then there are no non-zero coefficients of monomials of the form  $x_i x_j x_k$  with i, j, k distinct; this implies that one can write the equation of X in the form  $x_0^2 L_0 + x_1^2 L_1 + x_2^2 L_2 + x_3^2 L_3 = 0$ , where  $L_i$  are linear forms. Note that first partials will be a linear combination of squares  $x_i^2$ . In other words, the first partials are squares of linear forms. We may now conclude this is the Fermat surface by a result of Beauville: implication (iv)  $\Rightarrow$  (v) of Théorème from §2 of [1].

Otherwise, there exists a canonical point that we may assume to be (1 : 0 : 0 : 0). Write the form F defining X as follows:

$$F = a_0 x_0^3 + A_1 x_0^2 + B_2 x_0 + C_3 = 0$$

where  $a_0, A_1, B_2, C_3$  are constant, linear, quadratic, and cubic forms of  $x_1, x_2, x_3$ . We compute the polar  $P = P_{c_X}(X) = a_0 x_0^2 + B_2$  and see that  $B_2$  must be the square of a linear form.

If  $a_0 \neq 0$ , then, by a change of coordinates in  $x_0$  only, we may assume  $B_2$  is a multiple of  $x_1$ . If  $a_0 = 0$ , then by a change of coordinates in  $x_1, x_2, x_3$  we may again assume  $B_2$  is a multiple of  $x_1$ . In either case, the canonical point remains (1:0:0:0). Thus:

$$F = x_0(a_1x_0 + a_2x_1)^2 + A_1x_0^2 + C_3 = 0$$

for  $a_1 = \sqrt{a_0}$  and some constant  $a_2$ . Note that  $c_X \in X$  if and only if  $a_1 = 0$ .

Suppose  $a_1 \neq 0$ . Then we may assume  $a_1 = 1$  and take  $x_0 \mapsto x_0 + A_1$  to obtain the form

$$F = x_0^3 + a_2^2 x_1^2 x_0 + C_3, \ P = (x_0 + a_2 x_1)^2$$

for case (b).

We now suppose  $a_1 = 0$ , so  $c_X \in X$  and  $P = (a_2x_1)^2$ . Since the polar cannot be zero, we may assume  $a_2 = 1$ . Either  $A_1$  is a multiple of  $x_1$  or it is not. The two remaining cases are the obtained from these two possibilities. The facts about tritangent planes are verified using the normal forms.  $\Box$ 

4.2. Critical loci in characteristic 3. The critical locus  $\operatorname{Crit}(X)$  of a projective hypersurface Z is the subscheme defined by the ideal of partial derivatives  $\partial_0 F, \ldots, \partial_n F$ , where F is the homogeneous form defining X. If X has degree m, then by Euler's formula

$$\sum_{i=0}^{n} x_i \partial_i F = mF$$

the critical locus of Z coincides with the singular locus of X when the degree m is coprime to the characteristic. However, when the characteristic divides

the degree, the critical locus may be larger than the singular locus — there may be a non-trivial critical locus even when the variety Z is smooth.

**Proposition 4.5.** Let Z be a smooth hypersurface of degree m in  $\mathbb{P}^n$  over a field k of characteristic p dividing m. If m = 2 and n is even then  $\operatorname{Crit}(Z)$  is empty. Otherwise,  $\operatorname{Crit}(Z)$  is a 0-dimensional closed subscheme of degree  $h^0(\mathcal{O}_{\operatorname{Crit}(Z)})$  equal to

(4.2) 
$$J_m(n) := \frac{(m-1)^{n+1} - (-1)^{n+1}}{m}$$

Proof. Let V be the vector space such that  $\mathbb{P}^n = \mathbb{P}(V)$  and consider  $F \in S^m(V^{\vee}) \cong \mathbb{k}[t_0, \ldots, t_n]_m$ . The differential dF defines a section of  $\Omega^1_{S(V^{\vee})}(m)$ . The critical locus  $\operatorname{Crit}(Z)$  is the scheme of zeros of this section. Note that the intersection  $\operatorname{Crit}(Z) \cap X$  is the set of singular points of the hypersurface X. Since X is smooth,  $\operatorname{Crit}(Z)$  is either empty or purely 0-dimensional. Thus  $h^0(\mathcal{O}_{\operatorname{Crit}(Z)})$  is equal to the Chern number  $c_n(\Omega^1_{\mathbb{P}^n}(m))$ .

The known properties of Chern classes (see [14], Example 3.2.2) allow one to compute  $h^0(\mathcal{O}_{\operatorname{Crit}(Z)})$ . We have  $h^0(\mathcal{O}_{\operatorname{Crit}(Z)}) = J_m(n)$ , where

$$J_{m}(n) = \sum_{i=0}^{n} c_{i}(\Omega_{S(V^{\vee})}^{1}) c_{1}(\mathcal{O}_{\mathbb{P}^{n}}(m))^{n-i}$$
  
$$= \sum_{i=0}^{n} {\binom{n+1}{i}} (-1)^{i} c_{1}(\mathcal{O}_{\mathbb{P}^{n}}(1))^{i} \cdot (mc_{1}(\mathcal{O}_{\mathbb{P}^{n}}(1))^{n-i})$$
  
$$= \sum_{i=0}^{n} {\binom{n+1}{i}} (-1)^{i} m^{n-i}$$
  
$$= \frac{(m-1)^{n+1} - (-1)^{n+1}}{m}.$$

as desired.

**Remark 4.6.** Consider the case m = 2 where Z is a quadric and F is a quadratic form. The critical locus of Z is the set of zeroes of the alternating bilinear form B corresponding to F. For a smooth form when n is odd, the form B is non-degenerate and so the critical locus is always empty. When n is even, the form B is degenerate with a one-dimensional radical in the ambient vector space; thus  $\operatorname{Crit}(Z)$  consists of a single point in  $\mathbb{P}^n$ . This explains why  $J_2(n) = 0$  if n is odd, but  $J_2(n) = 1$  if n is even.

In the particular case of a cubic surface X in characteristic p = 3, we see that  $J_3(3) = 5$ . Since  $\operatorname{Crit}(Z)$  is invariant under projective transformations of X, it is a useful invariant in studying automorphism groups of X.

Another useful observation is that the subspace of perfect cubes spanned by  $x_0^3, \ldots, x_n^3$  form a  $\operatorname{GL}(V)$ -invariant subspace of  $S^3(V^{\vee})$  when p = 3. Thus the quotient space  $S^3(V^{\vee})/\mathbf{F}(V^{\vee})$  has a  $\operatorname{GL}(V)$ -action, where  $\mathbf{F}$  is the Frobenius map raising a linear form to the third power. When dim V = 4, it was shown in [3] and [4] that the quotient space only has finitely many GL(V)-orbits. In particular, the quotient is a prehomogeneous vector space unique to characteristic 3.

These orbits were completely classified by Cohen and Wales in [4] with the help of a computer. Since we are interested only in forms F defining a smooth surface, we state only this part of their classification.

**Proposition 4.7** (Cohen, Wales). Let F be a homogeneous form defining a smooth cubic surface with p = 3. Then F belongs to one of the following  $GL_4(\Bbbk)$ -orbits of cubic forms:

(i) 
$$\left(\sum_{i=0}^{3} c_{i}x_{i}^{3}\right) + x_{0}x_{1}x_{2} + x_{1}x_{2}x_{3} + x_{2}x_{3}x_{0} + x_{3}x_{0}x_{1},$$
  
(ii)  $\left(\sum_{i=0}^{3} c_{i}x_{i}^{3}\right) + x_{0}^{2}x_{1} + x_{2}^{2}x_{3} + x_{3}^{2}x_{1},$   
(iii)  $\left(\sum_{i=0}^{3} c_{i}x_{i}^{3}\right) + x_{0}^{2}x_{1} + x_{0}^{2}x_{2} + x_{0}x_{2}^{2} + x_{1}^{2}x_{2} + x_{0}x_{2}x_{3},$   
(iv)  $\left(\sum_{i=0}^{3} c_{i}x_{i}^{3}\right) + x_{0}^{2}x_{1} + x_{2}^{2}x_{3} + x_{3}^{2}x_{0},$ 

Since the derivative of a perfect cube is trivial when p = 3, the critical locus (and Hessian surface) only depends on the orbit and not the specific surface. We can distinguish the orbits by the support of Crit(X). We obtain points with multiplicities  $\{1, 1, 1, 1, 1\}$ ,  $\{3, 1, 1\}$ ,  $\{4, 1\}$ , and  $\{5\}$  in cases (i),(ii),(iii), and (iv), respectively.

**Remark 4.8.** Cohen and Wales [4] actually computed the stabilizers of each of these elements modulo  $\mathbb{F}(V^{\vee})$ . These stabilizers act as affine transformations on the coordinates  $c_1, \ldots, c_4$ . One can compute all the automorphism groups of smooth cubic surfaces by identifying fixed points of subgroups of this action. As with the proof of Proposition 4.7, this is probably best done with the aid of computers. This can be seen as analogous to the approach of Remark 4.2. Again, surfaces with isomorphic automorphism groups can lie in different classes.

### 5. The Fermat cubic surface

The *Fermat cubic surface* is the cubic surface defined by

$$x_0^3 + x_1^3 + x_2^3 + x_3^4 = 0$$

in  $\mathbb{P}^4(k)$ . This is not even reduced when p = 3, but is smooth in all other characteristics. We will see that the Fermat cubic is the unique smooth cubic surface in the strata 3C when  $p \neq 3$ .

There is an "obvious" group of automorphisms isomorphic to  $3^3 \rtimes \mathfrak{S}_4$ generated by permutations of the coordinates and multiplying coordinates by cube roots of unity. In fact, this is the full group of automorphisms unless p = 2.

**Lemma 5.1.** Let X be the Fermat cubic. Then  $\operatorname{Aut}(X)$  is generated by reflections. If  $p \neq 2, 3$  then  $\operatorname{Aut}(X) \simeq 3^3 \rtimes \mathfrak{S}_4$ . If p = 2 then  $\operatorname{Aut}(X) \simeq \operatorname{PSU}_4(2)$ .

We will consider the case of p = 2 below. When  $p \neq 2, 3$ , Lemma 5.1 follows from the following:

**Lemma 5.2.** Suppose  $d \ge 3$ ,  $n \ge 4$ ,  $p \nmid d-1$ , d and consider the hypersurface Z defined by

$$F = x_0^d + \cdots x_n^d = 0$$

in  $\mathbb{P}^n$ . Then the group of (projective) automorphisms of Z is is isomorphic to  $d^{n-1} \rtimes \mathfrak{S}_n$ .

*Proof.* A slightly stronger result is proved in [23], where the d is only assumed to not be a power of p. The difficulty here is showing that the given automorphism group is the full group of automorphisms and not a proper subgroup.

Recall that the Hessian hypersurface  $\operatorname{He}(Z)$  is the scheme defined by the determinant of the second partials of F. It is intrinsic to the projective embedding and not the choice of coordinates; thus the projective automorphisms of Z induce projective automorphisms of  $\operatorname{He}(Z)$ . The hypersurface  $\operatorname{He}(Z)$  is defined by

$$(d(d-1))^n x_0^{d-2} \cdots x_m^{d-2} = 0 ,$$

which is non-trivial when  $p \nmid d, d-1$ . The automorphisms of He(Z) are clearly generated by permutations of the coordinates and multiplying coordinates by constant factors. To be an automorphism of F, these constant factors must be dth roots of unity.

The Eckardt points and exceptional divisors of the Fermat cubic surface for p > 3 are well known. The automorphism group acts transitively on these objects so it suffices to find one and then obtain the rest by applying automorphisms. There are 18 Eckardt points, one of which is (1:-1:0:0). One exceptional line is defined by  $x_0 + x_1 = x_2 + x_3 = 0$ .

5.1. The Fermat in characteristic 2. In the remainder of the section we establish Lemma 5.1 for p = 2 and describe the geometry of the Fermat cubic in more detail.

Recall that, using a result of A. Beauville, we showed in Proposition 4.4 that the Fermat cubic is the unique smooth cubic surface in characteristic 2 without a canonical point.

Let  $\mathbb{F}_4$  be the field of four elements and let V be a non-degenerate Hermitian inner product space on  $\mathbb{F}_4$  of dimension 4. In other words, if  $\mathbf{F} : \mathbb{F}_4 \to \mathbb{F}_4$ is the Frobenius automorphism defined by  $\mathbf{F}(x) = x^2$ , then we have a nondegenerate Hermitian bilinear form H on  $\mathbb{F}_4^4$  which we may write as

$$H(x,y) = \sum_{i=0}^{3} x_i \mathbf{F}(y_i)$$

where  $x = (x_0, x_1, x_2, x_3)$  and  $y = (y_0, y_1, y_2, y_3)$  are vectors in  $\mathbb{F}_4^4$ . Note that

$$H(x,x) = x_0^3 + x_1^3 + x_2^3 + x_3^3$$

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is the defining equation for the Fermat cubic X in  $\mathbb{P}^3$ . Thus, the automorphism group  $\operatorname{Aut}(X)$  of the Fermat cubic X is the projective special unitary group  $\operatorname{PSU}_4(\mathbb{F}_2)$ . This is a group of order 25920 which has index 2 in the Weyl group  $W(\mathsf{E}_6)$ .

Consider the map  $\sigma$  on X defined on  $\mathbb{F}_4^4$  by

$$\sigma(x_0:x_1:x_2:x_3) = (\mathbf{F}(x_0):\mathbf{F}(x_1):\mathbf{F}(x_2):\mathbf{F}(x_3)) ,$$

which depends on a choice of coordinates. The action of  $\sigma$  preserves  $X(\mathbb{F}_4)$ when written in its diagonal form, permutes the 27 lines and preserves their configuration. Thus  $\sigma$  acts as an element of  $W(\mathsf{E}_6)$ . On the other hand, there is no element  $\sigma$  in  $\mathrm{PSU}_4(2)$  acting in this way — the action of  $\sigma$  is not geometric. Thus  $\sigma$  and  $\mathrm{PSU}_4(2)$  must generate all of  $W(\mathsf{E}_6)$ . In particular, we have proven Lemma 5.1 since the automorphism group of X cannot be larger than  $\mathrm{PSU}_4(2)$ .

The following lemma characterizes the orbits of the various subspaces of  $\mathbb{P}^{3}(\mathbb{F}_{4})$  connected to the geometry of the Fermat cubic. A similar result holds for *any* Hermitian surface (see Theorems 19.1.7 and 19.1.9 of [15]), but we emphasize the connection to cubic surfaces in the statement and its proof.

**Lemma 5.3.** The orbits of Aut(X) on the set of all subspaces of  $\mathbb{P}^3(\mathbb{F}_4)$  are as follows:

- $(C_1)$  45 Eckardt points (these are precisely the points which lie on X).
- $(C_0)$  40 points which do not lie on X.
- $(C_5)$  27 exceptional lines. They each contain precisely 5 Eckardt points.
- $(C_3)$  240 trihedral lines. These contain 3 Eckardt points and 2 non-Eckardt points.
- $(C'_1)$  90 lines that intersect X at exactly one point.
- (C<sub>13</sub>) 45 tritangent planes. Each contains 13 Eckardt points, 8 non-Eckardt points, 3 exceptional lines, 16 trihedral lines, and 2 other lines.
- (C<sub>9</sub>) 40 planes which intersect X in a smooth cubic curve. Each contains 9 Eckardt points, 12 non-Eckardt points, no exceptional lines, 12 trihedral lines, and 9 other lines.
- $(C_{45})$  the whole space.

*Proof.* Recall that  $\mathbb{P}^3(\mathbb{F}_4)$  contains 85 points, 357 lines and 85 planes;  $\mathbb{P}^2(\mathbb{F}_4)$  contains 21 points and 21 lines; and  $\mathbb{P}^1(\mathbb{F}_4)$  contains 5 points.

Since  $x^3 = 1$  for all nonzero  $x \in \mathbb{F}_4$ , the points on X are precisely those with an even number of non-zero coordinates. A short counting argument shows that there are 45 of them. A tangent space computation reveals that any one of them is an Eckardt point. Since  $\operatorname{Aut}(X)$  acts transitively on the Eckardt points, all 45 points on X must be Eckardt points.

There are 40 remaining points that do not lie on X, which we call "non-Eckardt points." These points satisfy  $\langle x, x \rangle = 1$  for any vector x representing them. By the Gram-Schmidt process, any four mutually orthogonal such vectors can be brought to diagonal form by a unitary transformation. In particular, Aut(X) acts transitively on the 40 non-Eckardt points.

Since all the Eckardt points are defined over  $\mathbb{F}_4$ , so must be the 27 exceptional lines between them. They form an orbit of the automorphism group. They each contain 5 Eckardt points since they are projective lines containing only points of X.

The tangent space P at each Eckardt point p contains three exceptional lines, so there are two more lines in P passing through p which do not contain any other Eckardt points. Thus there are  $2 \times 45 = 90$  such lines. The stabilizer of p in Aut(X) acts by  $\mathfrak{S}_3$  on the exceptional lines through p. Thus there is a faithful action of  $\mathfrak{S}_3$  on the tangent space P fixing p. The action of  $\mathfrak{S}_3$  on  $\mathbb{P}^1$  has no fixed points, so the other two lines through p are permuted by an element of Aut(X). Since the Eckardt points are permuted, Aut(X) acts transitively on the 90 lines.

There are 357 - 27 - 90 = 240 remaining lines. Since all lines tangent to a point of X have been identified, only those passing through three distinct points of X remain. These are precisely the lines on which the Hermitian form on the whole space restricts to a nondegenerate Hermitian form (vectors representing the two non-Eckardt points lift to an orthonormal basis). By the Gram-Schmidt process, these lines are all in the same Aut(X) orbit.

Given a subspace  $U \subset \mathbb{F}_4^4$  define the subspace

$$U^{\dagger} := \{ v \in \mathbb{F}_4^4 : \langle v, u \rangle = 0 \text{ for all } u \in U \}$$

called the *polar dual* of U. There is a bijection between planes and points given by the polar dual which commutes with the action of the automorphism group. Thus we have the orbital dichotomy of the planes of  $\mathbb{P}^3(\mathbb{F}_4^4)$ . It remains to characterize them.

For the 45 tritangent planes, we have already seen the 2 lines with a unique Eckardt point and the three exceptional lines. The remaining lines must all pass through the three exceptional lines and thus are trihedral lines. There are 21 - 5 = 16 of them.

Finally, the remaining 40 planes are not tangent to X and thus each intersects X in a smooth cubic curve. Note that any plane containing two exceptional lines must be a tritangent plane, so there are no exceptional lines on the 40 planes. Thus, for each plane P, there must exist three points which lift to linearly independent vectors with non-zero norm. Thus the restriction of the Hermitian form to P is non-degenerate. We immediately check that there are 9 Eckardt points by writing out all the solutions of the form. The remaining counts of lines and points follow from polar duality and the fact that there are 21 points and 21 lines in the whole space.

The notation " $C_n$ " used in the statement is meant to emphasize the connection these subspaces have to the reflection subgroups of  $PSU_4(2)$  constructed in Section 13. Note that the Eckardt points correspond to isotropic

points of the Hermitian form and thus to reflections in  $PSU_4(2)$ . If one excludes  $C'_1$ , the points in each subspace correspond to reflections which generate subgroups of  $W(\mathsf{E}_6)$ . We will see that this gives a bijection between those orbits of subspaces of the Hermitian space  $\mathbb{P}^3(\mathbb{F}_4)$  and the possible automorphism groups of an arbitrary smooth cubic surface in characteristic 2.

Moreover, the Fermat cubic over  $\mathbb{F}_4$  realizes all possible Eckardt points, exceptional lines and trihedral lines. Thus one can study the combinatorics of these objects in arbitrary cubic surfaces over arbitrary fields by consulting the Fermat as a "universal model."

# 6. General forms

We recall the following classical theorem of Sylvester, which can be seen as showing that a generic cubic surface is a nice deformation of the Clebsch.

**Theorem 6.1** (Sylvester). Suppose  $p \neq 2, 3$ . A general smooth cubic surface X is isomorphic to one defined by the forms

(6.1) 
$$\sum_{i=0}^{4} c_i x_i^3 = \sum_{i=0}^{4} x_i = 0$$

in  $\mathbb{P}^4$  where  $c_0, \ldots, c_4 \in \mathbb{k}$  are non-zero parameters. The parameters are uniquely determined up to permutation and common scaling by the isomorphism class of the surface. Moreover, the automorphism group of any such surface is a subgroup of the group  $\mathfrak{S}_5$  which acts by permuting coordinates.

*Proof.* When p = 0, a proof of the first assertion can be found in Theorem 9.4.1 of [9]. An analysis of the proof shows that it works in all characteristics different from 2 and 3.

It remains to determine the automorphism groups of these surfaces. Let  $X = Y \cap P$  be one such surface, where Y is the cubic threefold and P is the hyperplane in the defining equation (6.1). Note that  $X \hookrightarrow P$  is the anticanonical embedding of the cubic surface.

Let C be the union of the 5 coordinate hyperplanes. The intersection  $S = C \cap P$  is a union of 5 planes, no 4 of which have a common point. The collection S is the famous Sylvester pentahedron. The intersections of the planes form 10 lines and 10 vertices. The automorphisms of the pentahedron are simply the permutations of the coordinates  $x_0, \ldots, x_4$ .

Let *H* be the Hessian surface of *X* in *P* (this is *not* the restriction of the Hessian of *Y* constructed in the proof of Lemma 5.2). From §9.4.2 of [9], the equation of the Hessian surface embedded in  $\mathbb{P}^4$  is

$$\sum_{i=0}^4 (c_0 \cdots \widehat{c_i} \cdots c_4) (x_0 \cdots \widehat{x_i} \cdots x_4) = \sum_{i=0}^4 x_i = 0 .$$

Since all the parameters are assumed non-zero, we may rewrite this as

$$x_0 \cdots x_4 \left(\sum_{i=0}^4 \frac{b_i}{x_i}\right) = \sum_{i=0}^4 x_i = 0$$

where  $b_i = c_i^{-1}$ . We will describe the singular locus of H. There are 10 additional conditions  $C_{ij}$  defining the singular locus defined by minors of a  $5 \times 2$  matrix. For example, we have

$$C_{01} := (b_1 - b_0)x_2x_3x_4 + (x_1 - x_0)(x_2x_3b_4 + x_2b_3x_4 + b_2x_3x_4) .$$

If all the  $x_i$  are non-zero then we may use the condition  $\sum \frac{b_i}{x_i} = 0$  to show that these conditions are equivalent to  $b_j x_i^2 = b_i x_j^2$ . By [9], Proposition 9.4.5, these are precisely the conditions for the original cubic to be singular at the given point; thus, we may assume at least one  $x_i$  is zero. If one  $x_i$  is zero, then another must be zero as well by the original equation for H. If  $x_0 = x_2 = 0$  then the condition  $C_{01}$  shows that that a third coordinate must be zero; this applies for any pair of coordinates. Thus, we conclude that there are exactly 10 singular points — namely the  $\mathfrak{S}_5$ -orbit of (1: -1: 0: 0: 0).

The singular points of H are precisely the 10 vertices of the pentahedron, and the 10 lines lie on H. Thus, one can reconstruct the pentahedron using the Hessian surface. The surface H is canonical, thus the pentahedron is as well. Thus the expression (6.1) is unique up to permutation and multiplication by a common non-zero scalar. We conclude that automorphisms of Xare subgroups of  $\mathfrak{S}_5$  that act by permuting the coordinates.

When p = 3, Sylvester's theorem fails since the corresponding cubic is not even reduced. In p = 2, the theorem also fails, but for a more subtle reason. Viewing the equation (6.1) over  $\mathbb{Z}$ , we may assume without loss of generality that  $c_4 = 1$  and eliminate  $x_4$  to obtain

$$\sum_{i=0}^{3} (c_i - 1) x_i^3 - \sum_{0 \le i \le j \le 3} 3x_i^2 x_j - \sum_{0 \le i < j < k \le 3} 6x_i x_j x_k = 0.$$

Since there are no terms of the form  $x_i x_j x_k$  if p = 2, there is no canonical point. Thus by Proposition 4.4, we see that any surface in Sylvester's form is isomorphic to the Fermat cubic — a unique surface is not generic!

**Remark 6.2.** We define the *Clebsch cubic surface* as the cubic surface admitting a group of automorphisms isomorphic to  $\mathfrak{S}_5$ . We shall see that it is unique up to isomorphism when it exists and corresponds to the stratum 5A in the moduli space of cubic surfaces. Classically, the Clebsch cubic surface is defined as the cubic surface given by equations (6.1) with  $(c_0, c_1, c_2, c_3, c_4) = (1, 1, 1, 1, 1)$ . Here permutations of the coordinates generate a group isomorphic to  $\mathfrak{S}_5$ . Note that the construction fails in characteristic 3 and 5. In characteristic 3 it is not even reduced; while in characteristic 5, the point (1:1:1:1:1) is singular. If  $p \neq 5$ , alternate equations for the

Clebsch are

$$\sigma_3 = \sigma_1 = 0$$

where  $\sigma_i$  denotes the elementary symmetric polynomial of degree *i* in the variables  $x_0, \ldots, x_4$ . This provides a cubic surface with an  $\mathfrak{S}_5$ -action, which is smooth when  $p \neq 5$ . We shall see that there is no Clebsch surface in characteristic 5.

We would like a generic form that works in all characteristics. The following normal form is due to Emch [12] who described it for cubic surfaces over  $\mathbb{C}$ . As Sylvester's normal form is a nice deformation of the Clebsch cubic surface, Emch's normal form is a nice deformation of the Fermat cubic surface.

**Theorem 6.3** (Emch). A general smooth cubic surface over an algebraically closed field of arbitrary characteristic can be defined by the form

(6.2) 
$$\sum_{i=0}^{3} x_i^3 + \sum_{0 \le i < j < k \le 3} a_{ijk} x_i x_j x_k$$

in appropriate coordinates  $x_0, \ldots, x_3$  where  $a_{012}, \ldots, a_{123}$  are parameters.

**Remark 6.4.** Some of these surfaces are singular. For example, setting all parameters  $a_{ijk}$  to -1, the surface has a singular point (1:1:1:1). If all the parameters in (6.2) are non-zero, then by rescaling the coordinates we obtain

(6.3) 
$$\sum_{i=0}^{3} c_i x_i^3 + \sum_{0 \le i < j < k \le 3} x_i x_j x_k$$

which is the first normal form from Proposition 4.7 in characteristic 3.

*Proof.* Our argument is inspired by the argument in [4] for the case p = 3. We will use the equivalent form (6.3) throughout the proof. Let  $V_0$  be the span of the monomials  $x_0^3, \ldots, x_3^3$  in Sym<sup>3</sup>( $\mathbb{k}^4$ ). Define the form

$$F_0 = \sum_{0 \le i < j < k \le 3} x_i x_j x_k \; .$$

It suffices to show that a generic orbit of  $G = \operatorname{GL}_4(\mathbb{k})$  intersects the affine subspace  $F_0 + V_0$  in at most finitely many points. We will do this by showing that the tangent space to the orbit at some F in this subspace is transverse to the space  $V_0$ .

Let F be a form as in (6.3). Let  $E_{ij}$  be the usual basis of the Lie algebra  $\mathfrak{gl}_4(\Bbbk)$  where  $E_{ij}(x_j) = x_i$ . The induced action of  $\mathfrak{gl}_4(\Bbbk)$  on  $\operatorname{Sym}^3(\Bbbk^4)$  is given by the usual Leibniz rule

$$E_{ij}(x_k x_l x_m) = E_{ij}(x_k) x_l x_m + x_k E_{ij}(x_l) x_m + x_k x_l E_{ij}(x_m) .$$

For i, j, k, l distinct, we obtain

$$E_{ii}(F) = 3c_i x_i^3 + x_i x_j x_k + x_i x_j x_l + x_i x_k x_l$$
  

$$E_{ij}(F) = 3c_j x_j^2 x_i + x_i^2 x_k + x_i^2 x_l + x_i x_k x_l.$$

Writing

$$M = \sum_{i,j} m_{ij} E_{ij}$$

for a general element of  $\mathfrak{gl}_4(k)$ . The tangent space T of the orbit of G(F) is spanned by M(F) as the coefficients  $m_{ij}$  vary.

We find the coefficient of  $x_i^2 x_j$  in M(F) is:

(6.4) 
$$3c_i m_{ji} + m_{ik} + m_{il}$$

while the coefficient of  $x_i x_j x_k$  is:

$$(6.5) m_{ii} + m_{jj} + m_{kk} + m_{il} + m_{jl} + m_{kl}$$

The zero set  $Z_F$  of these expressions will give the infinitesimal transformations along the space  $V_0$ . As F varies in the space  $F_0 + V_0$ , so does  $Z_F$ . Since the dimension of  $Z_F$  is upper semicontinuous in F, it suffices to show  $Z_F$  is zero-dimensional at some point F.

If  $p \neq 2$ , we consider the point  $F = F_0$ . From (6.4) we obtain conditions  $m_{ik} = -m_{il}$  for all i, k, l distinct. This forces  $m_{ik} = -m_{il} = m_{ij} = -m_{ik}$  for all i, j, k, l distinct, thus all the off-diagonal elements of M must be zero. We are left with the conditions that  $m_{ii} + m_{jj} + m_{kk} = 0$  for all distinct i, j, k. This has no non-trivial solution in characteristic  $\neq 3$ . In characteristic 3, we obtain only the scalar matrices — this tangent direction disappears in the projectivization.

We use a different point for characteristic 2. Consider  $(c_0, c_1, c_2, c_3) = (\lambda, \lambda, \lambda, \lambda)$  where  $\lambda \neq 0, 1$ . Adding together the coefficients of  $x_i^2 x_j$ ,  $x_i^2 x_k$  and  $x_i^2 x_l$  we obtain

$$S_i := m_{ji} + m_{ki} + m_{li} = 0$$

Adding together the coefficients of  $x_i^2 x_j$ ,  $x_k^2 x_j$  and  $x_l^2 x_j$  we obtain

$$\lambda(m_{ji} + m_{jk} + m_{jl}) = m_{ji} + m_{jk} + m_{jl}$$

using  $S_i$ ,  $S_k$  and  $S_l$  relations. Since  $\lambda \neq 1$ , we conclude that

$$T_j := m_{ji} + m_{jk} + m_{jl} = 0$$
.

Summing together the coefficient of  $x_i^2 x_j$  with  $T_i$  we see that  $\lambda m_{ji} = m_{ij}$ . Adding together  $x_j^2 x_i$  and  $T_j$ , we conclude that  $\lambda m_{ij} = m_{ji}$ . Thus all the off-diagonal elements are zero. We conclude that the diagonal elements are also zero by the same argument as before.

**Remark 6.5.** Above we show that a general smooth cubic surface can be written in Emch's normal form. If  $p \neq 2$ , then certainly not every smooth cubic surface can be written in this form. However, if p = 2, it may be that *every* smooth cubic surface can be written in Emch's normal form! If true, then the normal forms for p = 2 in later sections could be greatly simplified.

**Remark 6.6.** In characteristic zero, in a sequel paper [13], Emch proves that there are 40 different ways of writing a general cubic surface in the normal form (6.2). The different ways naturally correspond to *Steiner complexes* (see  $\S9.1.1$  of [9]) or *summit planes* (see [7]).

Using the general normal forms we may produce large families of groups with specified automorphism groups:

**Lemma 6.7.** If  $p \neq 2$  then there exist d-dimensional strata of smooth cubic surfaces X such that

(1A) Aut(X) = 1 with d = 4, (2A) Aut(X) =  $\mathfrak{S}_2$  with d = 3, (2B) Aut(X) =  $\mathfrak{S}_2 \times \mathfrak{S}_2$  with d = 2, (3D) Aut(X) =  $\mathfrak{S}_3$  with d = 2, (4B) Aut(X) =  $\mathfrak{S}_4$  with d = 1, (6E) Aut(X) =  $\mathfrak{S}_3 \times \mathfrak{S}_2$  with d = 1, and (5A) Aut(X) =  $\mathfrak{S}_5$  with d = 0 provided  $p \neq 5$ .

*Proof.* First, assume  $p \neq 3$ . Using Sylvester's normal form, we consider the induced action of  $\mathfrak{S}_5$  on the projective space of parameters. The stabilizers of this action correspond to cubic surfaces with those groups as their full automorphism group. The points with non-trivial stabilizers are obtained by setting certain parameters equal to one another. One obtains precisely the groups in the statement of the theorem provided there exists a smooth cubic surface in each family. One checks all families have a smooth member with the exception of the  $\mathfrak{S}_5$ -surface in characteristic 5.

Now assume p = 3. Consider the first normal form from Proposition 4.7, which after rescaling coordinates, is equal to Emch's normal form. As noted in Section 4.2, the critical locus consists of 5 distinct points which span the ambient projective space. Thus the possible automorphisms are subgroups of  $\mathfrak{S}_5$ .

Apply the change of coordinates

$$x_i \mapsto \left(\sum_{j=0}^3 x_j\right) + x_i$$

to obtain the normal form

(6.6) 
$$\left(\sum_{i=0}^{3} d_{i}x_{i}^{3}\right) - \sum_{0 \le i \le j \le 3} x_{i}^{2}x_{j} + \sum_{0 \le i < j < k \le 3} x_{i}x_{j}x_{k} = 0.$$

Where the  $d_i$ 's are general parameters. The advantage of this normal form is that the  $\mathfrak{S}_5$ -action is more transparent: it is generated by permutations of the  $x_i$ 's and the matrix

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & -1 & -1 & -1 \end{pmatrix}$$

of order 5. Moreover,  $\mathfrak{S}_5$  acts linearly on the vector space spanned by the parameters  $\{d_0, \ldots, d_3\}$  (the action is via affine transformations in the original normal form). As for  $p \neq 3$ , the stabilizers are linear subspaces of the desired dimensions and each contains a point which corresponds to a smooth cubic surface.

The link with partitions of 5 is more tenuous when p = 2 as the automorphism groups are often larger. However, we have the following:

**Lemma 6.8.** If p = 2 then there exist d-dimensional strata of smooth cubic surfaces X such that

(1A)  $1 \subseteq \operatorname{Aut}(X)$  with d = 4, (2A)  $\mathfrak{S}_2 \subseteq \operatorname{Aut}(X)$  with d = 3, (2B)  $\mathfrak{S}_2 \times \mathfrak{S}_2 \subseteq \operatorname{Aut}(X)$  with d = 2, (3D)  $\mathfrak{S}_3 \subseteq \operatorname{Aut}(X)$  with d = 2, (4B)  $\mathfrak{S}_4 \subseteq \operatorname{Aut}(X)$  with d = 1, (5A)  $\mathfrak{S}_5 \subseteq \operatorname{Aut}(X)$  with d = 0.

Proof. As with the Sylvester form, if one sets the parameters of (6.3) equal to one another, we obtain subgroups of  $\mathfrak{S}_4$  as automorphisms. This exhibits automorphisms of the desired forms for all except  $\mathfrak{S}_5$ . Each of these strata gives an affine subspace W of  $V_0 + F_0$  with the desired dimension d from the proof of Theorem 6.3. It was shown that a form with all parameters equal gives a point of  $V_0 + F_0$  which meets transversely with the orbits of  $\mathrm{PGL}_4(\Bbbk)$ . Such points are in W for every case. By upper semicontinuity, we conclude the orbits of  $\mathrm{PGL}_4(\Bbbk)$  meet  $V_0 + F_0$  in an open subset of the points of W transversely as well. The Fermat cubic has  $\mathfrak{S}_5$  symmetry when p = 2 since  $\mathfrak{S}_5 \subset \mathrm{PSU}_4(2)$ .

Lemmas 6.7 and 6.8 give open subsets of the automorphism strata in the moduli space of cubic surfaces, which is indicated by the labeling of the cases. However, in general they are not the whole strata — the Sylvester or Emch form may only describe a general element in the family.

### 7. RATIONALITY OF THE MODULI SPACE

Recall that the moduli space of complex cubic surfaces is known to be rational. The proof either uses the explicit structure of the algebra of invariants due to Clebsch, or the Sylvester form of a general cubic surface (see [9], 9.4.3). Using the latter, the proof goes as follows. The space of cubics in Sylvester form can be identified with an open subset of the affine space  $\Bbbk^4$  spanned by  $c_1/c_0, \ldots, c_4/c_0$  (see Theorem 6.1). Two forms correspond to isomorphic surfaces if and only if they are in the same  $\mathfrak{S}_5$  orbit, where  $\mathfrak{S}_5$  acts on the affine space via the standard action modulo the degree 1 elementary symmetric function. By the fundamental theorem of symmetric functions, the invariant ring is a polynomial ring; thus the quotient is rational. Since Sylvester's Theorem also applies in positive characteristic  $p \neq 2, 3$ , the proof of rationality carries over to these cases as well. In this section, using results about normal forms of general cubic surfaces, we prove the following:

**Theorem 7.1.** Over an algebraically closed field of arbitrary characteristic, the coarse moduli space  $\mathcal{M}_{cub}$  of smooth cubic surfaces is rational.

*Proof.* By the above, we have to deal only with cases when p = 2 or p = 3. First, we assume that p = 3.

A generic cubic surface can be put into the normal form 6.6, where once again two normal forms correspond to isomorphic surfaces if and only if they are in the same  $\mathfrak{S}_5$ -orbit. Once again, the action on the affine space  $\mathbb{k}^4$  spanned by  $d_0, \ldots, d_3$  is again the standard 4-dimensional irreducible representation of  $\mathfrak{S}_5$ , so the quotient is rational.

Now we assume p = 2. Note that the existence of a canonical point is an open condition on the moduli space, and the canonical point lying on the surface is a closed condition. Thus, the isomorphism classes of cubic surfaces from class (b) in Proposition 4.4 form a Zariski open subset in the moduli space. By generality, we may assume that the coefficient c in  $(x_0 + cx_1)^2$  is not zero, and by scaling  $x_1$ , it is equal to 1. Write the cubic form  $C(x_1, x_2, x_3)$  in the form

$$C(x_1, x_2, x_3) = c_1 x_1^3 + x_1^2 L(x_2, x_3) + x_1 Q(x_2, x_3) + P(x_2, x_3).$$

The surface is singular unless the homogeneous form P has three distinct roots in  $\mathbb{P}(x_2 : x_3)$ , which we may take to be (1 : 0), (0 : 1), and (1 : 1). Scaling, we may assume that  $P(x_2, x_3) = x_2 x_3 (x_2 + x_3)$ . By a linear change of coordinates via  $x_2 \mapsto a_1 x_1 + x_2$  and  $x_3 \mapsto a_2 x_1 + x_3$ , we may select  $a_1$ and  $a_2$  so that the coefficients of  $x_2^2$  and  $x_3^3$  are zero in  $Q(x_2, x_3)$ . Thus a general cubic surface is defined by

$$x_0(x_0+x_1)^2 + b_1x_1^3 + x_1^2(b_2x_2+b_3x_3) + b_4x_1x_2x_3 + x_2x_3(x_2+x_3) = 0$$

for parameters  $b_1, \ldots, b_4$ . Since the surface has a canonical point, we may assume  $b_4 \neq 0$ . By scaling we obtain the form

$$(7.1) \ x_0(x_0+x_1)^2 + (c_1/c_4)x_1^3 + x_1^2(c_2x_2+c_3x_3) + x_1x_2x_3 + c_4x_2x_3(x_2+x_3) = 0$$

where  $c_1, \ldots, c_4$  are parameters, which we may assume are all non-zero.

Suppose two cubic surfaces in form (7.1) are isomorphic (for possibly different values of  $c_1, \ldots, c_4$ ). Let  $\psi \in \mathrm{PGL}_4(\Bbbk)$  be a map taking one form to the other. Since the point (1:0:0:0) is canonical, there is a unique representative  $A \in \mathrm{GL}_4(\Bbbk)$  for  $\psi$  whose first column is the first standard basis vector (1,0,0,0). We set  $\psi^* : k[x_0,\ldots,x_3] \to k[x_0,\ldots,x_4]$  on the homogeneous coordinate ring to be the dual action of A on the corresponding total space  $\mathbb{A}^4$ . Since the monomials  $x_0^3$  and  $x_0 x_1^2$  are the only monomials in (7.1) containing  $x_0$ , we see that  $\psi^*(x_0) = x_0$  and  $\psi^*(x_1) = x_1$ . Thus, we are left with

$$\psi^*(x_2) = a_1 x_1 + a_2 x_2 + a_3 x_3$$
  
$$\psi^*(x_3) = a_4 x_1 + a_5 x_2 + a_6 x_3$$

where  $a_1, \ldots, a_6$  are to be determined.

We explicitly determine the coefficients of the monomials in the transformed equation:

- (7.2)  $x_1 x_2^2 \colon c_4 a_1 a_5^2 + c_4 a_2^2 a_4 + a_2 a_5$
- (7.3)  $x_1 x_3^2 : c_4 a_1 a_6^2 + c_4 a_3^2 a_4 + a_3 a_6$
- $(7.4) x_1 x_2 x_3 : a_2 a_6 + a_3 a_5 .$

Let  $B = \begin{pmatrix} a_2 & a_3 \\ a_5 & a_6 \end{pmatrix}$  be the bottom right 2 × 2 submatrix of A, which represents the action of  $\psi^*$  considering only the variables  $x_2, x_3$ . Since we assume  $c_4 \neq 0$ , the map  $\psi^*$  must leave  $x_2x_3(x_2 + x_3)$  fixed. From (7.4), we conclude that B must have determinant 1. We conclude that B is an invertible matrix consisting of 0's and 1's.

The expressions (7.2) and (7.3) must be zero, which amounts to a linear system of  $a_1, a_4$  if the other variables are fixed. Since  $\det(B) \neq 0$ , this linear system has unique solution  $a_1 = \frac{a_2 a_3}{c_4}$  and  $a_4 = \frac{a_5 a_6}{c_4}$ . Bearing in mind that *B* is a non-singular matrix consisting only of 0's and

Bearing in mind that B is a non-singular matrix consisting only of 0's and 1's, one computes that  $\psi$  induces the following action on the affine space  $\mathbb{A}^4$  spanned by  $c_1, c_2, c_3, c_4$ :

$$c_1 \mapsto c_1 + a_2 a_3 c_2 + a_5 a_6 c_3$$
$$c_2 \mapsto a_2 c_2 + a_5 c_3$$
$$c_3 \mapsto a_3 c_2 + a_6 c_3$$
$$c_4 \mapsto c_4 .$$

These form a group isomorphic to  $\mathfrak{S}_3$  where, for example, two generators are obtained from

$$B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$
 and  $B = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$ .

Using the coordinates  $c'_1 = c_1$ ,  $c'_2 = c_1 + c_2$ ,  $c'_3 = c_1 + c_3$ ,  $c'_4 = c_4$ , we see that the possible  $\psi$ 's act as the group  $\mathfrak{S}_3$  by permuting the parameters  $c'_1, c'_2, c'_3$ and leaving  $c'_4$  fixed. By the fundamental theorem of symmetric functions, the quotient  $\mathbb{A}^4/\mathfrak{S}_3$  is rational and, thus, so is the moduli space of cubic surfaces.

#### 8. Conjugacy classes of automorphisms

Our strategy for establishing the classification is as follows. For each conjugacy class in  $W(\mathsf{E}_6)$  we will describe the smooth cubic surfaces that

have an automorphism whose image in  $W(\mathsf{E}_6)$  has that class. In the interest of brevity, we will write for example "X admits an automorphism of class 3D" or simply "X is a 3D surface." In each case, we will describe the automorphism group of each surface and determine normal forms for the corresponding cubic surfaces. In many cases, while we will actually describe the full automorphism group initially, the proof that there are no further automorphisms will be deferred until Section 14.

Except for the cases 4A, 8A and 12A, we will show that the existence of an automorphism of a given class implies the existence of a reflection group acting on the surface which contains the given automorphism. These will frequently turn out to be the full automorphism groups of the generic surface admitting each class.

After we have gone through all the conjugacy classes, it will remain to prove that we have indeed described the full automorphism groups of these surfaces and that the corresponding strata in the moduli space have the expected dimensions. This matter will occupy Sections 13 and 14.

We recall the conjugacy classes of elements of  $W(\mathsf{E}_6)$  in Table 4 along with their trace and characteristic polynomials of their actions on the standard 6-dimensional vector space (see Chapter 9 of [9]).

Fortuitously, the characteristic polynomials uniquely determine the conjugacy classes. Using the characteristic polynomials, one can easily compute the classes of the non-trivial powers of a given element. The table also lists under what characteristic assumptions the given classes can be realized by an action on a cubic surface; we will explicitly construct realizations in the following sections. However, it is easy to see that the many of the remaining classes are *not* realizable:

**Lemma 8.1.** The classes 2C, 2D, 4C, 4D, 6G, 6H, 6I, 10A and 12C are not realizable over a cubic surface of any characteristic. Additionally, if p = 2 then 8A is not realizable; if p = 3 then 3C, 6C, 6F are not realizable.

**Proof.** Suppose that  $\alpha$  is an automorphism of a smooth cubic surface and g is its class in  $W(\mathsf{E}_6)$ . First, note that if g is in the image of  $\tilde{g}$  via the standard embedding  $W(\mathsf{D}_5) \hookrightarrow W(\mathsf{E}_6)$ , then there exists an exceptional divisor which can be blown down which realizes  $\tilde{g}$  on a del Pezzo surface of degree 4. Consulting Table 3, we may thus exclude 2C, 2D, 4C, 4D, 6G, 12C. In characteristic 2, we may exclude 8A. In characteristic 3, we may exclude 3C, 6C, and 6F.

The class 6H can be excluded since its cube has class 2C, which has already been excluded. Similarly, 6I can be excluded since its cube has class 2D, and 10A can be excluded since its fifth power is 2C.  $\Box$ 

There are two additional excluded cases not covered by Lemma 8.1 since the corresponding proofs are a bit more involved. When p = 3, we will see that the class 9A does not occur in Lemma 10.14 below. When p = 5, we will see that the class 5A does not occur by Lemma 12.1 below.

Name	Trace	Char. Poly	Realizable	Powers
1A	6	$\Phi_1^6$	yes	
2A	-2	$\Phi_1^2\Phi_2^4$	yes	
2B	2	$\Phi_1^4\Phi_2^2$	$\mathbf{yes}$	
2C	4	$\Phi_1^{ar{5}}\Phi_2^{ar{1}}$		
2D	0	$\Phi_1^3\Phi_2^3$		
3A	-3	$\Phi_3^3$	yes	
3C	3	$\Phi_1^4\Phi_3^1$	p  eq 3	
3D	0	$\Phi_1^2\Phi_3^2$	$\mathbf{yes}$	
4A	2	$\Phi_1^2 \Phi_4^2$	yes	2A
4B	0	$\Phi_1^2\Phi_2^2\Phi_4^1$	$\mathbf{yes}$	$2\mathrm{B}$
4C	-2	$\Phi_1^{ar{1}}\Phi_2^{ar{3}}\Phi_4^{ar{1}}$		$2\mathrm{B}$
4D	2	$\Phi_{1}^{ar{3}}\Phi_{2}^{ar{1}}\Phi_{4}^{ar{1}}$		$2\mathrm{B}$
5A	1	$\Phi_1^2\Phi_5^1$	$p \neq 5$	
6A	1	$\Phi^1_3\Phi^2_6$	yes	2A, 3A
6C	1	$\Phi_{1}^{2}\Phi_{2}^{2}\Phi_{6}^{1}$	p  eq 3	2A, 3C
6E	-2	$\Phi_{2}^{2}\Phi_{3}^{1}\Phi_{6}^{1}$	$\mathbf{yes}$	2A, 3D
6F	-1	$\Phi_{1}^{2}\Phi_{2}^{2}\Phi_{3}^{1}$	p  eq 3	2B, 3C
6G	1	$\Phi_{1}^{3}\Phi_{2}^{1}\Phi_{3}^{1}$		2C, 3C
6H	-2	$\Phi_{1}^{ar{1}}\Phi_{2}^{ar{1}}\Phi_{3}^{ar{2}}$		2C, 3D
6I	0	$\Phi_1^{ar{1}}\Phi_2^{ar{1}}\Phi_3^{ar{1}}\Phi_6^{ar{1}}$		2D, 3D
8A	0	$\Phi^{1}_{1}\Phi^{1}_{2}\Phi^{1}_{8}$	$p \neq 2$	2A, 4A
9A	0	$\Phi_9^1$	$p \neq 3$	3A
10A	-1	$\Phi^{1}_{1}\Phi^{1}_{2}\Phi^{1}_{5}$		2C, 5A
12A	-1	$\Phi^1_3 \Phi^1_{12}$	yes	2A, 3A, 4A, 6A
12C	1	$\Phi_1^1 \Phi_2^1 \Phi_4^1 \Phi_6^1$		2B, 3C, 4C, 6F

TABLE 4. Cyclic subgroups of  $W(\mathsf{E}_6)$ 

**Remark 8.2.** In characteristic 0, T. Hosoh [16] determined all the possible automorphism groups of a smooth cubic surface using computers. His method was to explicitly construct the moduli space of marked cubic surfaces and explicitly determine the action of  $W(\mathsf{E}_6)$  on this space. The possible automorphism groups are the non-trivial stabilizers of this action. The same approach works in arbitrary characteristic, but is not feasible to do by hand and does not produce normal forms.

**Remark 8.3.** In Section 9.5 of [9], the first author computed all the possible automorphism groups of smooth cubic surfaces in characteristic 0. The approach there was to first consider the cyclic automorphisms. These were determined by considering every possible diagonal matrix with order the same as an element of  $W(\mathsf{E}_6)$  and determining whether they leave a smooth cubic hypersurface invariant. The class of each automorphism in  $W(\mathsf{E}_6)$  was then computed using the Lefschetz fixed point formula. One may carry out an analogous procedure in positive characteristic. Here, one must also consider Jordan canonical forms rather than only diagonal matrices and to compute the classes in  $W(\mathsf{E}_6)$  one can use a fixed point formula of S. Saito [19]. We use some of these ideas in what follows, but we do not carry out this program systematically.

# 9. Involutions

**Proposition 9.1.** Let X be a smooth cubic surface in the space  $\mathbb{P}(V)$  where V is a four-dimensional vector space. Suppose g is an involution of  $\mathbb{P}(V)$  leaving X invariant. Then one of the following holds:

(1) Up to choice of coordinates, g has a lift  $\tilde{g} \in GL(V)$  of the form

(9.1) 
$$\widetilde{g} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

The element g corresponds to an element of class 2A in  $W(E_6)$ . The automorphism g only leaves invariant three exceptional lines, which lie in a tritangent plane T. The remaining 24 lines are partitioned into 12 pairs of lines, where each pair lies in a tritangent plane containing one of the lines in T; the involution g interchanges the exceptional lines in each pair. The lines in any non-trivial orbit are incident.

(2) Up to choice of coordinates, g has a lift  $\tilde{g} \in GL(V)$  of the form

(9.2) 
$$\widetilde{g} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} .$$

The element g corresponds to an element of class 2B in  $W(E_6)$ . There is a unique g-invariant exceptional line  $\ell$  which is incident to every other g-invariant exceptional line. The line  $\ell$  is pointwisefixed by g. There are 5 pairs of exceptional lines that, along with the pointwise-fixed exceptional line  $\ell$ , form g-invariant tritangent planes. In 3 of these pairs each line is g-invariant; in the remaining 2 pairs the lines are interchanged by the action of g. The remaining 16 lines are partitioned into skew pairs of lines interchanged by the action of g.

*Proof.* The possible matrix representations follow immediately by writing down all Jordan canonical forms for an element of order 2. In characteristic  $\neq 2$ , there are 4 such forms but they reduce to only 2 distinct forms in PGL(V). The matrices in the statement of the theorem were selected to be independent of characteristic.

Every involution on a cubic surface X must leave invariant some exceptional line since there are an odd number of them. Blowing down one of these lines, we obtain a del Pezzo surface Y of degree 4 with the action of an involution. From Table 3, we conclude that elements of class 2A on X correspond to elements of class  $\overline{1}\overline{1}\overline{1}\overline{1}\overline{1}$  on Y, and elements of class 2B on X

correspond to elements of class  $\overline{11111}$  or 221 on Y. As in Lemma 8.1, these are the only possible classes.

Choosing a g-invariant line  $\ell$ , we may determine the descriptions of the orbits of the 27 lines by identifying  $\ell$  with the exceptional divisor  $E_6$  and then considering the actions of involutions of the first and second kind on the 16 lines of the del Pezzo surface of degree 4 obtained by blowing down  $\ell$ . The action on the remaining 11 lines can be determined from incidence relations.

In this manner, the orbit structure can be verified on a single example. The involution  $\iota_{1234}$  has orbits

$$(9.3) \qquad \{E_6\}, \{F_{56}\}, \{G_5\}, \{G_i, F_{i6}\}, \{E_5, G_6\}, \{E_i, F_{i5}\}, \{F_{ij}, F_{kl}\}$$

for  $\{i, j, k, l\} = \{1, 2, 3, 4\}$ . The invariant lines form a tritangent plane with the desired incidence properties. The involution  $\iota_{12}$  has orbits (9.4)

$$\{E_6\}, \{F_{i6}\}, \{G_i\}, \{G_a, F_{a6}\}, \{E_1, E_2\}, \{G_6, F_{12}\}, \{E_i, F_{jk}\}, \{F_{ai}, F_{bi}\}$$

for  $\{a, b\} = \{1, 2\}$  and  $\{i, j, k\} = \{3, 4, 5\}$ . Here  $E_6$  is the canonical invariant line, the pairs  $F_{i6}, G_i$  give three tritangent planes, while the orbits  $\{G_a, F_{a6}\}$  give the other two. Since  $E_6$  is incident to 6 invariant lines, it must have at least 3 g-fixed points and so must be pointwise-fixed by g.

It remains to connect the matrix representations to the conjugacy classes. Note that (9.1) contains a plane of fixed points, while (9.2) contains at most two lines of fixed points. Suppose g has a fixed plane in  $\mathbb{P}(V)$ . Then every exceptional line on the cubic surface X contains at least one fixed point. Blowing down a g-invariant exceptional line, this implies that the surface Ycannot have an orbit of skew lines and so g is of the class 2A. Conversely, suppose g is of class 2A. The fixed point locus C on Y has dimension 1. If  $p \neq 2$ , then C is a curve of genus 1. The proper transform of C on X cannot be contained in two lines, so the matrix must be (9.1). If p = 2, then the matrix (9.2) only has a single line of fixed points. This line cannot lie on Xsince blowing it down would result in a fixed point locus on Y of dimension 0. But if it does not lie on X then there are at most three fixed points again the fixed point locus on Y has dimension 0. We conclude that the matrix must be (9.1).

9.1. Reflections and the class 2A. Here we consider involutions  $\tilde{g}$  of the form (9.1). These involutions leave pointwise-fixed a proper subspace of maximal dimension, so they are *reflections*. The corresponding projective involution g is classically called a *homology*, but we will use the term *reflection* in the projective case as well. The locus of fixed points of g consists of a hyperplane A and a unique point  $q_0$ , which correspond respectively to the kernel and image of  $\tilde{g}$  – id. The hyperplane A is the *axis* of the reflection; the point  $q_0$ , the *center* of the reflection. If  $p \neq 2$ , then the center never lies on A. If p = 2, then the center always lies on A.
**Theorem 9.2.** The center  $q_0$  of the reflection g is an Eckardt point on X. Conversely, any Eckardt point on X is the center of a reflection leaving Xinvariant. The tritangent plane T corresponding to  $q_0$  contains precisely the g-invariant exceptional lines. The polar quadric  $P_{q_0}(X)$  is supported on the union of the tritangent plane T and the axis A of the reflection; moreover, T and A may coincide only when p = 2.

Proof. Suppose g is a reflection with center  $q_0$ . We will show that any ginvariant line  $\ell_0$  must contain  $q_0$ . A g-invariant line must either be contained in the axis A or contain  $q_0$ . When  $p \neq 2$ , blowing-down a pointwise-fixed line results in an isolated g-fixed point on the corresponding del Pezzo surface of degree 4, contradicting Proposition 3.2; thus  $\ell_0$  is not contained in the axis. Thus, when  $p \neq 2$ , the line  $\ell_0$  must contain  $q_0$ . Now, suppose that p = 2and  $\ell_0$  is contained in the axis A of g. Suppose  $q_0 \notin \ell_0$ . Then any plane  $H \neq A$  containing  $\ell_0$  is not g-invariant. In particular, every tritangent planes containing a given exceptional line; since 5 is odd, at least one of them must be g-invariant — a contradiction. Thus, regardless of the characteristic,  $\ell_0$ contains the center  $q_0$  of g. From Proposition 9.1, there are 3 g-invariant lines and so they must all pass through  $q_0$ , which shows that  $q_0$  is an Eckardt point.

Let us prove the converse. Assume first that  $p \neq 2$ . We may use the same argument as Theorem 9.1.23 from [9]. Let  $q_0$  be the Eckardt point and let  $P_{q_0}(X)$  be the polar quadric at the point  $q_0$ . It is equal to the union of the tangent plane T at  $q_0$  containing three lines in X passing through  $q_0$  and a plane A intersecting X along a cubic curve C. We may choose coordinates such that  $q_0 = (1:0:0:0)$  and  $T = V(x_1)$ . If  $q_0 \in A$  then we may take  $A = V(x_1 + \lambda x_2)$  and find that

(9.5) 
$$x_0 x_1 (x_1 + \lambda x_2) + a(x_1, x_2, x_3) = 0$$

which is singular at  $q_0$ . Thus  $q_0 \notin A$  and we may assume  $A = V(x_0)$ . The equation of X can be written in the form

(9.6) 
$$x_0^2 x_1 + a(x_1, x_2, x_3) = 0.$$

An involution acts as  $(x_0 : x_1 : x_2 : x_3) \mapsto (-x_0 : x_1 : x_2 : x_3)$  leaving X invariant and fixing  $q_0$  as desired.

Assume p = 2. A similar argument works in this case. Suppose  $q_0 = (1 : 0 : 0 : 0)$  is our Eckardt point. The equation for X must have the form

$$x_0^2 L(x_1, x_2, x_3) + x_0 Q(x_1, x_2, x_3) + C(x_1, x_2, x_3) = 0$$

for homogeneous forms L, Q, C. Note that L = 0 defines the tangent plane at  $q_0$ . Since  $q_0$  is an Eckardt point, the polar quadric  $P_{q_0}(X)$  contains the tangent plane at  $q_0$ . Thus Q is a product of L and some linear form which may assume is  $x_1$ . We obtain the normal form

(9.7) 
$$x_0(x_0+x_1)L(x_1,x_2,x_3)+C(x_1,x_2,x_3)=0.$$

which has an action of the involution  $(x_0 : x_1 : x_2 : x_3) \mapsto (x_0 + x_1 : x_1 : x_2 : x_3)$  which has axis  $x_1 = 0$  and center  $q_0$ .

By a linear change of coordinates, there are two different possibilities for L, which correspond to different geometric situations. Either we can reduce to the form

(9.8) 
$$x_0(x_0 + x_1)x_2 + C(x_1, x_2, x_3) = 0$$

where the axis and the tangent plane are distinct; or we have

(9.9) 
$$x_0(x_0 + x_1)x_1 + C(x_1, x_2, x_3) = 0.$$

where the axis and the tangent plane coincide.

**Proposition 9.3.** Suppose g is an involution of type 2A acting on a cubic surface X. If  $p \neq 2$  then X can be defined by

$$(9.10) \qquad (x_0 + x_1)(x_0 x_1 + c_0 x_2^2 + c_1 x_3^2 + c_2 x_2 x_3) + x_2 x_3(x_2 + x_3) = 0 .$$

If p = 2 and none of the exceptional lines passing through the corresponding Eckardt point lie on the axis, then X is defined by

(9.11) 
$$x_0x_1x_2 + (x_0 + x_1)^2x_3 + c_0(x_0 + x_1)x_3^2 + c_1x_2^3 + c_2x_2x_3^2 + x_3^3 = 0$$
.

In either case,  $c_0, c_1, c_2$  are parameters and  $g(x_0 : x_1 : x_2 : x_3) = (x_1 : x_0 : x_2 : x_3)$ .

We will see below that failure of the extra condition for p = 2 is equivalent to the existence of an involution of type 2B — we will find normal forms for the remaining surfaces in Proposition 9.8 below.

*Proof.* Assume  $p \neq 2$ . Replacing g by a conjugate we may assume it acts by negation of  $x_0$ . Then the equation can be written in the form

$$x_0^2 L(x_1, x_2, x_3) + F(x_1, x_2, x_3) = 0,$$

where L, F are a linear and cubic homogeneous forms. We may assume that  $L = x_1$ . The union of the exceptional lines passing through the Eckardt point (1:0:0:0) is given by equation  $x_1 = F(x_1, x_2, x_3) = 0$ . By a change of variables of  $x_2, x_3$ , we may assume that  $F(0, x_2, x_3) = x_2x_3(x_2 + x_3)$ . Thus the equation can be rewritten in the form

$$x_0^2 x_1 + a_1 x_1^3 + x_1^2 (a_2 x_2 + a_3 x_3) + x_1 (a_4 x_2^2 + a_5 x_3^2 + a_6 x_2 x_3) + x_2 x_3 (x_2 + x_3) = 0$$

Via a change of coordinates  $x_2 \mapsto x_2 + \lambda x_1$ ,  $x_3 \mapsto x_3 + \mu x_1$  we may assume  $a_2 = a_3 = 0$ . Note that now X is singular unless  $a_1 \neq 0$ . Thus, by rescaling  $x_0$  and  $x_1$  we may assume  $a_1 = 1$  to obtain

$$x_0^2 x_1 + x_1^3 + x_1(a_4 x_2^2 + a_5 x_3^2 + a_6 x_2 x_3) + x_2 x_3(x_2 + x_3) = 0.$$

Replacing  $x_0, x_1$  with  $\frac{i}{\sqrt[3]{4}}(x_0 - x_1), \frac{1}{\sqrt[3]{4}}(x_0 + x_1)$  we arrive at the asserted normal form.

Assume p = 2. We have seen already that the equation of X can be reduced to one of the forms (9.8) or (9.9). By the given condition, we may assume it is (9.8). Write F in the form

$$F = x_0(x_0 + x_1)x_2 + a_1x_2^3 + x_2^2A(x_1, x_3) + x_2B(x_1, x_3) + C(x_1, x_3).$$

In the tritangent plane  $x_2 = 0$  there are 3 distinct lines; since none of them lie on the axis, the line  $x_1 = 0$  is distinct from all three. These correspond to 4 points in  $\mathbb{P}^1(x_1, x_3)$  which we may assume are given by  $x_1 = 0, x_3 = 0, x_1 + \lambda x_3 = 0, \lambda x_1 + x_3 = 0$  for some non-zero parameter  $\lambda$ . Thus  $C(x_1, x_3) = x_3(x_1 + \lambda x_3)(\lambda x_1 + x_3) = \lambda x_3(x_1^2 + (\lambda + \lambda^{-1})x_1x_3 + x_3^2)$ . After rescaling  $x_3$  we have

$$F = x_0(x_0 + x_1)x_2 + a_1x_2^3 + a_2x_1x_2^2 + a_3x_2^2x_3 + x_2(a_4x_1^2 + a_5x_1x_3 + a_6x_3^2) + x_3(x_1^2 + a_7x_1x_3 + x_3^2).$$

The change of coordinates  $x_3 \mapsto x_3 + \sqrt{a_3}x_2$  sets  $a_3$  to 0 without otherwise changing the form of the equation. The change  $x_0 \mapsto x_0 + a_5x_3$  now kills  $a_5$ . Now,  $x_0 \mapsto x_0 + a_2x_2$  kills  $a_2$ . Finally,  $x_0 \mapsto x_0 + cx_1$  where  $c^2 + c = a_4$ kills  $a_4$ . Replace  $x_0, x_1$  with  $x_0, x_0 + x_1$  to arrive at the asserted normal form.

9.2. Involutions of class 2B. Let  $\ell$  be an exceptional line on a smooth cubic surface X. Every plane containing  $\ell$  intersects X along  $\ell$  and a residual conic. In this way, a pencil of planes containing  $\ell$  defines a pencil of conics on X. Restricting to  $\ell$ , we obtain a linear system  $g_2^1$  on  $\ell$  of divisors of degree 2 or, equivalently, a regular map  $g_2^1 : \ell \to \mathbb{P}^1$ . We call  $\ell$  a separable (resp. *inseparable*) line if  $g_2^1$  is separable (resp. inseparable).

**Lemma 9.4.** Let  $\ell$  be an exceptional line on a smooth cubic surface X. If  $p \neq 2$ , then  $\ell$  contains 0, 1, or 2 Eckardt points. If p = 2, then  $\ell$  contains 0, 1, or 5 Eckardt points. The line  $\ell$  is inseparable if and only if it contains 5 Eckardt points.

*Proof.* The map  $g_2^1 : \ell \to \mathbb{P}^1$  is ramified precisely when the corresponding conic is tangent to  $\ell$ . A tangent conic can either be irreducible, or can be the union of two lines that, together with  $\ell$ , span a tritangent plane with the tangency point an Eckardt point.

When  $p \neq 2$ , the line  $\ell$  is separable and it contains at most 2 Eckardt points. When p = 2, if  $\ell$  is separable, then there is at most one Eckardt point since an involution acting on  $\mathbb{P}^1$  has at most one fixed point. If  $\ell$ is inseparable, then every tritangent plane containing  $\ell$  must contain an Eckardt point on  $\ell$ . There are always 5 such planes.

**Lemma 9.5.** Let X be a smooth cubic surface admitting an automorphism g of class 2B. Let  $\ell$  be the unique exceptional line pointwise-fixed by g. There are 2 Eckardt points on  $\ell$  whose corresponding reflections  $h_1, h_2$  generate a group isomorphic to  $2^2$  containing g. Moreover, if p = 2, then  $\ell$  contains 5 Eckardt points whose corresponding reflections generate a group isomorphic to  $2^4$  containing g; the line  $\ell$  lies in the axis of every one of these reflections.

*Proof.* From Proposition 9.1, there is a canonical pointwise-fixed exceptional line  $\ell$ , which is incident to all other *g*-invariant exceptional lines. Blow down  $\ell$  to a point q on a del Pezzo surface Y of degree 4 where g acts as an involution of the second kind. There, g is a unique product of two commuting involutions  $h_1$  and  $h_2$  of the first kind. Note that  $h_1$  and  $h_2$  both leave  $\ell$  invariant since q is contained in the fixed locus of both. From Proposition 9.1, involutions of class 2A leave invariant only the exceptional divisors passing through their corresponding Eckardt points. Thus, the two Eckardt points lie on  $\ell$ .

Now we consider p = 2. By Proposition 3.2, g has a unique fixed point on Y, namely the canonical point. The canonical point is fixed by all automorphisms of Y, so the entire automorphism group of Y acts on X. In general, this is the group  $2^4$  generated by the 5 involutions of the first kind. As above, they must all leave  $\ell$  invariant so  $\ell$  contains all 5 corresponding Eckardt points. Since the 5 reflections commute, they each fix the 5 Eckardt points. An automorphism cannot fix 5 points on  $\mathbb{P}^1$  unless it acts trivially. We conclude that  $\ell$  is in the axis of each of these reflections.

**Remark 9.6.** If  $p \neq 2$ , the fact that the pointwise-fixed line contains two Eckardt points can be also deduced from the Lefschetz fixed-point formula. Since the trace of an element of type 2B on the second cohomology group is equal to 3, the Euler-Poincaré characteristic of the fixed locus  $X^g$  is equal to 5. Thus  $X^g$  consists of the line and 3 isolated fixed points. There are five ginvariant tritangent trios containing the fixed line. Since the singular points of tritangent trios containing the line are fixed, at most three of the singular points do not lie on the fixed line. Thus there are two tritangent trios whose singular points lie on the line — these are the two Eckardt points.

**Corollary 9.7.** Two reflections  $r_1, r_2$  commute if and only if their corresponding Eckardt points lie on a common exceptional line  $\ell$ ; in this case, the product  $r_1r_2$  has class 2B and its canonical line is  $\ell$ . If  $\ell$  is an exceptional line containing two (or more) Eckardt points, then their corresponding reflections commute.

**Proposition 9.8.** Let X be a 2B surface. If  $p \neq 2$ , X can be defined by the equation

$$(9.12) F = x_0^2(x_2 + c_0 x_3) + x_1^2(c_1 x_2 + x_3) + x_2 x_3(x_2 + x_3) = 0,$$

where  $g(x_0 : x_1 : x_2 : x_3) = (-x_0 : -x_1 : x_2 : x_3)$ . If p = 2, then X can be defined by the equation

 $(9.13) \quad F = x_0^3 + x_1^3 + x_2^3 + x_3^3 + c_0 x_2 x_3 (x_0 + x_1) + c_1 x_0 x_1 (x_2 + x_3) = 0,$ 

where  $g(x_0: x_1: x_2: x_3) = (x_1: x_0: x_3: x_2).$ 

*Proof.* Assume  $p \neq 2$ . By Lemma 9.5, we may in fact assume that X is invariant under the group  $H \cong 2^2$  where  $x_0 \mapsto \pm x_0$  and  $x_1 \mapsto \pm x_1$  while  $x_2, x_3$  remain fixed. The invariant cubic has the form

$$x_0^2 L_1(x_2, x_3) + x_1^2 L_2(x_2, x_3) + C_3(x_2, x_3)$$

where  $L_1, L_2, C$  are homogeneous forms of degree 1, 1, 3 respectively. One checks that  $L_1, L_2, C$  must have distinct roots or else X is singular. Thus, we obtain the desired normal form.

Assume p = 2. By Lemma 9.5, we may assume that X is invariant under the transposition that interchanges  $x_0, x_1$  and also the transposition that interchanges  $x_2, x_3$ ; together these generate a group H isomorphic to  $2^2$ . The invariant ring under H is the polynomial ring  $\Bbbk[\sigma_1, \sigma_2, \tau_1, \tau_2]$  where

$$\sigma_1 := x_0 + x_1, \ \sigma_2 := x_0 x_1, \ \tau_1 := x_2 + x_3, \ \tau_2 := x_2 x_3$$

Thus F has the form

$$c_1\sigma_1\tau_2 + c_2\sigma_2\tau_1 + c_3\sigma_1\sigma_2 + c_4\tau_1\tau_2 + c_5\sigma_1^3 + c_6\sigma_1^2\tau_1 + c_7\sigma_1\tau_1^2 + c_8\tau_2^3$$

where  $c_1, \ldots, c_8$  are parameters.

One finds that the partial derivatives at the point  $q = (\lambda, \lambda, \mu, \mu)$  are

$$\partial_{x_0} F|_q = \partial_{x_1} F|_q = c_1 \mu^2 + c_3 \lambda^2$$
$$\partial_{x_2} F|_q = \partial_{x_3} F|_q = c_2 \lambda^2 + c_4 \mu^2$$

and so the form is singular if  $c_1c_2 = c_3c_4$ .

Consider the linear map m given by the matrix

$$M = I_4 + \begin{pmatrix} a_0 J_2 & a_1 J_2 \\ a_2 J_2 & a_3 J_2 \end{pmatrix}$$

where  $I_n$  is the  $n \times n$  identity matrix,  $J_2$  is the  $2 \times 2$  matrix with all entries equal to 1, and  $a_0, \ldots, a_3$  are constants. Note that M has order 2, and is therefore invertible, for all values of  $a_i$ . We find that

$$m(\sigma_1) = \sigma_1$$
  

$$m(\sigma_2) = \sigma_2 + \wp(a_0)\sigma_1^2 + a_1\sigma_1\tau_1 + a_1^2\tau_1^2$$
  

$$m(\tau_1) = \tau_1$$
  

$$m(\tau_2) = \tau_2 + a_2^2\sigma_1^2 + a_2\sigma_1\tau_1 + \wp(a_3)\tau_1^2$$

where  $\wp(t) := t^2 + t$  is the Artin-Schreier map.

If  $c'_1, \ldots, c'_8$  are the corresponding coefficients of m(F), then we see that  $c'_1 = c_1, \ldots, c'_4 = c_4$  and

 $(9.14) c_5' = c_5 + c_1 a_2^2 + c_3 \wp(a_0)$ 

(9.15) 
$$c_6' = c_6 + c_1 a_2 + c_2 \wp(a_0) + c_3 a_1 + c_4 a_2^2$$

$$(9.16) c'_7 = c_7 + c_1 \wp(a_3) + c_2 a_1 + c_3 a_1^2 + c_4 a_2$$

(9.17)  $c'_8 = c_8 + c_2 a_1^2 + c_4 \wp(a_3)$ .

We claim that we may select  $a_0, \ldots, a_3$  so that  $c'_5 = c_3, c'_6 = c'_7 = 0, c'_8 = c_4$ . In this case, the new form is

$$c_1'\sigma_1\tau_2 + c_2'\sigma_2\tau_1 + c_3'(\sigma_1\sigma_2 + \sigma_1^3) + c_4'(\tau_1\tau_2 + \tau_1^3) ,$$

which can be rescaled to be of the form in the theorem  $(c'_3 \text{ and } c'_4 \text{ are non-zero since } X \text{ is smooth}).$ 

It remains to prove the claim. If  $c_1 = 0$ , then  $c_3, c_4 \neq 0$  or else the form is singular. Since (9.14) is now an equation only involving  $a_0$ , it has a solution. Substituting this solution into (9.15), we see that  $a_1 = \frac{c_4}{c_3}a_2^2 + K$  where K is a constant. Substituting this into (9.16) we obtain a univariate polynomial in  $a_2$  with highest term  $\frac{c_4^2}{c_3}a_2^4$ ; thus  $a_1$  and  $a_2$  have solutions. Finally, (9.17) is now a univariate polynomial in  $a_3$  with highest term  $c_4a_3^2$ ; thus the whole system has a solution.

The case of  $c_2 = 0$  follows by symmetry. Thus, we may assume  $c_1, c_2$  are both non-zero. From (9.15) and (9.16), we obtain expressions for  $\wp(a_0)$  and  $\wp(a_3)$  in terms of  $a_1$  and  $a_2$ . Substituting these into (9.14) and (9.17) we now simply must find solutions for  $a_1, a_2$  for the system

$$(c_3c_4 + c_1c_2)a_2^2 + c_1c_3a_2 + c_3^2a_1 = K_1$$
  
$$(c_3c_4 + c_1c_2)a_1^2 + c_2c_4a_1 + c_4^2a_2 = K_2$$

where  $K_1, K_2$  are constants. There is a solution if  $c_3 = c_4 = 0$ , so we may assume, without loss of generality, that  $c_3 \neq 0$ . Recall  $c_3c_4 + c_1c_2 \neq 0$  or else X is singular. The first equation now provides an expression for  $a_1$  in terms of  $a_2$  which has a quadratic highest term. Substituting this into the second equation, we obtain a quartic in  $a_2$ . Thus the system has a solution.  $\Box$ 

**Remark 9.9.** When  $p \neq 2$ , in the normal form from Proposition 9.8, the exceptional line  $\ell$  is defined by

$$x_2 = x_3 = 0$$

with two Eckardt points (1:0:0:0) and (0:1:0:0). Note that the five tritangent planes containing  $\ell$  are precisely those defined by the linear forms  $x_2$ ,  $x_3$ ,  $x_2 + x_3$ ,  $x_2 + c_0 x_3$  and  $c_1 x_2 + x_3$ .

For p = 2, the exceptional line is defined by  $x_0 + x_1 = x_2 + x_3$  with the two associated Eckardt points (1 : 1 : 0 : 0) and (0 : 0 : 1 : 1); and the canonical point is  $(c_0 : c_1 : c_1)$ .

## 10. Automorphisms of order 3

10.1. **Trihedral Lines.** Recall from section 9.1 of [9] that a *tritangent trio* is a set of three exceptional lines which span a tritangent plane. A pair of tritangent planes intersecting along a line not in the surface is classically known as a *Cremona pair*. A *triad of tritangent trios* is a set of three tritangent trios such that no two share a common exceptional line. Given a pair of tritangent trios with no common exceptional lines, there is a unique third tritangent trio forming a triad with the first two. Every triad of

tritangent trios has a unique conjugate triad which contains the same 9 exceptional lines. We call these a conjugate pair of triads of tritangent trios.

Geometrically, a *trihedron* will be the set of three tritangent planes corresponding to a triad of tritangent trios. Similarly, one defines a *conjugate trihedron* and a *conjugate pair of trihedra* (or simply *trihedral pair*).

The Weyl group  $W(\mathsf{E}_6)$  acts transitively on the set of conjugate pairs of triads. A representative example is the following set of 9 exceptional lines:

(10.1) 
$$\begin{array}{c} F_{14} & F_{25} & F_{36} \\ F_{26} & F_{34} & F_{15} \\ F_{35} & F_{16} & F_{24} \end{array}$$

where each row and column forms a tritangent trio, and the rows form one triad with the columns its conjugate triad.

It is worth emphasizing that all of the aforementioned objects are features of the abstract configuration of 27 lines — their existence is completely independent of a choice of cubic surface. On the other hand, the existence of Eckardt points and trihedral lines depend on the specific cubic surface.

Recall that a *trihedral line*  $\ell$  is a line containing exactly 3 Eckardt points, which is not contained in the cubic surface. Similarly to how Eckardt points correspond to the unusual situation where the three exceptional lines in a tritangent plane have a common point, a trihedral line corresponds to the situation where three tritangent planes in a trihedron contain a common (necessarily non-exceptional) line.

**Lemma 10.1.** Let X be a smooth cubic surface. Consider a trihedral pair  $((T_1, T_2, T_3), (T'_1, T'_2, T'_3))$ , where  $\{T_i\}, \{T'_i\}$  are tritangent trios. The following are equivalent:

- (a)  $T_1 \cap T_2 \cap T_3$  is a line,
- (b)  $T'_1, T'_2, T'_3$  correspond to Eckardt points on a line, and
- (c) two of  $T'_1, T'_2, T'_3$  correspond to Eckardt points.

*Proof.* It suffices to assume the 9 exceptional lines are those from (10.1) where  $T_1, T_2, T_3$  correspond to the columns and  $T'_1, T'_2, T'_3$  correspond to the rows.

Assume (a). If  $T_1 \cap T_2 \cap T_3$  contain a line then  $T_1 \cap T_2 = T_1 \cap T_3$ . Thus  $F_{14} \cap F_{25} = T_1 \cap T_2 \cap T'_1 = T_1 \cap T_3 \cap T'_1 = F_{14} \cap F_{36}$ . This means that  $F_{14} \cap F_{25} \cap F_{36}$  is nonempty and so  $T'_1$  has an Eckardt point contained in  $T_1 \cap T_2 \cap T_3$ . Similar arguments apply to  $T'_2$  and  $T'_3$  so (b) follows.

Clearly, (b) implies (c). So it remains to show (c) implies (a). Suppose  $T'_1, T'_2$  correspond to Eckardt points  $p_1, p_2$ . Then  $p_1 = F_{14} \cap F_{25} \cap F_{36}$  and  $p_2 = F_{26} \cap F_{34} \cap F_{15}$ . Now  $T_1 \cap T_2$  contain both  $p_1$  and  $p_2$  and the same is true of  $T_1 \cap T_3$ . Thus  $T_1 \cap T_2 \cap T_3$  contains both points and thus contains a line.

We also have the following, which generalizes Proposition 9.1.26 of [9] to arbitrary characteristic (with a different proof).

**Corollary 10.2.** Let X be a smooth cubic surface. If X contains two Eckardt points lying on a line  $\ell$  not contained in X then there is a unique third Eckardt point such that  $\ell$  is a trihedral line.

10.2. Orbit structures. Let X be a smooth cubic surface with an automorphism g of order 3. There are three types of orbits for the induced action of g on the 27 lines:

- an invariant line,
- a tritangent trio, or
- a skew triple of lines.

For a g-invariant pair of conjugate triads, the action of g can only permute the rows and columns of the matrix (10.1). Thus, the possible orbit structures on the set of 9 lines in the pair of conjugate triads is as follows:

- 9 invariant lines,
- 3 tritangent trios, or
- 3 skew triples.

**Lemma 10.3.** No automorphism of order 3 fixes an exceptional line pointwise.

Proof. Let  $\ell$  be an exceptional line that is pointwise fixed under the action of an automorphism g of order 3. At most two other exceptional lines can meet  $\ell$  at the same point, so any exceptional line intersecting  $\ell$  non-trivially must also be g-invariant. There are exactly 5 tritangent planes containing  $\ell$ ; selecting a line from each plane, we obtain 5 skew exceptional lines that are each g-invariant. Blowing these down we obtain a del Pezzo surface Yof degree 8 with 5 g-fixed points in general position. If  $Y \cong \mathbb{P}^1 \times \mathbb{P}^1$ , then there is no non-trivial g-action with 5 fixed points in general position (all fixed points must lie on one or two fibers of a projection to  $\mathbb{P}^1$ ). Similarly, if Y is a blow-up of  $\mathbb{P}^2$  then we can blow-down equivariantly to  $\mathbb{P}^2$  with 6 g-fixed points in general position, which is again impossible.  $\Box$ 

We now determine the possible orbit structures for all 27 lines.

**Theorem 10.4.** Let g be an automorphism of a smooth cubic surface of order 3. Let  $\zeta$  be a primitive cube root of unity (if  $p \neq 3$ ).

- (1) The following are equivalent:
  - (a) g is of type 3A,
  - (b) X is a minimal g-surface,
  - (c) the orbit structure on the 27 lines is 9 tritangent trios,
  - (d) up to projective equivalence, the action of g on  $\mathbb{P}^3$  is given by

$$\begin{pmatrix} \zeta & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} if p \neq 3, or \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} if p = 3.$$

(2) The following are equivalent:

- (a) g is of type 3C,
- (b) X is a g-equivariant blowup of 6 points on  $\mathbb{P}^2$  where three points form an orbit and the other three are fixed,
- (c) the orbit structure on the 27 lines is 6 skew triples and 9 invariant lines,
- (d) up to projective equivalence, the action of g on  $\mathbb{P}^3$  is given by

$$\begin{pmatrix} \zeta & 0 & 0 & 0 \\ 0 & \zeta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

This is the Fermat cubic when  $p \neq 3$ ; This case does not occur when p = 3.

- (3) The following are equivalent:
  - (a) g is of type 3D,
  - (b) X is a g-equivariant blowup of 6 points on  $\mathbb{P}^2$  forming two orbits each of size 3,
  - (c) the orbit structure on the 27 lines is 3 tritangent trios and 6 skew triples,
  - (d) up to projective equivalence, the action of g on  $\mathbb{P}^3$  is given by

$$\begin{pmatrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Proof. Recall from [9], 9.1.1 that, after fixing a geometric basis in  $\operatorname{Pic}(X)$  defined by a blowing-down morphism  $X \to \mathbb{P}^2$ , one defines a natural bijection between 36 double-sixers of skew lines on X and positive roots in the lattice  $E_6$ . A sublattice of  $\mathsf{E}_6$  spanned by two positive roots  $\alpha, \beta$  with  $\alpha \cdot \beta = 1$  is isomorphic to the root lattice  $\mathsf{A}_2$ . The 3 pairs of roots in this sublattice correspond to 3 distinct double-sixers whose pairwise intersections each consist of 6 lines: the corresponding collection of 18 lines is called an *azygetic triad*. The remaining 9 lines form a *pair of conjugate triads*. Three pairwise orthogonal root lattices  $\mathsf{A}_2 \perp \mathsf{A}_2 \perp \mathsf{A}_2$  give rise to a triple of azygetic triads called a *Steiner complex*. Each azygetic triad corresponds to the 9 lines in the corresponding pair of conjugate triads; the 27 lines are the union of all three sets of 9 lines.

There are exactly 40 Steiner complexes. Thus any automorphism of order 3 leaves one Steiner complex invariant. Thus, the automorphism preserves a sublattice  $A_2 \perp A_2 \perp A_2$  of  $E_6$ . From Carter's classification, an element of Type 3A (resp. 3C, resp. 3D) is conjugate to the product of cyclic permutations in three copies of  $A_2$  (resp. one copy, resp. two copies). This is reflected in Carter's notation for the conjugacy classes  $3A = 3A_2$ ,  $3C = A_2$ ,  $3D = 2A_2$ . Thus the 27 lines can be partitioned into 3 g-invariant pairs of conjugate triads.

Suppose there exists an invariant set of three skew lines. Then these three lines can be equivariantly blown down. The resulting surface is a del Pezzo surface is of degree 6, which is never minimal for a group of order 3. Thus we can blow down three more lines. We now have six skew lines permuted by g, thus the conjugacy class can be easily computed via  $S_6 \subset W(\mathsf{E}_6)$ . In the case where we have two orbits of order 3 we have 3D; for one orbit of order 3 and three invariant lines we have 3C. This leaves 3A where there are no skew lines; so the cubic surface is g-minimal. We have shown the equivalence of (a) and (b) in each of the three cases.

Note that skew lines correspond to points in general position on  $\mathbb{P}^2$  which are invariant under an automorphism of order 3. In characteristic 3, any three distinct fixed points of an automorphism of order 3 in  $\mathbb{P}^2$  must lie on a line. Thus no cubic surface realizes an automorphism of type 3C when p = 3.

We now describe the orbit structures of each type of automorphism on the 27 lines. Since they are distinct, the orbit structures determine the conjugacy class and vice versa.

The class 3A is minimal, so does not contain any orbits of skew lines. The only possibility is 9 orbits contained in tritangent planes.

It is impossible to have more than 9 invariant lines, since then there would be at least two disjoint invariant pairs of conjugate triads consisting of 9 invariant lines each. These 18 lines would contain a double-sixer of invariant lines, which would force a trivial action of g.

If there exists an orbit that forms a tritangent plane then there can be no invariant lines. Indeed, there are exactly 8 other lines incident to each line in the tritangent plane. These partition the remaining 24 lines so, in order to preserve incidence, they cannot be invariant under g.

The automorphism of type 3D leaves invariant two orbits of three points each in the plane model. Partition these 6 points into 3 pairs, each pair containing exactly one point from each orbit. To each pair, associate the line passing through these two points. The strict transforms of these lines form a g-invariant tritangent trio in X. The 6 points also give rise to two distinct skew triples of lines in X. These orbits cannot lie in an invariant pair of conjugate triads, so the only possibility is that they belong to two different pairs of conjugate triads. Thus 3D has the description given in the statement of the theorem.

We conclude that only 3C has invariant lines. It cannot have more than 9, so it must have exactly 9. It also cannot have any invariant tritangent planes, since they are incompatible with the existence of invariant lines. Thus it must have the description given in the statement of the theorem.

It remains to consider the matrix descriptions of each of the conjugacy classes. One can enumerate all the Jordan canonical forms of  $4 \times 4$  matrices of order 3. Up to projective equivalence, they all occur in the statement of

the theorem except for the matrix

$$\begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

in characteristic 3. From Section 1.12 of [11], we reduce the equation to the form

$$ax_0(x_0^2 - x_1^2) + bx_2(x_2^2 - x_3^2) + (x_0x_3 - x_1x_2)L_1(x_1, x_3) + C_3(x_1, x_3) = 0.$$

Computing the partial derivatives, we find that the point (1, 0, -1, 0) is a singular point. Thus this surface does not occur.

Suppose g fixes pointwise a plane in  $\mathbb{P}^3$ . Thus every exceptional line contains a fixed point. Thus the orbit structure does not contain any skew triples. We must be in the case 3A. Conversely, suppose we are in the case 3A. There are 9 invariant tritangent planes so there are at least 9 fixed points in the dual space of  $\mathbb{P}^3$ . No more than 3 such points can be collinear, since no 4 tritangent planes can share a common non-exceptional common line. Thus, there must be a pointwise-fixed plane in the dual space. Thus we have a fixed plane in the original space. A pointwise fixed plane corresponds to a pseudoreflection, so we have established the equivalence of all items for the case 3A.

Now suppose we are in case 3C. We may assume we are not in characteristic 3 so every invariant exceptional line contains exactly 2 fixed points. There are 9 invariant lines so there must be at least two pointwise-fixed lines in  $\mathbb{P}^3$ . Thus, we must have the given matrix representation. Conversely, if we have the given matrix representation then X must be the Fermat by the following standard argument. The invariant cubics are all of the form

$$C_1(x_0, x_1) + C_2(x_2, x_3) = 0$$

for cubic forms  $C_1, C_2$ . Since the surface must be smooth,  $C_1(x_0, x_1)$  has three distinct roots in  $\mathbb{P}^1 = \mathbb{P}(x_0 : x_1)$  and so can put in the form  $x_0^3 + x_1^3$ . The same is true for  $C_2$  so we have the Fermat cubic. One checks that g has the expected action on the exceptional lines by an explicit computation in coordinates on the Fermat.

The remaining matrix must be for 3D since we have excluded all the other possibilities.  $\hfill \Box$ 

10.3. Automorphisms of type 3A. We say a smooth cubic surface X is *cyclic* if X has a triple cover of  $\mathbb{P}^2$  with cyclic Galois group. There may be more than one triple cover, but this only occurs for the Fermat surface.

**Lemma 10.5.** A smooth cubic surface is cyclic if and only if it admits an automorphism g of class 3A. Moreover, the automorphism g generates the group of deck transformations of a cover.

*Proof.* By Theorem 10.4, an automorphism of class 3A acts as a pseudoreflection on the ambient  $\mathbb{P}^3$ . This gives a description of X as a cyclic surface. Conversely, if X is a cyclic cubic surface with g as its deck transformation then it must have a pointwise fixed curve. Thus 3A is the only possibility.  $\Box$ 

When  $p \neq 3$ , cyclic surfaces have the same normal form as in  $\mathbb{C}$  by the same argument as in, for example, page 486 of [9]. Namely, we may write the cyclic surface in the form  $x_3^3 + C(x_0, x_1, x_2) = 0$  and then put the homogeneous cubic form  $C(x_0, x_1, x_2)$  in Hesse standard form. We obtain the following:

**Proposition 10.6.** Suppose  $p \neq 3$ , X is a cyclic cubic surface, and C is the ramification divisor of the deck transformation g. Then X may be written in the form

$$x_0^3 + x_1^3 + x_2^3 + x_3^3 + cx_0x_1x_2$$

where c is a parameter and g acts via  $x_3 \mapsto \zeta x_3$  where  $\zeta$  is a primitive third root of unity. Here C is a smooth genus 1 curve in the plane defined by  $x_3 = 0$ . The 9 Eckardt points lying on C are

$$(1: -\epsilon: 0: 0), (0: 1: -\epsilon: 0), (1: 0: -\epsilon: 0)$$

where  $\epsilon$  is 1,  $\zeta$  or  $\zeta^2$ . Taking one of these points to be the origin, the points may be identified with the 3-torsion subgroup of the elliptic curve C, which is isomorphic to  $3^2$ .

**Remark 10.7.** Suppose p = 2 and X is a cyclic surface other than the Fermat cubic with g the deck transformation. In the above normal form, the canonical point is (0 : 0 : 0 : 1) and the canonical plane is given by  $x_3 = 0$ . Thus the canonical plane is the axis of the pseudoreflection g and the canonical point is its center.

We defer the normal form for p = 3 as we will use a description of some of its automorphisms for the proof.

Recall that a *tactical configuration* is a finite set of points and a finite set of lines such that every point is contained in the same number of lines and every line contains the same number of points. Recall that the *Hesse configuration*  $(9_4 \ 12_3)$  is the configuration one obtains from the points and lines of the affine plane over the field of three elements. Equivalently, it can be obtained from the set of flexes of a smooth curve of genus one over an algebraically closed field of characteristic not 3. It contains 9 points and 12 lines where each point lies on 4 lines and each line contains 3 points.

**Lemma 10.8.** Let g be an automorphism of type 3A. Then X contains 9 coplanar g-fixed Eckardt points contained in 12 trihedral lines, which form the Hesse configuration. The corresponding reflections generate a group isomorphic to  $H_3(3) \rtimes 2$  with center  $\langle g \rangle$ .

*Proof.* Note we do not assume anything about the characteristic!

Recall that g fixes a plane P pointwisely so every exceptional line must have a g-fixed point on P. If g permutes the exceptional lines in a tritangent trio, then this forces the constituent exceptional lines to share an Eckardt point on P. The orbit structure of the 27 exceptional lines is a union of g-invariant tritangent trios, so there is a set  $\mathcal{E}$  of 9 Eckardt points on P as desired. Since the corresponding tritangent trios partition the exceptional lines, there are no other Eckardt points on P.

Since there are no exceptional lines contained in P, any two points in  $\mathcal{E}$  are contained in a trihedral line with a third. Note that the set  $\mathcal{E}$  can be identified with a subset of the tritangent planes and the trihedral lines correspond to triads; thus, the configuration and its automorphism group are completely determined by abstract considerations using  $W(\mathsf{E}_6)$ . Thus, by establishing the lemma for any one cyclic cubic surface, we prove it for all the others. In particular, it is well known, and easy to check, for cyclic surfaces over  $\mathbb{C}$ .

In view of the previous description we may now establish the following:

**Lemma 10.9.** A smooth cubic surface admits an automorphism of class 3A if and only if it admits an automorphism of class 6A.

*Proof.* The square of an element of class 6A is of class 3A. Conversely, suppose X admits an automorphism of class 3A. The group from Lemma 10.8 also admits an involution of class 2A since there are g-fixed Eckardt points. This involution must commute with the center, which has class 3A. Their product must be of class 6A by Table 4.

This last lemma allows us to find a normal form when p = 3.

**Proposition 10.10.** Suppose p = 3, X is a cyclic cubic surface, and C is the ramification divisor of the deck transformation g. Then X may be written in the form

(10.2) 
$$x_0^3 + x_0 x_3^2 - x_1 x_2^2 + x_1^2 x_3 + c x_1 x_3^2$$

where c is a parameter and g acts via  $x_0 \mapsto x_0 + ix_3$  where i is a primitive 4th root of unity. Here C is a cuspidal cubic curve with cusp at (0:1:0:0). The smooth locus of C has a parametrization

$$\phi : \mathbb{G}_a \to C \text{ via } \phi(t) = (t:t^3:1:0)$$

The solutions  $\mathcal{E}$  of  $\alpha^9 - c\alpha^3 - \alpha = 0$  are a subgroup of  $\mathbb{G}_a$  isomorphic to  $3^2$ . Their images  $\{\phi(\alpha) : \alpha \in \mathcal{E}\}$  are Eckardt points of X.

*Proof.* By Lemma 10.9, there exists an automorphism of class 6A represented by a matrix

$$\begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

where any invariant smooth cubic is:

$$x_0^3 - x_0 x_3^2 + c_0 x_1 x_2^2 + c_1 x_3 x_2^2 + c_2 x_1^3 + c_3 x_1^2 x_3 + c_4 x_1 x_3^2 + c_5 x_3^3 .$$

Note that the change of coordinates  $x_0 \mapsto x_0 - \sqrt[3]{c_2}x_1$  ensures that  $c_2 = 0$ . The fixed point locus of the cyclic cover is given by  $x_3 = 0$  so now the ramification locus is

$$x_0^3 + c_0 x_1 x_2^2$$
.

An automorphism of class 3A has no pointwise-fixed lines, so the ramification locus cannot contain any lines. Thus  $c_0 \neq 0$  and the ramification curve is a cuspidal cubic as desired. Since  $c_0 \neq 0$ , we may apply  $x_1 \mapsto x_1 - \frac{c_1}{c_0}x_3$  to ensure  $c_1 = 0$ . Now applying  $x_0 \mapsto x_0 - rx_3$  where  $r^3 - r = c_5$  ensures that  $c_5 = 0$ . Now  $c_3$  must be non-zero or else (0:1:0:0) is singular. Thus, by rescaling  $x_1, x_2, x_3$  appropriately, we have the desired normal form.

The ramification locus is the intersection of X with the plane  $x_3 = 0$  and is defined by

$$x_0^3 - x_1 x_2^2 = 0 \; .$$

The location of the cusp and the validity of the parametrization  $\phi$  are verified by short computations. The subset  $\mathcal{E}$  forms a subgroup of  $\mathbb{G}_a$  since  $x \mapsto x^3$ and  $x \mapsto x^9$  are additive when p = 3. It remains to show that their images in C are Eckardt points.

For each  $q = \phi(\alpha)$ , one verifies that the tangent space is defined by

(10.3) 
$$x_1 - \alpha^3 x_2 - \alpha^6 x_3$$

Using this, we eliminate  $x_1$  from the expression for X to obtain the following

$$x_0^3 + x_0 x_3^2 - \alpha^3 x_2^3 + (c\alpha^3 - \alpha^9) x_2 x_3^2 + (\alpha^{12} + c\alpha^6) x_3^3 ,$$

which, along with (10.3), defines  $T \cap X$ . One can rearrange this expression as

$$(x_0 - \alpha x_2)^3 + (x_0 - \alpha x_2)x_3^2 + (\alpha^4 - c\alpha^6)x_3^3$$

where we use the relation  $\alpha^9 = c\alpha^3 + \alpha$ . Thus the intersection of the tangent space with X is a union of three exceptional lines each defined by

$$x_0 - \alpha x_2 - \beta x_3 = 0$$

as  $\beta$  varies over the three solutions to  $\beta^3 + \beta + (c\alpha^2 - 1)\alpha^4 = 0$ .

**Remark 10.11.** By a rescaling of the variables, one can instead have a negative sign for the monomial  $x_0x_3^2$  in (10.2). This has the pleasing consequence that the deck transformation is given by  $x_0 \mapsto x_0 + x_3$  instead of requiring the fourth root of unity *i*. In the current form, however, when c = 0 the Eckardt points are in direct bijection to the field  $\mathbb{F}_9$  of 9 elements (note that  $i \in \mathbb{F}_9$ ). Up to projective equivalence, there are only two smooth cubic surfaces defined over  $\mathbb{F}_9$ : this one and the Clebsch (see Theorem 20.3.8 of [15]). In Section 12.3, we will see that this surface has an automorphism group of order 216 — our normal form makes it transparent that all the automorphisms are also defined over  $\mathbb{F}_9$ .

Since we know the Eckardt points, we may now explicitly describe automorphisms for a cubic surface in form (10.2). The following can be checked by a tedious but straightforward calculation.

There is a group of automorphisms isomorphic to  $\mathcal{H}_3(3)$  given by the matrices:

$$\begin{pmatrix} 1 & 0 & \alpha & \beta \\ 0 & 1 & \alpha^3 & -\alpha^6 \\ 0 & 0 & 1 & \alpha^3 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

where  $\alpha, \beta$  are the solutions to

$$\alpha^9 - c\alpha^3 - \alpha = 0$$
  
$$\beta^3 + \beta + (c\alpha^2 - 1)\alpha^4 = 0$$

Note that  $\alpha = 0$  corresponds to the deck transformation subgroup. The reflections given by the Eckardt points on C are given by  $(x_0 : x_1 : x_2 : x_3) \mapsto (x_0 : x_1 : -x_2 : x_3)$  and its conjugates under the group described above.

We record the following easy lemma since its consequences are important later.

**Lemma 10.12.** If h is an automorphism of a cyclic cubic surface which normalizes the Galois group of the cover, then h leaves invariant the ramification curve and the 9 Eckardt points within.

*Proof.* The automorphism h leaves invariant the ramification curve. If h normalizes g then it must preserve the partition of the 27 lines into 9 g-invariant tritangent planes; thus it must leave invariant the set of Eckardt points.

As a converse, we will see that whenever there is an automorphism h of  $(C, \mathcal{E})$ , there is an automorphism h of the corresponding cyclic cubic surface inducing  $\tilde{h}$ .

When  $p \neq 3$ , recall that the automorphisms of a genus 1 curve are generated by translations and group automorphisms (given a choice of origin). The group of translations by 3-torsion points is the image of the group  $\mathcal{H}_3(3)$  above. A general curve only admits group automorphisms of order 2 — these are the reflections corresponding to Eckardt points above. When furthermore  $p \neq 2$ , the anharmonic curve admits a group automorphism of order 4 discussed in Section 12.4; an equianharmonic curve admits a group automorphism of order 3 giving rise to the Fermat cubic surface discussed in the next section. When p = 2, the supersingular elliptic curve carries automorphisms of order both 3 and 4 — this can be seen as another explanation for the fact that a surfaces admitting an automorphism of class 12A is always the Fermat surface if p = 2.

When p = 3, we are interested in automorphisms of the affine line that preserve the subset defined by  $\alpha^9 - c\alpha^3 - \alpha = 0$ . Translation by elements in the subset correspond to the image of  $\mathcal{H}_3(3)$  as before. Up to translation, the remaining automorphisms are of the form  $\alpha \mapsto \lambda \alpha$  for  $\lambda \in k^{\times}$ . Substituting into the defining equation for  $\alpha$  we find that, when  $c \neq 0$ , we must have  $\lambda^6 = \lambda^8 = 1$ . Thus  $\lambda^2 = 1$  and we only have automorphisms given by reflections corresponding to Eckardt points. However, when c = 0, we only require  $\lambda^8 = 1$ . Thus we have an automorphism of order 8 — the corresponding surface is discussed in Section 12.3.

**Remark 10.13.** When  $p \neq 2$ , a smooth cubic surface is cyclic if and only if its Hessian surface contains a hyperplane. The Hessian surface of the Fermat cubic is simply the union of four planes since it has 4 cyclic structures.

When p = 3, the Hessian surface of a cyclic cubic surface is a doubled plane union a cone over a conic in  $\mathbb{P}^2$ . In the coordinates of the normal form (10.2), the Hessian is  $(x_1x_3 + x_2^2)x_3^2$ . The doubled plane is defined by  $x_3 = 0$ , the intersection of the components is defined by  $x_3 = x_2 = 0$ , and the vertex of the cone by  $x_3 = x_2 = x_1 = 0$ . Thus there is a canonical flag associated to any cyclic cubic surface, which is compatible with our choice of normal form.

10.4. Automorphisms of type 3C. This case is the Fermat cubic has already been extensively discussed in Section 5. We only prove the following, for later use:

**Lemma 10.14.** A cubic surface is the Fermat cubic surface if and only if it admits an automorphism of class 3C, 6C, 6F, or 9A. The Fermat cubic surface does not exist when p = 3, so in this case none of these automorphisms occur.

*Proof.* We've seen above that admitting an automorphism of class 3C is equivalent to being the Fermat cubic surface. By considering the model over  $\mathbb{C}$ , we see that there are automorphisms of class 6C, 6F, and 9A. The class 6C and 6F have squares of class 3C so these certainly correspond to the Fermat cubic.

It remains to show an automorphism g of class 9A only acts on the Fermat. Indeed, since the cube of g is of class 3A, it must be a cyclic surface. In view of Lemma 10.12, there is an induced action of order 3 on the ramification curve and the subgroup G generated by the reflections corresponding to the 9 coplanar Eckardt points. One can use the complex Fermat surface as a model to determine the abstract action of g on these 9 points: the automorphism g acts via

$$(x_0: x_1: x_2: x_3) \mapsto (x_1: x_2: \zeta_3 x_0: x_3)$$

on the Fermat, so g does not act on G as a translation.

When p = 3, since g does not act as translation, and the remaining possibilities have order dividing 8, the surface does not exist. If  $p \neq 3$ , then C is an elliptic curve and we have an automorphism of order 3 which is not translation; thus C is equianharmonic. Since such a curve is unique, we conclude that X is the Fermat cubic.

### 10.5. Automorphisms of type 3D.

**Lemma 10.15.** Let g be an automorphism of type 3D. Then X contains a g-invariant trihedral line  $\ell$  such that the reflections corresponding to the Eckardt points on  $\ell$  generate a group isomorphic to  $\mathfrak{S}_3$  that contains g.

*Proof.* There exist six skew lines  $E_1, \ldots, E_6$  in X such that g acts on them as the permutation (123)(456). The conjugate pair of triads given by (10.1) is invariant under this action.

Up to a choice of coordinates, we may blow down  $E_1, \ldots, E_6$  to the points (1:0:0), (0:1:0), (0:0:1), (a:b:c), (c:a:b), (b:c:a). Here g acts by permuting the standard coordinate vectors. There is another conjugacy class of automorphisms of order 3 acting on  $\mathbb{P}^2$ , but each of its orbits are contained in a line, so the 6 points would not be of general position.

Let  $T_1, T_2, T_3$  be the tritangent trios corresponding to the columns of (10.1), and  $T'_1, T'_2, T'_3$  be the conjugate triad corresponding to the rows. Recall that the lines  $F_{ij}$  correspond to lines between the points in the plane model corresponding to  $E_i$  and  $E_j$ . A calculation shows that  $F_{14}, F_{26}, F_{35}$  all contain the point corresponding to (bc: ab: ac) in the plane model. Thus,  $T_1$  corresponds to an Eckardt point. Similarly, there are two other Eckardt points corresponding to the other two columns of (10.1). They lie on a trihedral line  $\ell$  since the corresponding tritangent planes  $T_1, T_2, T_3$  form a trihedron.

Let  $r_i$  be the reflection corresponding to the Eckardt point corresponding to  $T_i$ . Recall that the action of  $r_i$  leaves invariant only the exceptional lines in the corresponding tritangent plane  $T_i$ , while all other exceptional lines are taken to the other exceptional line in the unique tritangent plane containing a line from  $T_i$ . Note that rows of (10.1) are tritangent trios precisely of this form. Thus  $r_i$  acts by interchanging the other two columns of (10.1).

Note that any particular line  $E_i$  is incident to exactly 3 lines in (10.1) — exactly one in each row and column. Thus, we may determine the action of  $r_i$  on all 27 lines from its action on the 9 lines of the trihedral pair. We conclude that  $\langle r_1, r_2, r_3 \rangle \simeq \mathfrak{S}_3$ . Setting  $h = r_2 r_1$ , we find  $h(T_i) = T_{i+1}$  and  $h(T'_i) = T'_i$ , where *i* is interpreted mod 3. From this we conclude that  $h(E_i) = E_{\sigma(i)}$  where  $\sigma = (123)(456)$ . Thus  $g = h \in \langle r_1, r_2, r_3 \rangle$ .

**Lemma 10.16.** Let X be a cubic surface admitting an automorphism g of type 3D. If  $p \neq 3$  and X does not also admit an automorphism of type 6E, then it can be defined by the equation

(10.4) 
$$x_0^3 + x_1^3 + x_2^3 + x_3^3 + c_0 x_0 x_1 x_2 + c_1 (x_0 + x_1 + x_2) x_3^2 = 0$$
.

If p = 3, then X can be defined by the equation (10.5)  $(c_0(x_0+x_1+x_2)+c_1x_3)(x_0x_1+x_0x_2+x_1x_2)+x_0x_1x_2+(x_0+x_1+x_2)x_3^2=0$ . In both cases  $g(x_0:x_1:x_2:x_3) = (x_1:x_2:x_0:x_3)$ . *Proof.* In the case  $p \neq 3$ , we may choose a normal form as in [9] equation (9.66).<sup>1</sup> We would prefer a normal form which highlights the  $\mathfrak{S}_3$ -symmetry. Suppose g acts via  $g(t_0: t_1: t_2: t_3) = (t_0: \zeta t_1: \zeta^2 t_2: t_3)$ . By enumerating all homogeneous monomials of degree 3 invariant under this action we obtain the following normal form

$$C(t_0, t_3) + L(t_0, t_3)t_1t_2 + t_1^3 + t_2^3 = 0$$

for a smooth cubic surface where C and L are homogeneous forms. One checks that C must have distinct solutions in  $\mathbb{P}^1$  or else the surface is singular. If L = 0 then X is the Fermat surface and has automorphisms of type 6E; thus we may assume  $L \neq 0$ . If C and L share a common zero then there exists an automorphism of  $\mathbb{P}^1$  which leaves the common zero fixed and interchanges the remaining solutions of C; this extends to an automorphism of X of type 2A which commutes with g. Thus, we may assume C and Lhave no common solutions or else there exists an automorphism of type 6E.

Without loss of generality, we may assume  $L = t_0$  and  $C(t_0, t_3)$  has the monomials  $t_0^3$  and  $t_3^3$  in its support. We now show that we may in addition assume  $t_0^2 t_3$  has coefficient zero in C. Let p(t) = C(t, 1) be the dehomogenization of C and suppose  $r_1, r_2, r_3$  are its roots (non-zero by our assumption on the common zeroes of L and C). We want to produce a fractional linear transformation f(t) such that p(f(t)) is still cubic, has no  $t^2$  term, and such that f(0) = 0. Consider the fractional linear transformation

$$f:t\mapsto \frac{t}{at+1}$$

for a parameter a. We want to solve for the parameter a such that

(10.6)  
$$0 = f(r_1) + f(r_2) + f(r_3)$$
$$= \frac{(r_1 + r_2 + r_3) + 2a(r_1r_2 + r_1r_3 + r_2r_3) + 3a^2r_1r_2r_3}{(ar_1 + 1)(ar_2 + 1)(ar_3 + 1)}$$

If  $p \neq 2$ , we may assume  $r_1 = 1, r_2 = -1$  and this becomes

$$r_3 - 2a - 3a^2 r_3 = 0 \; ,$$

which has a solution such that the denominator of (10.6) is then non-zero whenever  $r_3 \neq 1, -1, 0$ . If p = 2, the equation (10.6) becomes

$$(r_1 + r_2 + r_3) + a^2 r_1 r_2 r_3 = 0$$

which has a solution since  $r_1, r_2, r_3$  are non-zero; the denominators of (10.6) are non-zero whenever  $r_1, r_2, r_3$  are distinct and non-zero.

Thus, our normal form is

$$t_0^3 + t_1^3 + t_2^3 + c_0 t_0 t_1 t_2 + c_1 t_0 t_3^2 + t_3^3 = 0$$

<sup>&</sup>lt;sup>1</sup>Note that the coefficient at  $t_0t_2t_3$  in the equation cannot be made equal to 1.

for parameters  $c_0, c_1$ . We now make the change of coordinates

$$t_0 \mapsto x_0 + x_1 + x_2$$
  
$$t_1 \mapsto x_0 + \zeta^2 x_1 + \zeta x_2$$
  
$$t_2 \mapsto x_0 + \zeta x_1 + \zeta^2 x_2$$
  
$$t_3 \mapsto x_3$$

to arrive at the equation

$$(3+c_0)(x_0^3+x_1^3+x_2^3)+(18-3c_0)x_0x_1x_2+c_1(x_0+x_1+x_2)x_3^2+x_3^3.$$

The surface is singular if  $c_0 = -3$ , so we may rescale the variables to obtain the desired normal form.

Now assume p = 3. By Lemma 10.15, we may assume that the equation is invariant with respect to permutation of the first three coordinates. We can write  $F \in \mathbb{k}[x_3][x_0, x_1, x_2]^{\mathfrak{S}_3}$  in the form

(10.7) 
$$F = a\sigma_1^3 + b\sigma_1\sigma_2 + c\sigma_3 + d\sigma_1^2x_3 + e\sigma_2x_3 + f\sigma_1x_3^2 + gx_3^3,$$

where  $\sigma_1, \sigma_2, \sigma_3$  are the elementary symmetric polynomials in  $x_0, x_1, x_2$ . The point (1:1:1:0) is singular unless  $c \neq 0$ , so we may assume without loss of generality that c = 1.

We use a linear transformation  $\tau$ , which commutes with  $\mathfrak{S}_3$ , defined by the matrix

(10.8) 
$$M = \begin{pmatrix} 1+a_2 & a_2 & a_2 & a_4 \\ a_2 & 1+a_2 & a_2 & a_4 \\ a_2 & a_2 & 1+a_2 & a_4 \\ a_5 & a_5 & a_5 & 1 \end{pmatrix},$$

which has determinant 1. Note that neither  $\tau(\sigma_1)$  nor  $\tau(\sigma_2)$  contain pure powers of  $x_3^2$ , so the coefficient of  $x_3^3$  in F is  $a_4^3 + g$ . Taking  $a_4 = \sqrt[3]{-g}$ , we may thus assume that g = 0. Now,  $f \neq 0$  or else X is singular, so we may assume f = 1.

Setting  $a_4 = 0$ , the transformation  $\tau$  induces the following action:

$$\sigma_1 \mapsto \sigma_1$$
  

$$\sigma_2 \mapsto \sigma_2 - a_2 \sigma_1^2$$
  

$$\sigma_3 \mapsto \sigma_3 + a_2^2 (a_2 + 1) \sigma_1^3 + a_2 \sigma_1 \sigma_2$$
  

$$x_3 \mapsto a_5 \sigma_1 + x_3 .$$

Assuming  $a_4 = 0$  we obtain a coefficient of  $-ea_2 - a_5 + d$  for  $\sigma_1^2 x_3$  in  $\tau(F)$ . Thus we may assume d = 0 in F. Applying  $\tau$  again with  $a_4 = 0$  and  $a_5 = -ea_2$ , the coefficient of  $\sigma_1^2 x_3$  remains 0 and the coefficient of  $\sigma_1^3$  becomes

$$a_2^3 + (1 - e^2)a_2^2 - ba_2 + a,$$

and so one can choose  $a_2$  to eliminate the coefficient of  $\sigma_1^3$  also. We are left with the expression

$$F = b\sigma_1\sigma_2 + \sigma_3 + e\sigma_2x_3 + \sigma_1x_3^2 ,$$

which is the desired normal form.

# 11. Automorphisms of order 4

Let X be a smooth cubic surface and g be an automorphism of order 4.

**Lemma 11.1.** One of the following holds:

(1) Up to choice of coordinates, g has a lift  $\tilde{g} \in GL(V)$  of the form

(11.1) 
$$\widetilde{g} = \begin{pmatrix} i & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \text{ if } p \neq 2, \text{ or } \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \text{ if } p = 2.$$

Here *i* denotes a primitive 4th root of unity. The element *g* corresponds to an element of class 4A in  $W(E_6)$ .

(2) Up to choice of coordinates, g has a lift  $\tilde{g} \in GL(V)$  of the form

(11.2) 
$$\widetilde{g} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

The element g corresponds to an element of class 4B in  $W(E_6)$ .

Proof. From Lemma 8.1, only classes 4A and 4B may occur, so we only need to determine the corresponding classes of matrices of order 4 which leave invariant a smooth cubic. If  $p \neq 2$  then one can diagonalize the matrix. The analysis of the possibilities is then the same as the case over  $\mathbb{C}$  given in §9.5.1 of [9]. The class 4A can be distinguished from 4B by the eigenvalues of  $\tilde{g}^2$ . If p = 2, then there are only two matrices of order 4 up to conjugacy:  $J_4(1)$  and  $J_3(1) \oplus J_1(1)$  where  $J_k(\lambda)$  is a  $k \times k$  Jordan block with eigenvalue  $\lambda$ . A matrix  $J_4(1)$  has square  $J_2(1) \oplus J_2(1)$  and thus corresponds to 4B. A matrix  $J_3(1) \oplus J_1(1)$  has square  $J_2(1) \oplus J_1(1)^{\oplus 2}$  and thus corresponds to 4A.

11.1. Class 4A.

**Lemma 11.2.** Let X be a smooth cubic surface with an automorphism g of class 4A. There are exactly three invariant exceptional lines  $\ell_0, \ell_1, \ell_2$ , which form a tritangent plane. The remaining 24 lines are partitioned into 6 orbits of 4 lines each. Each orbit consists of two pairs of incident lines, each of which form tritangent planes with one of  $\ell_0, \ell_1, \ell_2$ .

*Proof.* From Table 3, we see that X is obtained by blowing up a point on a del Pezzo surface Y of degree 4 where g acts on Y with class  $\overline{221}$ . Let  $E_1, \ldots, E_5$  correspond to a skew set of exceptional lines on Y and let  $E_6$ be the line corresponding to the blown up point. We may assume g acts as  $\iota_{13}(12)(34)$  on Y. Note that  $g^2$  is the involution  $\iota_{1234}$  and we know its orbit structure from (9.3). We check that the each line in the tritangent trio  $E_6, F_{56}, G_5$  is g-invariant. One checks that  $\iota_{13}(12)(34)$  acts freely on the 16 lines on Y using, for example, the  $\mathbb{F}_2^5$  model discussed in Section 3. One checks that  $g(G_1) = G_2$  and  $g(G_3) = G_4$  by exploiting incidence relations with the lines on Y. These are in different  $g^2$  orbits, so g acts transitively

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on the 24 non-invariant lines. Since  $g^2$ -orbits are pairs of incident lines as stated in the theorem, we have proved the result.

**Lemma 11.3.** Suppose p = 2, X is a smooth cubic surface, and g is an automorphism of class 4A. An invariant exceptional line on X is blown down to the canonical point of a del Pezzo surface Y of degree 4.

*Proof.* From Table 3, the involution  $g^2$  acts as an involution of first kind on Y. Blowing down to a quartic del Pezzo surface Y, we have a point pon the fixed locus F of  $g^2$ , which is an involution of the first kind. The existence of g, an element of class  $\overline{221}$ , implies that Y is also invariant under an involution of class 221. Thus, by Proposition 3.2, the locus F is a pair of rational curves tangent at the canonical point. Note that F is the intersection of Y with a hyperplane. This is still true after projecting away from p in  $\mathbb{P}^4$  to recover X in  $\mathbb{P}^3$ . The preimage of F under the blowup is thus a tritangent plane. Since the original curves were tangent, it has an Eckardt point. Since the three exceptional curves are all g-invariant, the original point p must have been a common point of the components of F this is the canonical point.

We will see in Lemma 12.9 below that in characteristic 2, the surfaces admitting an automorphism of class 4A coincide with those admitting automorphisms of class 4B and 6E. So, in the next Lemma we state the result only in the case  $p \neq 2$  deferring the case p = 2 until the next section.

**Lemma 11.4.** Suppose  $p \neq 2$  and X is a smooth cubic surface with an automorphism g of class 4A. Then we have the normal form

(11.3) 
$$x_3^2 x_2 + x_2^2 x_0 + x_1 (x_1 - x_0) (x_1 - cx_0) = 0$$

where  $g: (x_0: x_1: x_2: x_3) \mapsto (x_0: x_1: -x_2: ix_3)$ . The stratum of such surfaces is 1-dimensional and is isomorphic to the moduli space of elliptic curves.

*Proof.* If  $p \neq 2, 3$ , a normal form for can be also be found in (9.67) of [9]. A general *g*-invariant cubic has the form

$$a_1x_2x_3^2 + (a_2x_0 + a_3x_1)x_2^2 + C(x_0, x_1)$$

for parameters  $a_1, a_2, a_3$  and a homogeneous binary form C of degree 3. After a linear change of coordinates and scaling variables we may assume the cubic is of the form

$$x_2x_3^2 + x_0x_2^2 + C(x_0, x_1)$$

where, since the surfaces is smooth, C must have distinct roots and  $x_0$  cannot divide C. Setting  $x_3 = 0$ , we simply have an elliptic curve, which we may put into Legendre form. This produces the desired normal form for the cubic surface.

## 11.2. Class 4B.

**Lemma 11.5.** If X admits an automorphism g of class 4B, then there is a canonical g-invariant tritangent plane T.

In characteristic  $\neq 2$ , there are six Eckardt points on T, with two on each exceptional line of T, whose corresponding reflections generate a group G isomorphic to  $\mathfrak{S}_4$  containing g. The group G has a normal subgroup N isomorphic to  $2^2$  generated by elements of the form 2B which leave the exceptional lines in T invariant. The quotient group  $G/N \cong \mathfrak{S}_3$  acts by permuting the lines of T.

In characteristic 2, the three exceptional lines on T meet at a canonical Eckardt point. There are 4 other Eckardt points on each line of T giving 13 in total. Their corresponding reflections generate a group of order 192 isomorphic to  $2^3 \rtimes \mathfrak{S}_4$ , which contains g.

*Proof.* Recall that  $g^2$  is an involution of type 2B. Thus there is a canonical exceptional line  $\ell$  containing two Eckardt points  $p_1, p_2$  whose corresponding reflections  $r_1, r_2$  have product  $r_1r_2 = g^2$ . The action on the 27 lines is the same regardless of the cubic surface so it suffices to consider the situation of the Fermat cubic:

$$x_1^3 + x_2^3 + x_3^3 + x_4^3 = 0$$
.

We may assume g is the permutation (1234). Thus  $g^2$  is (13)(24) and the reflections are (13) and (24). The line  $\ell$  is defined by  $x_1 + x_3 = x_2 + x_4 = 0$  in the Fermat model. The reflections generate the group  $\mathfrak{S}_4$ . The reflections are the 6 transpositions, so we obtain 6 Eckardt points. The other two involutions (12)(34) and (14)(23) have canonical exceptional lines  $\ell'$  and  $\ell''$ . The lines  $\ell, \ell', \ell''$  form a tritangent plane T, which is canonical by construction. We see that  $N = \langle (12)(34), (14)(23) \rangle \simeq 2^2$  acts trivially on the set of three lines.

If the characteristic is 2, then  $\ell$  must contain 5 Eckardt points. By symmetry, so must  $\ell'$  and  $\ell''$ . Since all possible Eckardt points are realized, one of them must be the intersection  $\ell \cap \ell' \cap \ell''$ . Blowing down  $\ell$ , we obtain a quartic del Pezzo surface of degree 4 whose automorphism group contains  $2^4 \times 2^2$  of order 64.

The reflection corresponding to the canonical point commutes with all other reflections so it generates a central subgroup of G of order 2. Let H be the quotient of G by this group of order 2. Let  $r_1, \ldots, r_4$  denote the images in H of the reflections corresponding to the remaining Eckardt points on  $\ell$ . Label those from  $\ell'$  by  $s_1, \ldots, s_4$ ; and from  $\ell''$ , by  $t_1, \ldots, t_4$ . Note  $r_1r_2r_3r_4 = 1$  and  $r_ir_j = r_jr_i$  for all i, j; the same is true for the  $s_i$  and  $t_i$ .

Since all the points are coplanar, a line passing through Eckardt points on  $\ell$  and  $\ell'$  passes through a unique third point on  $\ell''$ . This line is a trihedral line and the corresponding reflections generate a group isomorphic to  $\mathfrak{S}_3$ . If the corresponding reflections are  $r_i, s_j, t_k$ , then  $r_i s_j = t_k r_i = s_j t_k$ .

We may keep track of the 16 trihedral lines via four permutations  $\rho_1, \ldots, \rho_4$ of  $\{1, 2, 3, 4\}$  defined such that  $\{r_i, s_j, t_{\rho_i(j)}\}$  describe all possible trihedral lines as i, j vary over  $\{1, 2, 3, 4\}$ . We may label the reflections such that  $\rho_1$ is the identity. Since  $r_1, \ldots, r_4$  commute, the computation

$$s_{\rho_i(j)}r_1r_i = r_1t_{\rho_i(j)}r_i = r_1r_is_j = r_ir_1s_j = r_it_jr_1 = s_{\rho_i^{-1}(j)}r_ir_1$$

shows that the remaining  $\rho_i$ 's are involutions. A similar computation with  $r_i r_j s_k = r_j r_i s_k$  show that the  $\rho_i$ 's commute with one another.

Consider the subgroup K of H generated by  $R = r_1 r_2$  and  $S = s_1 s_{\rho_2(1)}$ . Note that  $S = s_i s_{\rho_2(i)}$  for all *i*. One computes the product

$$RS = r_1 r_2 s_1 s_{\rho_2(1)} = r_2 r_1 s_{\rho_2(1)} s_1 = r_2 t_{\rho_2(1)} r_1 s_1 = t_{\rho_2(1)} s_1 s_1 t_1 = t_1 t_{\rho_2(1)} =: T$$

and checks that  $K \cong 2^2$ . By checking  $s_i R s_i = RS = T$  and similar conditions, we see that K is normal in H. One could have also defined R as  $r_1r_3$  or  $r_1r_4$ , to obtain different but isomorphic normal subgroups. Thus K is normal, but not characteristic in H. (Note that  $R = r_1r_2 = r_3r_4$ , though, so there are essentially only the three such normal subgroups.)

In the group H/K, we have  $r_1 \equiv r_2$  and  $r_3 \equiv r_4$ ; similar equations are true for the  $s_i$ 's and  $t_i$ 's. Thus the 6 reflections generating  $\mathfrak{S}_4$  above generate H/K. We obtain the semidirect product description described above for the original group G.

**Remark 11.6.** From Theorem 20.3.4 of [15], up to projective equivalence, there is a unique smooth cubic surface over the field  $\mathbb{F}$  of 8 elements; its automorphism group is precisely the group of order 192 described in Lemma 11.5. Of course, over the algebraic closure, this is simply the Fermat cubic surface and the geometric automorphism group is larger.

We will see in Lemma 12.9 below that in characteristic 2, the surfaces admitting an automorphism of class 4A coincide with those admitting automorphisms of class 4B and 6E.

**Proposition 11.7.** Let X be a 4B surface. Then X is isomorphic to a surface given by equation

$$x_0^3 + x_1^3 + x_2^3 + x_3^3 + c(x_0x_1x_2 + x_0x_1x_3 + x_0x_2x_3 + x_1x_2x_3) = 0.$$

*Proof.* We know that  $\operatorname{Aut}(X)$  contains  $\mathfrak{S}_4$  that acts by permuting the variables. The equation must be of the form

$$a_1\sigma_1^3 + a_2\sigma_1\sigma_2 + a_3\sigma_3 = 0,$$

where  $\sigma_i$  are elementary symmetric polynomials in the coordinates.

A change of variables that commutes with the permutations of the coordinates is given by a matrix

$$M := \begin{pmatrix} 1+\beta & \beta & \beta & \beta \\ \beta & 1+\beta & \beta & \beta \\ \beta & \beta & 1+\beta & \beta \\ \beta & \beta & \beta & 1+\beta \end{pmatrix}$$

with determinant  $D := (1 + 4\beta)$ . It acts via

$$\sigma_1 \mapsto (1+4\beta)\sigma_1$$
  

$$\sigma_2 \mapsto \sigma_2 + (6\beta^2 + 3\beta)\sigma_1^2$$
  

$$\sigma_3 \mapsto \sigma_3 + (4\beta^3 + 3\beta^2)\sigma_1^3 + 2\beta\sigma_1\sigma_2$$

which transforms the equation to the form

(11.4) 
$$a_1'\sigma_1^3 + a_2'\sigma_1\sigma_2 + a_3'\sigma_3 = 0,$$

where

$$\begin{aligned} a_1' &= (1+4\beta)^3 a_1 + (6\beta^2 + 3\beta)(1+4\beta)a_2 + (4\beta^3 + 3\beta^2)a_3 \\ a_2' &= (1+4\beta)a_2 + 2\beta a_3 \\ a_3' &= a_3 \end{aligned}$$

Note that the coefficient of any monomial  $x_i^2 x_j$  with  $i \neq j$  is equal to  $a'_2 + 3a'_1$ . Let  $p_3 := x_1^3 + x_2^3 + x_3^3 + x_4^3$ , which, by Newton's identities, is  $\sigma_1^3 - 3\sigma_1\sigma_2 + 3\sigma_3$ . If  $a'_2 = -3a'_1$ , then the transformed cubic (11.4) can be written as

$$a_1'p_3 + (a_3' - 3a_1')\sigma_3$$
.

After noting that  $a'_1 \neq 0$  or else X is singular, we see that we have precisely the desired normal form.

It remains to show that we can find a transformation so that  $a_2' + 3a_1' = 0$ . Note that  $a_2' + 3a_1' = f(\beta)$  where

(11.5) 
$$f(\beta) := 12(16a_1 + 6a_2 + a_3)\beta^3 + 9(16a_1 + 6a_2 + a_3)\beta^2 + (36a_1 + 13a_2 + 2a_3)\beta + (3a_1 + a_2).$$

We claim that there is a choice of  $\beta$  such that  $f(\beta) = 0$  and  $D = (1+4\beta) \neq 0$ . Note that  $D \neq 0$  when p = 2. When  $p \neq 2$ , we compute that  $f(-\frac{1}{4}) = -\frac{1}{8}a_3$ ; if  $a_3 = 0$  then the cubic surface is reducible, so  $D \neq 0$  whenever  $f(\beta) = 0$ . When p = 2, we see that  $f(\beta) = a_3\beta^2 + a_2\beta + (a_1 + a_2)$  and conclude that  $f(\beta)$  always has a root since  $a_3 \neq 0$ . If p = 3, then  $f(\beta) = (a_2 - a_3)\beta + a_2$ ; this always has a root since  $a_2 = a_3$  implies that (1 : -1 : -1 : 1) is a singular point. If  $p \neq 2, 3$ , then  $f(\beta)$  has no roots only if all the coefficients of powers of  $\beta$  are zero. This occurs only when  $a_3 = 8a_1$  and  $a_2 = -4a_1$ . In this case, the cubic is singular at (1 : 1 : 1 : 1).

Since we can always find a root for  $f(\beta)$  with  $D \neq 0$ , we have the desired transformation.

**Remark 11.8.** From the normal form in p = 2, we see immediately that a 4B surface X is either the Fermat cubic, or has a canonical point that coincides with the canonical Eckardt point in the canonical tritangent plane. The tritangent plane here is the plane  $x_0+x_1+x_2+x_3=0$  and the canonical point is (1:1:1:1).

#### 12. Automorphisms of higher order

12.1. Class 5A. Recall that the *Clebsch cubic surface* is a surface admitting a group of automorphisms isomorphic to  $\mathfrak{S}_5$ . A normal form for such a surface is defined by

(12.1) 
$$\sum_{i} x_i = \sum_{i < j < k} x_i x_j x_k = 0$$

in  $\mathbb{P}^4 = \mathbb{P}(x_0 : \ldots : x_4)$ . Due to the Newton identities, in characteristic  $\neq 3$  the Clebsch surface can be defined by the more familiar equations

$$\sum_{i=0}^{4} x_i = \sum_{i=0}^{4} x_i^3 = 0 \; .$$

There is an obvious action of  $\mathfrak{S}_5$  by permuting the coordinates. In characteristic 5, there is a singular point (1:1:1:1:1). But in all other characteristics it is smooth.

**Lemma 12.1.** When p = 5, there is no smooth cubic surface admitting an automorphism of order 5.

*Proof.* The class 5A is the unique conjugacy class order 5 in  $W(\mathsf{E}_6)$ . Since X has 36 double-sixers, one of them is invariant. An automorphism of order 5 cannot switch the two sixers of skew lines. Thus, blowing down a sixer, we realize g as a projective automorphism of 6 points, which must fix one of the points.

There are two possible Jordan canonical forms for a  $3 \times 3$  matrix of order 5:

$$M_1 = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \text{ and } M_2 = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

Let  $x_1, x_2, x_3$  generate the dual basis and view them as elements of the homogeneous coordinate ring of  $\mathbb{P}^2$ . From Proposition 7.6.1 of [11], the possible invariant conics in each case are

$$c_0 x_2^2 + c_1 x_2 x_3 + c_2 x_3^3$$

for the matrix  $M_1$  and

$$c_0(x_1x_3 + 2x_2^2 + 3x_2x_3) + c_1x_3^2$$

for the matrix  $M_2$  where  $c_0, c_1, c_2$  are parameters.

In the first case, the conics are never smooth. In the second case, the unique fixed point (1:0:0) lies on any invariant conic. Thus, it is impossible to find 5 invariant points lying on a smooth conic such that there is a fixed point not lying on the conic. This is a contradiction.

We now have the following:

**Theorem 12.2.** If X is a smooth cubic surface with an automorphism of order 5 then X is isomorphic to the Clebsch cubic surface. In characteristic 5, there is no such surface.

Proof. The class 5A is the unique conjugacy class of order 5 in  $W(\mathsf{E}_6)$ . It can be represented by the permutation (12345) on six skew lines  $E_1, \ldots, E_6$ . Since  $E_6$  is invariant, it can be blown down equivariantly to a del Pezzo surface Y of degree 4. The surface Y is uniquely determined by a set S of 5 distinct points in  $\mathbb{P}^1$  up to projective equivalence. The automorphism group of such a surface is of the form  $2^4 \rtimes G$  where G is the embedded automorphism group of S. Up to projective equivalence, there is a unique set of 5 points in  $\mathbb{P}^2$  invariant under an automorphism of order 5. Thus, there is a unique surface Y and so there can be at most one smooth cubic surface X with the desired property. When the characteristic is not 5, X must be the Clebsch surface.  $\Box$ 

**Remark 12.3.** A group of order 5 has two invariant lines and no invariant tritangent planes. This implies that the invariant lines are skew. Given two skew lines on a cubic surface, there is a set of five mutually skew lines that intersect both given lines. Blowing the latter down, the two invariant exceptional lines are no longer exceptional, so they are not invariant lines and the surface is not a blowup of a single point on  $\mathbb{P}^2$ . Thus the cubic surface is equivariantly isomorphic to the blow-up of five points on a nonsingular quadric Q. We can start from an orbit of five points on a quadric and consider a rational map  $Q \longrightarrow \mathbb{P}^3$  given by linear system of quadric sections of Q passing through the points in the orbit. The image of this map is a cubic surface. The previous theorem implies the unexpected fact that, in characteristic 5, the image must be a singular cubic surface.

**Lemma 12.4.** In characteristic 2, the Fermat cubic surface and the Clebsch cubic surface are isomorphic.

*Proof.* Note that the Fermat cubic surface has an automorphism of degree 5, so this follows immediately from the previous result. This can also be seen directly using a careful choice of matrix as in the proof of Proposition 11.7.  $\Box$ 

**Lemma 12.5.** If  $p \neq 5$  and g is an automorphism of order 5, then there is a set of 10 Eckardt points whose corresponding reflections generate a group isomorphic to  $\mathfrak{S}_5$  containing g.

*Proof.* This is a Clebsch cubic surface which can be put in the form (12.1) where g acts by permuting the coordinates. The reflections correspond to transpositions in  $\mathfrak{S}_5$ . There are 10 of them and they generate  $\mathfrak{S}_5$ .

Proposition 12.6. The Clebsch cubic surface has the normal form

$$\sigma_1 \sigma_2 - \sigma_3 = \left( \sum_{i \neq j} x_i^2 x_j \right) + 2 \left( \sum_{i < j < k} x_i x_j x_k \right)$$

in  $\mathbb{P}(x_0:x_1:x_2:x_3)$  in all characteristics.

*Proof.* Make the substitution  $x_4 = -x_0 - x_1 - x_2 - x_3$  in (12.1).

**Remark 12.7.** One could also put the Clebsch in the normal form from Proposition 11.7 for an appropriate choice of c. From the proof, a tedious calculation shows that c satisfies  $5c^3 + 18c^2 - 189c + 378 = 0$  when p = 0.

12.2. Class 6E.

**Lemma 12.8.** Let X be a smooth cubic surface and suppose g is an automorphism of class 6E. Then there exist four Eckardt points on X, of which three lie on a trihedral line contained in the tritangent plane of the fourth. Their corresponding reflections generate a group G isomorphic to  $\mathfrak{S}_3 \times 2$ containing g.

Proof. From Table 4, an automorphism g has class 6E if and only if it is a product g = ab of commuting automorphisms a of class 3D and b of class 2A. The automorphism a has a canonical trihedral line  $\ell$  which must be invariant under b since a and b commute. If b acted nontrivially on the Eckardt points on  $\ell$  then it would have to leave one fixed since b has order 2; this kind of action cannot commute with the cyclic permutation induced by the action of a. Thus b fixes each Eckardt point of  $\ell$ . In particular, b commutes with their corresponding reflections. Thus there are exceptional lines connecting each Eckardt point on  $\ell$  to the point corresponding to b. Since b commutes with a and the reflections on its trihedral line, they generate a group isomorphic to  $\mathfrak{S}_3 \times 2$  as desired.

**Lemma 12.9.** When p = 2, a smooth cubic surface admits an automorphism whose class is one of 4A, 4B, 6E if and only if it admits automorphisms of all three classes.

*Proof.* We begin by considering the classes 4A and 4B. In both cases, the blow-down of any invariant exceptional line is the canonical point on a quartic del Pezzo surface. The class 4A corresponds to  $2\overline{2}1$ , while the class 4B corresponds to  $2\overline{2}\overline{1}$ . Any surface admitting one of these must admit the other. Since they both preserve the canonical point, blowing it up we obtain a cubic surface admitting automorphisms of both classes.

If the surface admits an automorphism of class 4A or 4B, then it admits a group of automorphisms of order 192 as described in Lemma 11.5. There is an automorphism a of class 3D — for example, the product of any two non-commuting reflections. The center of the group is an involution b of class 2A. Since b commutes with a, the product g = ab is an element of order 6. From Table 4, we see that g must be of class 6E on account of its powers  $a = g^4$  and  $b = g^3$ .

Now suppose there is an automorphism of class 6E. From Lemma 12.8, we have an Eckardt point where the exceptional lines in its tritangent plane each contain another Eckardt point. Since p = 2, there are 5 Eckardt points

on each of these exceptional lines and we have precisely the situation of Lemma 11.5. In particular, there are automorphisms of class 4A and 4B.  $\Box$ 

By the previous Lemma, a normal form for 6E surfaces when p = 2 was exhibited in Proposition 11.7.

**Proposition 12.10.** Let X be a 6E surface. If  $p \neq 2, 3$ , then X has the normal form

$$x_0^3 + x_1^3 + x_2^3 + (x_0 + x_1 + x_2)x_3^2 + cx_0x_1x_2 = 0.$$

If p = 3 then X has the normal form

$$c(x_0 + x_1 + x_2)(x_0x_1 + x_0x_2 + x_1x_2) + (x_0x_1x_2) + (x_0 + x_1 + x_2)x_3^2 = 0.$$

*Proof.* If  $p \neq 2, 3$ , we can diagonalize g to assume that it acts as

$$(t_0: t_1: t_2: t_3) \mapsto (t_0: \zeta t_1: \zeta^2 t_2, -t_3)$$
,

where  $\zeta$  is a primitive third root of unity. The equation becomes

$$t_3^2 t_0 + t_0^3 + t_1^3 + t_2^3 + c t_0 t_1 t_2 = 0$$

(c.f. [9], (9.7.4)). After the change of coordinates

 $(t_0: t_1: t_2: t_3) \mapsto (x_0 + x_1 + x_2: x_0 + \zeta^2 x_1 + \zeta x_2: x_0 + \zeta x_1 + \zeta^2 x_2: x_3)$ , we arrive at the equation

$$(c+3)(x_0^3+x_1^3+x_2^3) + (18-3c)x_0x_1x_2 + (x_0+x_1+x_2)x_3^2 = 0.$$

The surface is singular if c+3 = 0, so we may rescale the variables to obtain the desired normal form.

For p = 3, we may simply follow the same proof as in Lemma 10.16 demanding in addition that the form is invariant under  $x_3 \mapsto -x_3$ . Now the initial form (10.7) has d = e = g = 0 and all the transformations using the matrix (10.8) can be done assuming  $a_4 = a_5 = 0$ .

# 12.3. Class 8A.

**Lemma 12.11.** If p = 2, no smooth cubic surface admits an automorphism of class 8A.

*Proof.* By checking Jordan canonical forms, there is no element of  $GL_4(\Bbbk)$  of order 8.

**Lemma 12.12.** Suppose  $p \neq 2$  and X is a smooth cubic surface admitting an automorphism g of class 8A. There is a unique such surface defined by the normal form:

(12.2) 
$$x_0^3 + x_0 x_3^2 - x_1 x_2^2 + x_1^2 x_3 = 0$$

where g acts via a diagonal matrix with entries  $(1, \epsilon^6, \epsilon, \epsilon^4)$  where  $\epsilon$  is a primitive eighth root of unity.

If p = 3, then the surface is cyclic and contains a subgroup isomorphic to  $\mathcal{H}_3(3) \rtimes 8$ .

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Proof. Since  $p \neq 2$ , we can assume g is defined using a diagonal matrix. The argument is then the same as on page 489 of [9]. When p = 3, this is a special case of the normal form (10.2). The element g normalizes the Galois group of the cover and so g leaves invariant the group  $N = \mathcal{H}_3(3) \rtimes 2$  by Lemma 10.12. Note that  $g^4$  is an element of N of order 2. Since  $\mathcal{H}_3(3)$  is a normal subgroup of N and is a Sylow 3-group, it is a characteristic subgroup of N. Thus, it is a normal subgroup of  $\langle N, g \rangle$ . By Schur-Zassenhaus, we conclude that  $\langle N, g \rangle \cong \mathcal{H}_3(3) \rtimes 8$ .

**Lemma 12.13.** If p = 3, a cubic surface admits an automorphism of class 8A if and only if it admits an automorphism of class 12A.

Proof. If there is an automorphism g of class 8A, then  $g^2$  has class 4A. The Galois group of the cyclic cover is generated by an element h and  $ghg^{-1} = h^{-1}$ . Thus  $g^2$  and h commute. Thus  $g^2h$  is of class 12A. Conversely, if there is an automorphism of class 12A then there exist elements of class 4A and 3A that commute with each other. Thus X is cyclic and has an element of order 4 which normalizes the Galois group of the cover. By Lemma 10.12, there is an automorphism of order 4 of the 9 Eckardt points. This is only possible if c = 0 in (10.2); thus there is also an automorphism of order 8.  $\Box$ 

12.4. Class 12A. We already saw above that, when p = 3, this case coincides with those of 8A by Lemma 12.13.

**Lemma 12.14.** When p = 2, if a smooth cubic surface admits an automorphism whose class is one of 3C, 5A, 12A then it admits automorphisms of all three classes.

*Proof.* We have already seen that in Lemma 12.4 that the classes 3C and 5A coincide. Note that 3C is a cyclic surface whose ramification divisor is a supersingular elliptic curve. The surface 12A is also a cyclic surface; by Lemma 10.12 there is an automorphism of order 4 acting faithfully on its ramification divisor. Thus 12A also has a supersingular ramification divisor. Thus their ramification divisors are isomorphic and so are the corresponding surfaces.

**Lemma 12.15.** Suppose  $p \neq 2, 3$  and X is a smooth cubic surface admitting an automorphism g of class 12A. Then X is cyclic and its ramification divisor is an anharmonic cubic. The surface X has normal form

$$x_0^3 + x_1^3 + x_2^3 + x_3^3 + \lambda x_0 x_1 x_2$$

where  $\lambda = 3(\sqrt{3} - 1)$ . Here  $\operatorname{Aut}(X) \cong \mathcal{H}_3(3) \rtimes 4$ .

*Proof.* Since  $g^4$  is of class 3A, we have a cyclic cubic surface. Since g acts with order 4 on the 3-torsion subgroup of the ramification divisor C, we conclude C is anharmonic by Lemma 10.12. It remains only to find an automorphism of order 4 on a cyclic surface. The following matrix, from

§3.1.4 of [9],

$$\frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 1 & 1 & 0\\ 1 & \zeta & \zeta^2 & 0\\ 1 & \zeta^2 & \zeta & 0\\ 0 & 0 & 0 & \sqrt{3} \end{pmatrix} ,$$

where  $\zeta$  is a primitive third root of unity, has order 4 and leaves invariant the given normal form. Note that  $\mathcal{H}_3(3) \rtimes 4$  must be the full automorphism group since there is only one cyclic surface structure on X.

## 13. Collections of Eckardt points

The possible automorphisms of cubic surfaces are closely controlled by the subgroup generated by reflections. From Theorem 9.2, along with Lemmas 5.1, 9.5, 10.8, 10.15, 11.5, 12.5 and 12.8, we have the following:

**Lemma 13.1.** Let X be a smooth cubic surface with an automorphism g of any class except 4A, 8A or 12A. Then the reflections corresponding to the Eckardt points on X generate a subgroup containing g.

13.1. **Reflection groups acting on cubic surfaces.** In this section, we classify the possible collections of Eckardt points that may occur on a smooth cubic surface along with the reflection groups they generate. Over finite fields, the possibilities are classified in Lemma 20.2.10 of [15]. However, Hirschfeld's proof does not enumerate the corresponding reflection groups. Our proof follows similar lines.

Let X be a smooth cubic surface. Let  $\mathcal{E}$  be the set of Eckardt points of X. Let  $\mathcal{L}$  (resp.  $\mathcal{T}$ ) be the set of lines passing through two points of  $\mathcal{E}$  that lie on X (resp. do not lie on X). The lines in  $\mathcal{L}$  are all exceptional lines; they contain exactly 2 points of  $\mathcal{E}$  if  $p \neq 2$  or exactly 5 points of  $\mathcal{E}$  if p = 2. The lines in  $\mathcal{T}$  are precisely the trihedral lines of X and they contain exactly three points of  $\mathcal{E}$ .

Since Eckardt points can always be identified with tritangent planes, one can view a triple  $(\mathcal{E}, \mathcal{L}, \mathcal{T})$  as a kind of incidence structure where  $\mathcal{E}$  is a subset of the 45 tritangent trios and  $\mathcal{L}$  and  $\mathcal{T}$  are subsets of the power set of  $\mathcal{E}$  corresponding to the Eckardt points lying on the corresponding line. We say two such triples are *equivalent* if they are in the same  $W(\mathsf{E}_6)$ -orbit.

**Lemma 13.2.** Let X be a smooth cubic surface with corresponding triple  $(\mathcal{E}, \mathcal{L}, \mathcal{T})$ . Let G be the subgroup of  $\operatorname{Aut}(X)$  generated by reflections (equivalently, G is generated by the reflections corresponding to the Eckardt points  $\mathcal{E}$ ). Up to equivalence, the possibilities are enumerated in Table 5.

*Proof.* We proceed by building the triples inductively by adding points to existing triples taking into account the constraints imposed on collinear Eckardt points by Lemmas 9.4 and 10.2.

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Name	$\dim\operatorname{span}\mathcal{E}$	$ \mathcal{E} $	$ \mathcal{L} $	$ \mathcal{T} $	p	G	Surfaces
$C_0$	-1	0	0	0	any	1	1A
$C_1$	0	1	0	0	any	2	2A, 4A $(p \neq 2)$ , 8A $(p \neq 2, 3)$
$C_2$	1	2	1	0	$\neq 2$	$2^{2}$	$2B \ (p \neq 2)$
$C_3$	1	3	0	1	any	$\mathfrak{S}_3$	3D
$C_5$	1	5	1	0	= 2	$2^{4}$	$2B \ (p=2)$
$C_4$	2	4	3	1	$\neq 2$	$\mathfrak{S}_3  imes \mathfrak{S}_2$	$6E \ (p \neq 2)$
$C_6$	2	6	3	4	$\neq 2$	$\mathfrak{S}_4$	4B $(p \neq 2)$
$C_9$	2	9	0	12	any	$H_3(3) \rtimes 2$	3A, 8A=12A $(p = 3)$ , 12A $(p \neq 2, 3)$
$C_{13}$	2	13	3	16	= 2	$2^3 \rtimes \mathfrak{S}_4$	$4A = 4B = 6E \ (p = 2)$
$C_{10}$	3	10	15	10	$\neq 2, 5$	$\mathfrak{S}_5$	5A $(p \neq 2)$
$C_{18}$	3	18	27	42	$\neq 3$	$3^3 \rtimes \mathfrak{S}_4$	$3C \ (p \neq 2, 3)$
$C_{45}$	3	45	27	240	= 2	$PSU_4(2)$	$3C=5A=12A \ (p=2)$

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TABLE 5. Possible collections of Eckardt points.

The cases  $C_0$  and  $C_1$  are immediate. The classification of the collinear collections  $C_2$ ,  $C_3$ ,  $C_5$  and their automorphisms follow immediately from Lemmas 9.4 and 10.2.

Suppose  $\mathcal{E}$  spans a plane P. Let us consider the collection corresponding to  $C_9$ . The reflections corresponding to any three non-collinear Eckardt points in  $C_9$  generate the entire reflection group associated to  $C_9$ . Indeed, any two Eckardt points give rise to an element of order 3 which has 3 orbits each of 3 collinear Eckardt points. Since we have two pairs lying on different lines, we get a transitive action of the group on the Eckardt points and thus their corresponding reflections.

Thus, if a general planar collection  $\mathcal{E}$  can be embedded in  $C_9$  as an abstract incidence structure, then we obtain  $C_9$  itself. By Lemma 5.3,  $C_9$  and  $C_{13}$  are the maximal possible planar collections. For the remaining planar cases, we may assume  $\mathcal{E}$  is a subset of  $C_{13}$ ; thus P is a tritangent plane.

All of the Eckardt points must lie on the three exceptional lines in the tritangent plane. Since the points of  $\mathcal{E}$  are not collinear, at least two points p, q of  $\mathcal{E}$  lie on distinct exceptional lines. The line  $\overline{pq}$  is a trihedral line in  $\mathcal{T}$  whose third point r lies on the remaining exceptional line. These points generate a group  $\mathfrak{S}_3$  which permutes the exceptional lines, so there are an equal number of points of  $\mathcal{E}$  on each. Since p, q, r are collinear, there must be at least one more point. If the characteristic is not 2, there can only be two points on each exceptional line. If the point t is the intersection of the three lines we have the case  $C_4$ , otherwise, there must be 6 points in  $\mathcal{E}$  and we are in case  $C_{6}$ . If the characteristic is 2, we must have 5 points on every line and we are in case  $C_{13}$ .

Now assume E spans the whole space. If two lines  $\ell, \ell'$  from  $\mathcal{T}$  are skew, then we claim X is the Fermat surface. Suppose there exists a third trihedral line  $\ell''$  that passes through Eckardt points of both  $\ell$  and  $\ell'$ . In this case  $\{\ell, \ell''\}$ and  $\{\ell', \ell''\}$  span two distinct planes that each contain the  $C_9$  collection. This means that there are two distinct cyclic surface structures on X, which is only possible if X is the Fermat cubic surface. We are left with only the possibility that all the lines between Eckardt points on  $\ell$  and  $\ell'$  are exceptional. This means that the reflections corresponding to the Eckardt points on  $\ell$  commute with those from  $\ell'$ . Thus, there is a group isomorphic  $\mathfrak{S}_3 \times \mathfrak{S}_3$  acting on X. This implies the existence of an automorphism of class 3C and thus we must have the Fermat cubic surface by Theorem 10.4. This produces case  $C_{18}$  when p > 3 and  $C_{45}$  when p = 2. This case does not occur when p = 3. Note that  $C_{18}$  has two points on every exceptional line so it is certainly maximal when  $p \neq 2$ .

We may now assume that any pair of trihedral lines in  $\mathcal{E}$  must intersect in a point outside X. Whenever this occurs, the two lines span a plane P and  $P \cap \mathcal{E}$  must be a configuration of type  $C_6$ . Thus the plane P contains exactly 4 trihedral lines from  $\mathcal{T}$ . Let  $\mathcal{P}$  be the subsets of  $\mathcal{L}$  corresponding to such planes P. We thus want subsets of four elements where each pair of subsets contains exactly one common element. By directly trying to build such a collection, we see there is only one possibility for  $\mathcal{P}$ :

$$\{1, 2, 3, 4\}, \{1, 5, 6, 7\}, \{2, 5, 8, 9\}, \{3, 6, 8, 10\}, \{4, 7, 9, 10\}$$
.

This last case is  $C_{10}$ . This is the Clebsch cubic surface. If  $p \neq 2$ , then the automorphism group of such a surface is maximal, so the collection  $C_{10}$  must be as well. If p = 2, then we obtain the collection  $C_{45}$ .

**Remark 13.3.** The Clebsch surface is classically called the *Clebsch diagonal* cubic surface. We recall the reason for this name (see also §9.5.4 of [9]). Written in the coordinates (12.1), the cubic surface is a hypersurface in the space  $\mathbb{P}^3$  given by  $\sum_{i=0}^4 x_i = 0$ . The *Sylvester Pentahedron* is the set of 5 planes in  $\mathbb{P}^3$  defined by  $x_i = 0$  for  $i = 0, \ldots, 4$ . The planes are called *faces* of the pentahedron, intersections of pairs of planes form the *edges*, and intersections of triples of planes are the *vertices*. The 10 vertices are Eckardt points  $\mathcal{E}$  of the Clebsch surface, which are all of them when  $p \neq 2$ . The 10 edges are the trihedral lines  $\mathcal{T}$  in  $C_{10}$  described above.

Each face contains 6 coplanar Eckardt points as in the  $C_6$  arrangement described above. The three exceptional lines on each face are precisely the three diagonals of the tetrahedron defined by the other 4 faces. Thus the 15 exceptional lines  $\mathcal{L}$  in  $C_{10}$  are the "diagonals" from which the surface gets its name. The remaining 12 exceptional lines form a double-sixer.

When p = 2, a Sylvester pentahedron can be constructed, but it is not unique. In the coordinates (12.1), we see that the three diagonals of each quadrilateral meet at a point, which produces additional Eckardt points. This is yet another explanation for why the Fermat and the Clebsch surfaces are isomorphic when p = 2.

13.2. Automorphisms not arising from reflection groups. It remains to consider automorphism groups that are *not* generated by reflection groups. Since surfaces admitting automorphisms of class 8A or 12A also admit automorphisms of class 4A, the following essentially settles the matter.

**Lemma 13.4.** Suppose X admits an automorphism g of class 4A. If p = 2, then g is contained in a reflection subgroup of Aut(X). If  $p \neq 2$ , then either Aut(X) is cyclic, or X is the 12A surface.

*Proof.* When p = 2, we know from Lemma 12.9 that X is also a surface admitting an automorphism of class 4B and that g is contained in a reflection group.

Now suppose  $p \neq 2$  and  $p_0$  is the Eckardt point corresponding to the reflection  $g^2$ . From Lemma 11.2, we see that if q is an Eckardt point lying on an exceptional line  $\ell$  containing  $p_0$  then g(q) is a third Eckardt point on  $\ell$ — a contradiction when  $p \neq 2$ . If q is an Eckardt point lying on a trihedral line  $\ell$  containing  $p_0$  then  $g^2(q)$  is the third Eckardt point on the line. Since there at most three Eckardt points on  $\ell$ , we see that g(q) must lie on a distinct trihedral line. We conclude that if there is more than one Eckardt point then the configuration of Eckardt points can only be  $C_9$ . Since g does not leave invariant any trihedral line, we have an induced action of order 4 on the ramification locus of a cyclic cubic surface. Thus, X is the 12A surface.

It remains to consider the case where the only Eckardt point is  $p_0$ . Aside from 2A, 4A, 8A, all the other realizable classes imply the existence of other Eckardt points. Thus we may assume  $\operatorname{Aut}(X)$  consists of elements only of classes 2A, 4A, 8A that leave invariant the tritangent plane containing  $p_0$ . One now uses a similar argument as page 495 of [9]. Let H be the image of  $\operatorname{Aut}(X)$  on the projectivized tangent space of  $p_0$ . Since  $\operatorname{Aut}(X)$  must have order a power of 2, the order is coprime to the characteristic. Thus, the morphism  $\operatorname{Aut}(X) \to H$  has cyclic kernel. Any other automorphism can only interchange two of the three lines passing through  $p_0$ . Since  $\operatorname{Aut}(X)$  has order a power of 2, this implies that H = 2 or H = 1. Any automorphism interchanging two lines must have order 8 by the description in Lemma 11.2. Thus  $\operatorname{Aut}(X)$  is a non-split central extension of cyclic groups and so must be cyclic.

### 14. PROOF OF THE MAIN THEOREM

*Proof of Theorem 1.1.* Let X be a smooth cubic surface. Lemmas 8.1, 10.14, and 12.1 tell us which automorphism classes do not occur. Lemmas 10.9, 10.14, 12.9, and 12.14 tell us that certain strata coincide with other strata.

We now prove that the automorphism groups that appear in Table 1 actually act on a smooth cubic surface and that no larger groups occur. Let Rbe the subgroup of Aut(X) generated by reflections. The possible reflection groups are enumerated in Lemma 13.2 and coincide with the automorphism groups described in the normal forms above. Thus, Lemmas 5.1, 9.5, 10.8, 10.15, 11.5, 12.5, and 12.8 tell us that the only automorphism classes not necessarily contained in R are 4A, 8A and 12A. Aside from these cases, R = Aut(X) so we have a full description of their automorphism groups. From Lemma 13.4, we have either that the surface has automorphism generated by an automorphism of class 4A or 8A, or is the surface 12A. The surface 12A coincides with 3C when p = 2, so this has already been handled. In Lemma 12.15, the full automorphism group of 12A is computed when  $p \neq 2, 3$ . Finally, when p = 3, the 12A stratum coincides with the 8A stratum — its automorphism group is described completely in Lemma 12.12.

It remains to prove that the strata from Table 1 are all distinct and have the expected dimensions. In other words, we need to prove that there are no other unusual coincidences like the Fermat and the Clebsch coinciding in characteristic 2. Note that each stratum is connected (and in fact unirational). Indeed, each conjugacy class of cyclic group can be represented by only one matrix in  $GL_4(k)$ . Thus each stratum is the image of an eigenspace of a linear endomorphism of  $S^3(\mathbb{K}^4)$ . We need to show that each of the arrows in Figures 1, 2, 3, and 4 are not actually equalities.

First we consider  $p \neq 2$ . By Lemma 6.7, the strata 1A, 2A, 2B, 3D, 4B, 6E, and 5A are distinct and have the expected dimensions. When  $p \neq 2$ , there is a 1-dimensional family of 4A surfaces distinct from the other strata by Lemma 11.4. The remaining surfaces 3A, 3C, 12A, 8A are distinct, equal, or non-existent by the characterization of cyclic surfaces in Section 10.4.

Now we consider p = 2. The surfaces 2B, 4A, 3C are in bijection with del Pezzo surfaces of degree 4 via blowing up the canonical point. Thus they are distinct and their strata have the appropriate dimensions by the results of Section 3. The 3A stratum is in bijection with isomorphism classes of cubic plane curves and so has dimension 1 and does not coincide with 4A. The class 3D does not coincide with 2B since the latter does not admit automorphisms of order 3. Since the 3D stratum is connected and contains the distinct 1-dimensional strata 4B and 3A, it is in fact 2-dimensional in view of the normal form from Lemma 10.16. Finally, the 2A stratum has dimension 3 since it contains the distinct 2-dimensional strata 2B and 3D.

**Corollary 14.1.** Let X be a smooth cubic surface. Then the subgroup of Aut(X) generated by reflections has index 1, 2, or 4 in Aut(X). The surfaces of index 2 are 4A (if  $p \neq 2$ ) and 12A (if  $p \neq 2, 3$ ). The surface of index 4 is 8A.

# 15. LIFTING TO CHARACTERISTIC ZERO

In this section we prove Theorem 1.2.

Let  $\Bbbk$  be an algebraically closed field of positive characteristic p and let A be a complete discrete valuation ring of characteristic zero with residue field  $\Bbbk$ . Such an A always exists by the Witt vector construction (see Theorem II.5.3 in [21]). Let X be a smooth projective k-variety with an action of a finite group G.

We say that (X, G) lifts to A if there exists an A-scheme  $X_A$ , smooth and projective over A, with a G-action such that the special fiber is Gequivariantly isomorphic to X. We say (X, G) lifts to characteristic 0 if there exists a lift to (X, G) to A for some A as above.

Note that not every smooth cubic G-surface in positive characteristic lifts to a G-surface in characteristic 0. An obvious obstruction to lifting is that G, as a subgroup of  $W(\mathsf{E}_6)$ , may not be realizable as automorphisms on *any* cubic surface in characteristic 0. In this section, we show that this is the only obstruction.

**Theorem 15.1.** Let X be a smooth cubic surface defined over  $\Bbbk$  with an action of finite group G such that  $G \subset W(\mathsf{E}_6)$  also occurs as a group of automorphisms for some cubic surface in characteristic 0. Then, after possibly replacing A with a totally ramified quadratic extension, (X, G) lifts to A.

*Proof.* Let K be the field of fractions of A and  $\mathfrak{m}$  the maximal ideal of A. In §5 of [22], Serre showed that any rational G-surface lifts to characteristic 0 in the tame case (in other words, when p is coprime to |G|.) Thus, it remains only to consider the cases where p divides |G|.

In what follows, we consider a subgroup  $G \subset W(\mathsf{E}_6)$  that is realized by automorphisms on some smooth cubic surface Y of characteristic 0. Then we consider a smooth cubic surface X over k that realizes the group G (assuming such a surface exists). We then show that (X, G) lifts to A or a quadratic extension of A. Looking at the classification, it suffices to assume that  $G = \operatorname{Aut}(Y)$  for an appropriate Y.

Consider the standard representation of  $\mathfrak{S}_5$  on  $V = \mathbb{Z}^5$  that acts by permuting basis elements. Given a partition  $\lambda$  of 5, let  $H_{\lambda}$  be the subgroup of  $\mathfrak{S}_5$  isomorphic to  $\mathfrak{S}_{\lambda_1} \times \cdots \mathfrak{S}_{\lambda_n}$  that permutes the basis elements in each part of  $\lambda$ . By the fundamental theorem of symmetric functions,  $\mathbb{Z}[V]^{H_{\lambda}}$  is a polynomial ring generated by elementary  $\lambda$ -symmetric functions. If W is the quotient of V by the invariant linear form  $x_1 + \cdots + x_5$ , then  $\mathbb{Z}[W]^{H_{\lambda}}$  is a polynomial ring with a generating set  $f_1, \ldots, f_s$  where each  $f_i$  contains a monic monomial. Thus  $f_1, \ldots, f_s$  generate  $R[W_R]^{H_{\lambda}}$  for any ring R.

Now, consider a cubic G-surface (X, G) over k that is one of the cases 2A, 2B, 3D, 4B, 6E and 5A appearing in Lemma 6.7. In order to lift G to characteristic 0, we may assume that G is of the form  $H_{\lambda}$  described above. Moreover, the normal forms show that we may assume  $H_{\lambda}$  acts on the space  $W_{\Bbbk}$  in the manner described above. Thus X is defined by a cubic polynomial that can be written as a linear combination of monomials in  $f_1, \ldots, f_s$ . Lifting the coefficients to A we have a lift of (X, G).

Now, the class 3C corresponds to the Fermat cubic surface. From the normal form and the description of the automorphism group  $3^3 \rtimes \mathfrak{S}_4$ , it evidently lifts to characteristic 0 when p = 2. Since it is not defined when p = 3, there is nothing to check.

The automorphism group for 8A is only wild if p = 2, but then it doesn't exist.

We now turn to the group 4A. This is only wild when p = 2. By possibly replacing A with a totally ramified quadratic extension (see Proposition II.2.3 in [21]), we can assume there is an element  $s \in A$  satisfying  $s^2 - 2s - 2$ . Note that s - 1 is a square root of 3 and  $s \mapsto 0$  under the map  $A \to \mathbb{k}$ . Let  $\zeta$  be a primitive third root of unity in A, which exists by Hensel's Lemma since  $\mathbb{k}$  is algebraically closed.

Consider the group G of order 4 generated by the matrix

$$\frac{1}{s-1} \begin{pmatrix} 1 & 1 & 1\\ 1 & \zeta & \zeta^2\\ 1 & \zeta^2 & \zeta \end{pmatrix} ,$$

in A. Diagonalizing in K, or finding the Jordan canonical form in k, we find that this group corresponds to the non-trivial  $3 \times 3$  block of a matrix of class 4A. One checks in these more convenient bases that, over both fields, the invariants of degree  $\leq 3$  are generated by elements of degree 1, 2, and 3 that have no relations in degree  $\leq 3$ .

The following three polynomials in  $A[x_0, x_1, x_2]$  are G-invariant:

$$f_1 = sx_0 + x_1 + x_2$$
  

$$f_2 = x_0(x_0 + x_1 + x_2)$$
  

$$f_3 = x_0^3 + x_1^3 + x_2^3 + 3(s-2)x_0x_1x_2$$

Their leading terms mod  $\mathfrak{m}$  are  $\{x_1, x_0^2, x_0^3\}$ , so they have no relations in degree  $\leq 3$ . Thus,  $\{f_1^3, f_1f_2, f_3\}$  is a basis for the invariants of degree 3 over both fields k and K.

Extending G to act on  $A[x_0, x_1, x_2, x_3]$  by the trivial action on  $x_3$ , we conclude that the vector space of invariants of degree 3 is spanned by

$$f_1^3, f_1f_2, f_3, f_1^2x_3, f_2x_3, f_1x_3^2, x_3^3$$

over both fields K and k. Thus we may lift 4A to characteristic 0 from characteristic 2.

It remains to consider the cases 3A and 12A. From Proposition 10.6, the cyclic surfaces in characteristic 2 have the same normal form as in characteristic 0:

$$x_0^3 + x_1^3 + x_2^3 + x_3^3 + cx_0x_1x_2$$

and the automorphism groups are defined over  $\mathbb{Z}[\zeta]$  as well. Thus they lift. For the case 12A, we may already lift the natural automorphism 4A by setting  $c = 3(s-2) = 3(\sqrt{3}-1)$  and noticing that our normal form is  $f_3 + x_3^3$ . Thus the group  $H_3(3) \rtimes 4$  from class 12A lifts when p = 2.

If p = 3, by possibly replacing A with a totally ramified quadratic extension, we may assume that A contains a primitive third root of unity  $\zeta$ . Note that  $\zeta \equiv 1 \mod \mathfrak{m}$ . Consider the group G of order 3 generated by the
matrix

$$\begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & \zeta \end{pmatrix} ,$$

in A. As above, this is of type 3A in both K and k. Consider the following cubic homogeneous form

$$F = \zeta x_0^3 + (\zeta - 1)x_0^2 x_3 - x_0 x_3^2 + (1 - \zeta)x_0 x_1^2 + x_1^2 x_3 - x_1 x_2^2 + c(-3\zeta x_0^2 x_1 + 2(1 - \zeta)x_0 x_1 x_3 + x_1 x_3^2)$$

where c is a parameter. One checks that F is G-invariant. Passing to the residue field k, we have:

$$F_k = x_0^3 - x_0 x_3^2 + x_1^2 x_3 - x_1 x_2^2 + c x_1 x_3^2$$

so for any 3A surface we may construct a lift of F. Note that we use a slightly modified normal form here, see Remark 10.11.

Since both  $F_K$  and  $F_k$  are 3A-surfaces, they each have exactly 9 Eckardt points lying in the plane  $P: x_3 = 0$ . The Hessian cubic of  $X|_P$  is given by  $24\left[(3\zeta + 3)c^2 + 2\zeta + 1)x_0^2x_1 + (2\zeta + 1)cx_0x_1^2 + \zeta x_0x_2^2 + \zeta x_1^3 - \zeta cx_1x_2^2\right] = 0$ and its intersection with  $X \cap P$  gives the 9 Eckardt points of  $X_K$ . Dividing first by 24, the Hessian cubic reduces to  $x_0x_2^2 + x_1^3 - cx_1x_2^2$  modulo  $\mathfrak{m}$ , which one checks cuts out the 9 Eckardt points in  $X_k \cap P_k$ . Thus, the nine Eckardt points on  $X_K$  and  $X_k$  lift to A-points of X.

Following the proof of Theorem 9.2, an Eckardt point in  $X_K$  produces an axis plane and a tangent plane, which are defined by linear forms  $L_1$ and  $L_2$ . By rescaling by elements of  $\mathfrak{m}$  if necessary, these linear forms can be defined over A such that they are non-zero modulo  $\mathfrak{m}$ . Moreover, these correspond to distinct planes in  $X_k$  since the axis and tangent plane exist and are distinct here as well. Thus we may set  $x_0 = L_1$  and  $x_1 = L_2$  and extend to a basis for  $A^4$  to write F in the form

$$x_0^2 x_1 + C(x_1, x_2, x_3) = 0$$

as in Theorem 9.2. This is clearly invariant under the reflection taking  $x_0 \mapsto -x_0$ . Thus, all 9 reflections on  $X_k$  can be lifted to  $X_A$ . This means that group of order 54 that they generate lifts as desired.

Finally, if we consider an element of order 12 generated by

$$\begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & i & 0 \\ 0 & 0 & 0 & \zeta \end{pmatrix}$$

,

then the same argument works for the 12A surface where c = 0.



FIGURE 2. Specialization of strata in  $\mathcal{M}_{cub}$  when p = 2.



FIGURE 3. Specialization of strata in  $\mathcal{M}_{cub}$  when p = 3.



FIGURE 4. Specialization of strata in  $\mathcal{M}_{cub}$  when p = 5.

Name	char	$\operatorname{Aut}(X)$	Order	1A	2A	2B	3A	3C	3D	4A	$4\mathrm{B}$	5A	6A	6C	6E	6F	8A	9A	12A
1A	any	1	1	1															
2A	any	2	2	1	1														
2B	$\neq 2$	$2^{2}$	4	1	2	1													
	2	$2^{4}$	16	1	5	10													
3A	any	$\mathcal{H}_3(3) \rtimes 2$	54	1	9		2		24				18						
3C	$\neq 2,3$	$3^3 \rtimes \mathfrak{S}_4$	648	1	18	27	8	6	84		162		72	36	36	54		144	
	2	$PSU_4(2)$	25920	1	45	270	80	240	480	540	3240	5184	720	1440	1440	2160		5760	4320
3D	any	$\mathfrak{S}_3$	6	1	3				2										
4A	$\neq 2$	4	4	1	1					2									
	2	$2^3 \rtimes \mathfrak{S}_4$	192	1	13	30			32	12	72				32				
4B	$\neq 2$	$\mathfrak{S}_4$	24	1	6	3			8		6								
	2	(same as	5 4A)																
5A	$\neq 2, 5$	$\mathfrak{S}_5$	120	1	10	15			20		30	24			20				
	2	(same as	3C)																
6E	$\neq 2$	$\mathfrak{S}_3  imes \mathfrak{S}_2$	12	1	4	3			2						2				
	2	(same as	5 4A)																
8A	$\neq 2,3$	8	8	1	1					2							4		
	3	$\mathcal{H}_3(3) \rtimes 8$	216	1	9		2		24	18			18				108		36
12A	$\neq 2, 3$	$\mathcal{H}_3(3) \rtimes 4$	108	1	9		2		$\overline{24}$	18			18						36
	3	(same as 8A)																	
	2	(same as 3C)																	

TABLE 6. Automorphism groups of cubic surfaces with enumeration of conjugacy classes.

Name	char	Normal Form	Reference
2A	$\neq 2$	$(x_0 + x_1)(x_0x_1 + c_0x_2^2 + c_1x_3^2 + c_2x_2x_3) + x_2x_3(x_2 + x_3)$	Proposition 9.3
	2	$x_0x_1x_2 + (x_0 + x_1)^2x_3 + c_0(x_0 + x_1)x_3^2 + c_1x_2^3 + c_2x_2x_3^2 + x_3^3$	Proposition 9.3
		(Note: $p = 2$ normal form does not include 2B surfaces)	
2B	$\neq 2$	$x_0^2(x_2 + c_0 x_3) + x_1^2(c_1 x_2 + x_3) + x_2 x_3(x_2 + x_3) = 0$	Proposition 9.8
	2	$x_0^3 + x_1^3 + x_2^3 + x_3^3 + c_0 x_2 x_3 (x_0 + x_1) + c_1 x_0 x_1 (x_2 + x_3)$	Proposition 9.8
3A	$\neq 3$	$x_0^3 + x_1^3 + x_2^3 + x_3^3 + cx_0x_1x_2$	Proposition 10.6
	3	$x_0^3 + x_0 x_3^2 - x_1 x_2^2 + x_1^2 x_3 + c x_1 x_3^2$	Proposition 10.10
3C	$\neq 3$	$x_0^3 + x_1^3 + x_2^3 + x_3^3$	Lemma 10.14
3D	$\neq 3$	$x_0^3 + x_1^3 + x_2^3 + x_3^3 + c_0 x_0 x_1 x_2 + c_1 (x_0 + x_1 + x_2) x_3^2$	Lemma 10.16
		(Note: $p \neq 3$ normal form does not include 6E surfaces)	-
	3	$(c_0(x_0 + x_1 + x_2) + c_1x_3)(x_0x_1 + x_0x_2 + x_1x_2) + x_0x_1x_2 + (x_0 + x_1 + x_2)x_3^2$	Lemma 10.16
4A	$\neq 2$	$x_3^2 x_2 + x_2^2 x_0 + x_1 (x_1 - x_0) (x_1 - c x_0)$	Lemma 11.4
	2	(same as 4B)	
4B	any	$x_0^3 + x_1^3 + x_2^3 + x_3^3 + c(x_0x_1x_2 + x_0x_1x_3 + x_0x_2x_3 + x_1x_2x_3)$	Proposition 11.7
5A	$\neq 2, 5$	$\left(\sum_{i \neq j} x_i^2 x_j\right) + 2\left(\sum_{i < j < k} x_i x_j x_k\right)$	Proposition 12.6
	2	(same as 3C)	
6E	$\neq 2,3$	$x_0^3 + x_1^3 + x_2^3 + (x_0 + x_1 + x_2)x_3^2 + cx_0x_1x_2$	Proposition 12.10
	3	$c(x_0 + x_1 + x_2)(x_0x_1 + x_0x_2 + x_1x_2) + (x_0x_1x_2) + (x_0 + x_1 + x_2)x_3^2$	Proposition 12.10
	2	(same as 4B)	
8A	$\neq 2$	$x_0^3 + x_0 x_3^2 - x_1 x_2^2 + x_1^2 x_3$	Lemma 12.12
12A	$\neq 2, 3$	$x_0^3 + x_1^3 + x_2^3 + x_3^3 + 3(\sqrt{3} - 1)x_0x_1x_2$	Lemma 12.15
	3	(same as 8A)	
	2	(same as 3C)	

 TABLE 7. Normal forms of cubic surfaces for each automorphism group stratum.

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